

1 **Special Relativity – Alternative Lorentz transformations**

2

3 **Jan Slowak**

4 Independent researcher

5 jan.slowak@gmail.com

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7

8 **Abstract**

9 Einstein's theory of special relativity, SR, is a generally accepted theory that analyses,
10 for instance, relationships between two inertial reference systems moving at a
11 constant speed against each other. This relationship between the coordinates of an
12 event in the two inertial reference systems is made using so-called Lorentz
13 Transformations, LT. These transformations constitute the most central concept
14 within SR.

15

16 We will build an alternative theory to SR. We will derive **new transformations**
17 between the two reference systems. It will be easy to compare these two theories. We
18 will show that if all the steps taken during the derivation apply the existing
19 mathematics, logic and physics, our transformations will be flawless, contradiction
20 free! We follow the same steps, the same way of thinking as one do in [B1].

22 **Keywords**

23 Special Relativity, Reference System, Event, Light Signal, Lorentz Transformations,
24 Mathematical model, Alternative theory

25

26 **1 Our thought experiments**

27 Imagine a highway, perfectly straight and perfectly horizontal. On this highway, we
28 mark a point where an observer S is located. An additional observer, S', is at the same
29 point at the beginning of each thought experiment (in our case we can do these
30 experiments for real). The observer S' moves at constant speed $v > 0$ to the right in our
31 model. We decide that $v = 2 \text{ m/s}$.

32

33 The two observers exchange information using a Tesla car that moves during our
34 experiments at a constant speed $w = 20 \text{ m/s}$.

35

36 **An event** that occurs in our reality will be considered as a point in the two
37 2-dimensional reference systems:

38 (x, t) for S

39 (x', t') for S'

40 where x, x' is the coordinate of space and t, t' is the coordinate of time.

41

42 We will try to determine **two linear transformations** (equations) between (x, t) and
43 (x', t') and vice versa.

44

45 We denote them by LEx' and LET':

46

$$47 \quad \text{LEx}': x' = Ax + Bt$$

$$48 \quad \text{LET}': t' = Cx + Dt$$

49

50 With a little simple mathematics, we get the corresponding **inverse transformation**
51 $\text{LEx}: x = (D/K)x' - (B/K)t'$
52 $\text{LET}: t = -(C/K)x' + (A/K)t'$
53 where $K = AD - BC$. These two systems of equations are equivalent.

54

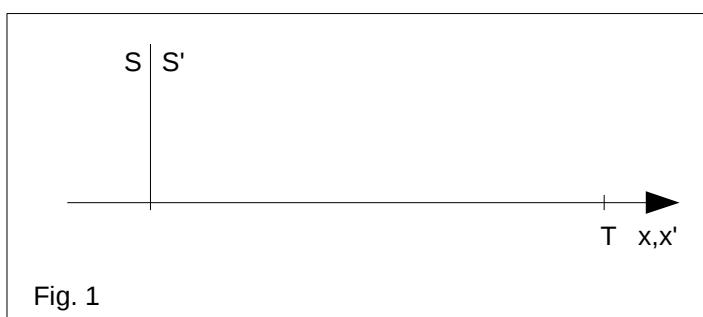
55 To determine the constants A, B, C and D , we perform two thought experiments and
56 name them special cases, SC.

57 We consider two inertial reference systems, S and S', two 2-dimensional coordinate
58 systems. Their x-axis and x'-axis coincide on the same line.

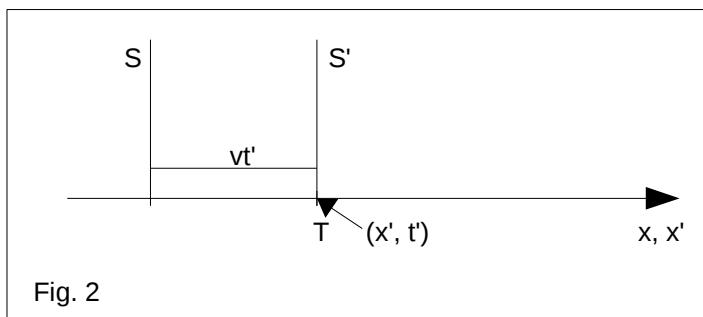
59

60 2. SC1

61 At the beginning of this experiment, S and S' are at the same point. The car is moving
62 at a constant speed, $w > 0$, **from the right** towards these two observers.



