# A new derivation of Euler-Bohlin invariant of linearly damped Harmonic oscillator with constant frequency 

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#### Abstract

: [In this paper a simple derivation of Euler-Bohlin invariant is given without any kind of symmetry analysis].

Key words : Invariant, Damped harmonic oscillator, Euler-Bohlin Invariant.


## 1. Introduction.

The standard equation of damped harmonic oscillator with constant frequency and damping force proportional to velocity is :

$$
\begin{equation*}
\ddot{\mathrm{x}}+2 \mathrm{~K} \dot{\mathrm{x}}+\omega^{2} \mathrm{x}=0 \text { (overhead dots represent time derivative) } \tag{1.1}
\end{equation*}
$$

A well known time-independent invariant of damped harmonic oscillator is EulerBohlin invariant [1] which is

$$
\begin{equation*}
\frac{\left(\dot{\mathrm{x}}+\lambda_{1} \mathrm{x}\right)^{\lambda_{1}}}{\left(\dot{\mathrm{x}}+\lambda_{2} \mathrm{x}\right)^{\lambda_{2}}}=\text { constant } \tag{1.2}
\end{equation*}
$$

where $\lambda_{1}$ and $\lambda_{2}$ are given by

$$
\left.\begin{array}{ll} 
& \lambda_{1}+\lambda_{2}=2 \mathrm{~K}  \tag{1.3}\\
\text { and } & \lambda_{1} \cdot \lambda_{2}=\omega^{2}
\end{array}\right]
$$

## 2. New derivation of invariant (1.2) of damped harmonic oscillator.

To derive we use a basic result of integrability of a first order nonlinear differential equation of the form :

$$
\begin{equation*}
y^{\prime}(x)-s(x)+\frac{R(x)}{y}=0, \quad y^{\prime}=\frac{d y}{d x} \tag{2.1}
\end{equation*}
$$

This integrability condition [2] of differential equation (2.1) is

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{dx}}\left(\frac{\mathrm{R}}{\mathrm{~S}}\right)=\frac{(\mathrm{n}-1)}{\mathrm{n}^{2}} \mathrm{~S} ; \quad \mathrm{n}=\mathrm{constant} \tag{2.2}
\end{equation*}
$$

And when the above condition is satisfied an integrating factor of (2.1) is given by [2]

$$
\begin{array}{r}
\mu=\frac{y}{[y+f(x)]^{n}} \\
\text { where } f(x)=-\frac{n R(x)}{S(x)} \tag{2.4}
\end{array}
$$

Now to use the above result, let

$$
\begin{equation*}
\dot{\mathrm{x}}=\mathrm{y}(\mathrm{x}) \tag{2.5}
\end{equation*}
$$

Therefore $\quad \ddot{x}=y^{\prime}(x) y(x) ; y^{\prime}=\frac{d y}{d x}$
using (2.5) and (2.6) equation (1.1) can be recasted as

$$
\mathrm{y}^{\prime}(\mathrm{x})+2 \mathrm{~K}+\frac{\omega^{2} \mathrm{x}}{\mathrm{y}}=0
$$

Equation (2.7) is of the form (2.1). Hence the integrability condition for (1.7) is, using (2.2)

$$
\begin{align*}
& \frac{d}{d x}\left(-\frac{\omega^{2} x}{2 K}\right)=\frac{(n-1)}{n^{2}}(-2 K) \\
& \text { i.e., } \frac{\omega^{2}}{2 K}=\frac{(n-1)}{n^{2}}(2 K) \\
& \text { i.e., } n^{2} \omega^{2}-4 K^{2} n+4 K^{2}=0
\end{align*}
$$

Equation (2.8) is a quadratic in $n$, have two values of $n$ given by $n_{1}$ and $n_{2}$, where

$$
\begin{array}{r}
\mathrm{n}_{1}+\mathrm{n}_{2}=\frac{4 \mathrm{~K}^{2}}{\omega^{2}} \\
\text { and } \mathrm{n}_{1} \cdot \mathrm{n}_{2}=\frac{4 \mathrm{~K}^{2}}{\omega^{2}} \tag{2.9}
\end{array}
$$

