

A Locally Parameter Element Wise Linear Transformations Based Forecasting Model For Dynamic State Systems With Large Number Of Parameters

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Abstract

In this research investigation, the author has presented ‘*A Locally Parameter Element Wise Linear Transformations Based Forecasting Model For Dynamic State Systems With Large Number Of Parameters*’.

Theory

Firstly, we represent any *Dynamic State System* using a *State Vector (Row Vector)* of a specified size, say

$$V_i = [V_i(1) \ V_i(2) \ V_i(3) \ \dots \ V_i(n-2) \ V_i(n-1) \ V_i(n)]$$

That is,

$$\bar{V}_i = [V_i(1) \ V_i(2) \ V_i(3) \ \dots \ V_i(n-2) \ V_i(n-1) \ V_i(n)]$$

$$\bar{V}_i = \sum_{j=1}^n \{ [V_i(j)] \hat{e}_j \}$$

Here, the *State Vector* has n parameters that are Evolving with time.

For the time instant $i = k$, we have the *State Vector* given by

$$\bar{V}_k = [V_k(1) \ V_k(2) \ V_k(3) \ \dots \ V_k(n-2) \ V_k(n-1) \ V_k(n)]$$

Let the *State Vector* be defined for $i = 1$ to $i = m$ instants.

We now *Normalize* all \bar{V}_i for $i = 1$ to $i = m$.

The *Normalization* is given by

$$\hat{V}_i = \frac{\bar{V}_i}{\left\{ \sum_{j=1}^n [V_i(j)]^2 \right\}^{1/2}}$$

That is,

$$\hat{V}_i = \frac{\sum_{j=1}^n \{[V_i(j)]\hat{e}_j\}}{\left\{\sum_{j=1}^n [V_i(j)]^2\right\}^{1/2}}$$

We now define $T_{s_j \rightarrow (s+1)_j}(j) = \frac{\hat{V}_{(s+1)_j}(j)}{\hat{V}_{s_j}(j)}$

We define

$$\hat{V}_{m+1}(j) = \left\{ \hat{V}_m(j) \right\} \left[\left(T_{u_j \rightarrow (u+1)_j}(j) \right) + \left\{ \hat{V}_{m_j}(j) - \hat{V}_{u_j}(j) \right\} \left\{ \frac{\left(T_{(u+1)_j \rightarrow (u+2)_j}(j) \right) - \left(T_{u_j \rightarrow (u+1)_j}(j) \right)}{\hat{V}_{(u+1)_j}(j) - \hat{V}_{u_j}(j)} \right\} \right]$$

where $\hat{V}_{u_j}(j) < \hat{V}_{m_j}(j) < \hat{V}_{(u+1)_j}(j)$ **for** $1 \leq u_j < m$.

Using the constraint that all the $|\bar{V}_i|$ **for** $i=1$ **to** $i=m+1$ **form One Normal Data Set, we calculate the value of** $|\bar{V}_{m+1}|$

i.e., we calculate α **at around the value of** $|V_m|$ **such that** $|\bar{V}_{m+1}| = |V_m| + \alpha$ **such that the** $|\bar{V}_i|$ **for** $i=1$ **to** $i=m+1$ **form One Normal Data Set, where** α **is a Real Scalar Value.**

Finally, we have

$$\bar{V}_{m+1} = |V_{m+1}| \hat{V}_{m+1}.$$

Conclusion

This Scheme can be used to predict the *One Step Evolution* **of any** *Dynamic State System* **with Large Number of Parameters.**

Moral

Clear Waters Run Deep.

References

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Dedication

*All of the aforementioned Research Works, inclusive of this One are **Dedicated to Lord Shiva.***