72 After a time, $t' > 0$, Tesla passes S' on its way to S.



82 At this moment S' reads time t' and considers that the event has occurred in its origin,
83 $x' = 0$.

84 $(x', t') = (0, t')$.

85

86 **It is obvious that the distance between S and S', at this moment, is vt' !**

87 After this, the car continues on to S and when it reaches this observer, S reads the
88 time t . What value does t have?

89 t is t' plus the time the car needs to drive the distance vt' .

90 $t = t' + vt'/w \rightarrow t = t'(1 + v/w) \rightarrow$

91 $\mathbf{t} = t'(\mathbf{w} + \mathbf{v})/\mathbf{w}$

92

93 Then S can calculate the time when the event occurred in S'-origo.

94 $\mathbf{t}' = \mathbf{tw}/(\mathbf{w} + \mathbf{v})$

95

96 and can then also calculate the distance to the point where the event occurred.

97 $x = vt' \rightarrow x = twv/(w + v)$

98

99 Now we have the coordinates of the event for both S' and S

100 $(x', t') = (0, t')$

101 $(x, t) = (twv/(w + v), tw/(w + v))$

102

103 We replace these coordinates in LEx' and LET' to determine A, B, C and D.

104

105 From LEx', (x', t') and (x, t) we get

106 $\text{LEx}': x' = Ax + Bt$

107 $0 = Atwv/(w + v) + Btw/(w + v) \rightarrow$

108 $0 = Av + B \rightarrow$

109 $\mathbf{B} = -\mathbf{Av}$

110

111 From LET', (x', t') and (x, t) we get

112 $\text{LET}': t' = Cx + Dt$

113 $tw/(w + v) = Ctwv/(w + v) + Dtw/(w + v) \rightarrow$

114 $1 = Cv + D \rightarrow$

115 $\mathbf{C} = (\mathbf{1} - \mathbf{D})/\mathbf{v}$

116

117 We get the same value for B and C if we use

118 $(x', t') = (0, t')$

119 $(x, t) = (vt', t').$

120

121 3. SC2

122 At the beginning of this experiment, S and S' are at the same point. The car is moving
123 at a constant speed, $w > 0$, **from the left** towards these two observers.

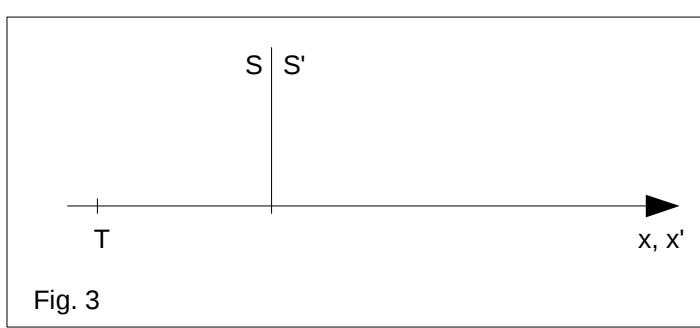


Fig. 3

133 After a time, $t > 0$, Tesla passes S on its way to S'.
 134 This event is shown in the Fig. 4.
 135
 136 When the car passes S, the observer in S reads the time t . It is considered that the
 137 event occurred in S-origo.
 138 $(x, t) = (0, t)$.

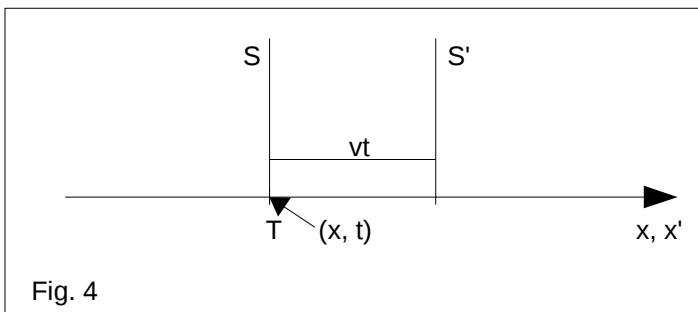


Fig. 4

148 **It is obvious that the distance between S and S', at this moment, is vt !**
 149
 150 After this, the car continues on to S'. But as the car approaches S', this reference
 151 system manages to go a small chunk.