Then two independent integrating factors of (2.7) are [using (2.3) and (2.4)]

$$
\begin{align*}
& \mu_{1}=\frac{y}{\left[y+\frac{n_{1} \omega^{2} x}{2 K}\right]^{n_{1}}}  \tag{2.10}\\
& \mu_{2}=\frac{y}{\left[y+\frac{n_{2} \omega^{2} x}{2 K}\right]^{n_{2}}} \tag{2.11}
\end{align*}
$$

Now, theory of first order ordinary differential equation asserts [3] that the ratio of two linearly independent integrating factors is constant and is the solution of differential equation concerned. It is an easy check that $\mu_{1}$ and $\mu_{2}$ are linearly independent.

Hence $\quad \frac{\mu_{1}}{\mu_{2}}=c=\frac{\left[y+\frac{n_{2} \omega^{2} x}{2 K}\right]^{n_{2}}}{\left[y+\frac{n_{1} \omega^{2} x}{2 K}\right]^{n_{1}}}$
Equation (2.12) is thus the solution of (2.7). And it is clear that a solution of (2.7) is an invariant of (1.1).

Therefore, it turns out that (2.12) is an invariant of (1.1).
Now, a little manipulation of (2.12) gives

$$
\begin{equation*}
\frac{\left[y+\frac{n_{2} \omega^{2} x}{2 K}\right]^{\frac{\omega^{2}}{2 K}}}{\left[y+\frac{n_{1} \omega^{2} x}{2 K}\right]^{\frac{\omega^{2}}{2 K} n_{1}}}=\text { Constant, because } c=\text { Const. } \tag{2.13}
\end{equation*}
$$

Equation (2.13) is exactly Euler-Bohlin invariant of (1.1). This may be verified as follows :

$$
\text { Let } \theta_{1}=\frac{\omega^{2}}{2 \mathrm{~K}} \mathrm{n}_{2} \quad \text { and } \quad \theta_{2}=\frac{\omega^{2}}{2 \mathrm{~K}} \mathrm{n}_{1}
$$

Then (2.13) can be rewritten as

$$
\begin{align*}
& \frac{\left(y+\theta_{1} x\right)^{\theta_{1}}}{\left(y+\theta_{2} x\right)^{\theta_{2}}}=\text { Const }=\frac{\left(\dot{x}+\theta_{1} x\right)^{\theta_{1}}}{\left(\dot{x}+\theta_{2} x\right)^{\theta_{2}}} \quad \text {, using }(2.5)  \tag{2.14}\\
& \text { and } \theta_{1}+\theta_{2}=\frac{\omega^{2}}{2 K} n_{2}+\frac{\omega^{2}}{2 K} n_{1}=\frac{\omega^{2}}{2 K}\left(n_{2}+n_{1}\right)=\frac{\omega^{2}}{2 K} \frac{4 K^{2}}{\omega^{2}}=2 K \\
& \text { using (2.9) }  \tag{2.15}\\
& \text { and } \theta_{1} \cdot \theta_{2}=\frac{\omega^{4}}{4 K^{2}} n_{2} n_{1}=\frac{\omega^{4}}{4 K^{2}} \frac{4 K^{2}}{\omega^{2}}=\omega^{2}
\end{align*}
$$

A comparison of (1.3) and (2.15) asserts that $\theta_{1}$ and $\theta_{2}$ are identical with $\lambda_{1}$ and $\lambda_{2}$.
Finally a comparison of (1.2) and (2.14) asserts that equation (2.14) is the Euler-Bohlin time independent invariant of damped harmonic oscillator equation (1.1).

## 3. Conclusion :

Euler-Bohlin invariant is a well known time independent invariant of damped harmonic oscillator. In above a new derivation of the invariant is given. The derivation is simple and uses no symmetry methods.

## References

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