# Nine steps transforming incompressible Navier-Stokes equations into parabolic partial differential equations 

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October 19, 2015


#### Abstract

It was shown that using spatial transform obtained by applying the difference to spatial global coordinates and time integral of velocities non linear Navier-Stokes equation transforms into parabolic equations.


## Nine steps of linearisation

Let's start from Navier-Stokes equations [1, 2, 3]

$$
\frac{\partial \mathbf{v}}{\partial t}+\mathbf{v} \cdot \nabla \mathbf{v}=-\frac{1}{\rho} \nabla p+\nu \nabla^{2} \mathbf{v}
$$

We know that in the left side is full time derivative

$$
\begin{equation*}
\frac{D \mathbf{v}}{D t}=-\frac{1}{\rho} \nabla p+\nu \nabla^{2} \mathbf{v} \tag{1}
\end{equation*}
$$

Now we could integrate both sides by time and obtain for $\mathbf{v}(\mathbf{r}, t)$

$$
\begin{equation*}
\mathbf{v}(\mathbf{r}, t)=-\frac{1}{\rho} \int_{0}^{t} \nabla_{\mathbf{r}} p(\mathbf{r}, \tau) d \tau+\nu \int_{0}^{t} \nabla_{\mathbf{r}}^{2} \mathbf{v}(\mathbf{r}, \tau) d \tau \tag{2}
\end{equation*}
$$

We obtained formal solution for velocities as follow

$$
\begin{equation*}
\mathbf{v}(\mathbf{r}, t)=\mathbf{F}(\mathbf{r}, t) \tag{3}
\end{equation*}
$$

Eq. (3) is valid for any $\mathbf{r}^{\prime}$ in the boundary where we try to solve NS equation. We could choose $\mathbf{r}^{\prime}$ so that

$$
\begin{equation*}
\mathbf{r}^{\prime}=\mathbf{r}-\int_{0}^{t} \mathbf{v}(\mathbf{r}, \tau) d \tau \tag{4}
\end{equation*}
$$

[^0]and
\[

$$
\begin{equation*}
\mathbf{v}\left(\mathbf{r}-\int_{0}^{t} \mathbf{v}(\mathbf{r}, \tau) d \tau, t\right)=\mathbf{F}\left(\mathbf{r}-\int_{0}^{t} \mathbf{v}(\mathbf{r}, \tau) d \tau, t\right) \tag{5}
\end{equation*}
$$

\]

or by taking full derivative of both sides we obtain

$$
\begin{align*}
& \frac{D \mathbf{v}\left(\mathbf{r}-\int_{0}^{t} \mathbf{v}(\mathbf{r}, \tau) d \tau, t\right)}{D t}=\frac{D \mathbf{F}\left(\mathbf{r}-\int_{0}^{t} \mathbf{v}(\mathbf{r}, \tau) d \tau, t\right)}{D t}=  \tag{6}\\
& -\nabla p\left(\mathbf{r}-\int_{0}^{t} \mathbf{v}(\mathbf{r}, \tau) d \tau, t\right)+\nu \nabla_{\left(\mathbf{r}-\int_{0}^{t} \mathbf{v}(\mathbf{r}, \tau) d \tau, t\right)}^{2} \mathbf{v}\left(\mathbf{r}-\int_{0}^{t} \mathbf{v}(\mathbf{r}, \tau) d \tau, t\right) \tag{7}
\end{align*}
$$

It is easy to prove that

$$
\begin{equation*}
\frac{D \mathbf{v}\left(\mathbf{r}-\int_{0}^{t} \mathbf{v}(\mathbf{r}, \tau) d \tau, t\right)}{D t}=\frac{\partial \mathbf{v}\left(\mathbf{r}-\int_{0}^{t} \mathbf{v}(\mathbf{r}, \tau) d \tau, t\right)}{\partial t} \tag{8}
\end{equation*}
$$

So, we obtain parabolic equations

$$
\begin{equation*}
\frac{\partial \mathbf{v}\left(\mathbf{r}^{\prime}, t\right)}{\partial t}=-\frac{1}{\rho} \nabla_{\mathbf{r}^{\prime}} p\left(\mathbf{r}^{\prime}, t\right)+\nu \nabla_{\mathbf{r}^{\prime}}^{2} \mathbf{v}\left(\mathbf{r}^{\prime}, t\right) \tag{9}
\end{equation*}
$$

which are analytically solvable for defined boundaries using for example Green function method. When we obtain velocities $\mathbf{v}\left(\mathbf{r}^{\prime}, t\right)$ in the local coordinates we could go back to the global coordinates by inserting new one coordinates $\mathbf{r}^{\prime}+\int_{0}^{t} \mathbf{v}(\mathbf{r}, \tau) d \tau$ into obtained analytical solution which implies that

$$
\nabla_{\mathbf{r}^{\prime}+\int_{0}^{t} \mathbf{v}(\mathbf{r}, \tau) d \tau} \mathbf{v}\left(\mathbf{r}^{\prime}+\int_{0}^{t} \mathbf{v}(\mathbf{r}, \tau) d \tau, t\right)=\nabla_{\mathbf{r}}^{2} \mathbf{v}(\mathbf{r}, t)
$$

and

$$
\begin{aligned}
& \frac{\partial \mathbf{v}\left(\mathbf{r}^{\prime}+\int_{0}^{t} \mathbf{v}(\mathbf{r}, \tau) d \tau, t\right)}{\partial t}=\frac{\partial \mathbf{v}\left(\mathbf{r}^{\prime}+\int_{0}^{t} \mathbf{v}(\mathbf{r}, \tau) d \tau, t\right)}{\partial t}+ \\
& \frac{\partial\left(\mathbf{r}^{\prime}+\int_{0}^{t} \mathbf{v}(\mathbf{r}, \tau) d \tau, t\right)}{\partial t} \cdot \nabla_{\mathbf{r}^{\prime}+\int_{0}^{t} \mathbf{v}(\mathbf{r}, \tau) d \tau} \mathbf{v}\left(\mathbf{r}^{\prime}+\int_{0}^{t} \mathbf{v}(\mathbf{r}, \tau) d \tau, t\right)= \\
& \frac{\partial \mathbf{v}(\mathbf{r}, t)}{\partial t}+\frac{\partial \mathbf{r}}{\partial t} \cdot \nabla_{\mathbf{r}} \mathbf{v}(\mathbf{r}, t)=\frac{\partial \mathbf{v}(\mathbf{r}, t)}{\partial t}+\mathbf{v}(\mathbf{r}, t) \cdot \nabla_{\mathbf{r}} \mathbf{v}(\mathbf{r}, t) .
\end{aligned}
$$

## References

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