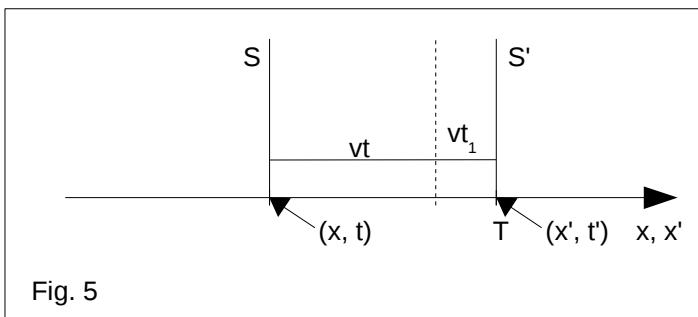


Fig. 5

161 The observer in S' reads the time t' .
 162 The distance between S and S' at this moment is x' . We see that

$$\begin{aligned} x' &= vt' \rightarrow \\ x' &= vt + vt_1 \rightarrow \\ t' &= t + t_1 \end{aligned}$$

166 but we also see that

$$x' = wt_1$$

168
 169 It is the distance that the car moves between S and S'. From here we get

$$\begin{aligned} vt + vt_1 &= wt_1 \rightarrow \\ vt &= t_1(w - v) \rightarrow \\ t_1 &= tv / (w - v) \rightarrow \end{aligned}$$

173 From

$$\begin{aligned} t' &= t + t_1 \text{ and} \\ t_1 &= tv / (w - v) \rightarrow \\ t' &= t + tv / (w - v) \rightarrow \\ t' &= tw / (w - v) \end{aligned}$$

178 Now we have the coordinates of the event for both S' and S
 179 $(x, t) = (0, t)$
 180 $(x', t') = (-vt', t')$ or
 181 $(x', t') = (-twv/(w-v), tw/(w-v))$
 182
 183 We have the minus sign because x' is measured to the left, towards the negative part
 184 of the x-axis, x'-axis.
 185 We replace these coordinates in LEx' and LET' to determine A, B, C and D.
 186
 187 From LEx', (x', t') and (x, t) we get
 188 $\text{LEx}': x' = Ax + Bt$
 189 $-twv/(w-v) = A*0 + Bt \rightarrow$
 190 $B = -wv/(w-v)$
 191
 192 From LET', (x', t') and (x, t) we get
 193 $\text{LET}': t' = Cx + Dt$
 194 $tw/(w-v) = C*0 + Dt \rightarrow$
 195 $tw/(w-v) = Dt \rightarrow$
 196 $D = w/(w-v)$
 197
 198 **4. Merger of results**
 199 From these two thought experiments we obtained the following relations for the
 200 constants A, B, C and D.
 201
 202 $B = -Av$
 203 $C = (1-D)/v$
 204 $B = -wv/(w-v)$
 205 $D = w/(w-v)$
 206 \rightarrow
 207 $A = -B/v \rightarrow$
 208 $A = w/(w-v)$
 209 $C = (1-D)/v \rightarrow$
 210 $C = -1/(w-v)$
 211
 212 We have seen in section 1 that the inverse transformation has the form
 213 $\text{LEx}: x = (D/K)x' - (B/K)t'$
 214 $\text{LET}: t = -(C/K)x' + (A/K)t'$
 215 where $K = AD - BC$.
 216
 217 When we calculate the value of the expression $AD - BC$ we get
 218 $K = w/(w-v)*w/(w-v) - (-wv/(w-v))*(-1/(w-v)) \rightarrow$
 219 $K = w^2/(w-v)^2 - wv/((w-v)^2) \rightarrow$
 220 $K = (w^2 - wv)/(w-v)^2 \rightarrow$
 221 $K = w(w-v)/(w-v)^2 \rightarrow$

222 $\mathbf{K} = \mathbf{w}/(\mathbf{w} - \mathbf{v})$

223

224 We see that $K = A = D$.

225

226 Now we can write the two new transformations between coordinate systems for S and
227 S'.

228 NTx': $x' = (w/(w-v))x - (wv/(w-v))t$

229 NTt': $t' = -(1/(w-v))x + (w/w-v)t$

230

231 If we denote $w/(w-v) = K$ we get

232 NTx': $x' = (x - vt)K$

233 NTt': $t' = (t - x/w)K$

234

235 We replace A, B, C, D and K in LTx and LTt.

236 NTx: $x = (D/K)x' - (B/K)t'$

237 NTt: $t = -(C/K)x' + (A/K)t'$

238 →

239 NTx: $x = x' + vt'$

240 NTt: $t = t' + x'/w$

241

242 It feels strange that NTx' and NTt' contain K-factor but NTx and NTt do not.

243

244 We have obtained two pairs of new transformations between the coordinates of the two
245 inertial reference systems:

246 NTx': $x' = (x - vt)K$

247 NTt': $t' = (t - x/w)K$

248

249 NTx: $x = x' + vt'$

250 NTt: $t = t' + x'/w$

251

252 Our two events from our two special cases are:

253 SC1 $(x', t') = (0, t')$

254 $(x, t) = (twv/(\mathbf{w} + \mathbf{v}), tw/(\mathbf{w} + \mathbf{v}))$

255

256 SC2 $(x, t) = (0, t)$

257 $(x', t') = (-twv/(\mathbf{w} - \mathbf{v}), tw/(\mathbf{w} - \mathbf{v}))$

258

259 But we also have the relationship between t and t' in each experiment:

260 SC1 $t = t'(w + v)/w$

261 $t' = tw/(w + v)$

262

263 SC2 $t' = tw/(w - v)$

264 $t = t'(w - v)/w$

265

266 In [B1] the value of A is determined by assuming that Lorentz transformations are
267 symmetric and by replacing

268 x' with x ,

269 t' with t ,

270 x with x' ,

271 t with t'

272 v with $-v$

273

274 in the LTx' and LTt'

275 $NTx': x' = (x - vt)K$

276 $NTt': t' = (t - x/w)K$

277 \rightarrow

278 $NTx: x = (x' + vt')K$

279 $NTt: t = (t' + x'/w)K$

280

281 But before we got the following

282 $NTx: x = x' + vt'$

283 $NTt: t = t' + x'/w$

284 \rightarrow

285 $K = 1 \rightarrow$

286 $v = 0$

287

288 Again we get the result that LT only applies to $v = 0$.

289 Why do we always get this result?

290 **The reason is that we are trying to build linear transformations between S
291 and S'.**

292 Such transformations **do not exist** between S and S' if we use as the carrier of the
293 message between these two reference systems light signals (or a Tesla car).

294

295 The transition from one reference system to another depends on how these two inertial
296 reference systems move relative to each other and especially from which direction the
297 light signal moves towards the reference system in motion [B3].

298

299 **5. Verification of calculations**

300 We verify our calculations by replacing these coordinates in our equations.

301 We should get equality as a result!

302

303 First, we look at all four transformations, NTx' , NTt' , NTx , NTt and conditions in SC1.

304

305 NTx' , SC1:

306 $NTx': x' = (x - vt)K$

307 $(x', t') = (0, t')$

308 $(x, t) = (twv/(w+v), tw/(w+v))$

309 $t = t'(w+v)/w$

310 $t' = tw / (w + v)$
 311 →
 312 $0 = (twv / (w + v) - vt w / (w + v))K \rightarrow$
 313 **$0 = 0 \rightarrow ok$**
 314
 315 NTt', SC1:
 316 NTt': $t' = (t - x/w)K$
 317 $(x', t') = (0, t')$
 318 $(x, t) = (twv / (w + v), tw / (w + v))$
 319 $t = t'(w + v) / w$
 320 $t' = tw / (w + v)$
 321 →
 322 $tw / (w + v) = ((-1/v)twv / (w + v) + tw / (w + v))K \rightarrow$
 323 **$0 = 0 \rightarrow ok$**
 324
 325 NTx, SC1:
 326 NTx: $x = x' + vt'$
 327 $(x', t') = (0, t')$
 328 $(x, t) = (twv / (w + v), tw / (w + v))$
 329 $t = t'(w + v) / w$
 330 $t' = tw / (w + v)$
 331 →
 332 $twv / (w + v) = 0 + vt w / (w + v)$
 333 **$0 = 0 \rightarrow ok$**
 334
 335 NTt, SC1:
 336 NTt: $t = t' + x' / w$
 337 $(x', t') = (0, t')$
 338 $(x, t) = (twv / (w + v), tw / (w + v))$
 339 $t = t'(w + v) / w$
 340 $t' = tw / (w + v)$
 341 →
 342
 343 $tw / (w + v) = 0 + tw / (w + v)$
 344 **$0 = 0 \rightarrow ok$**
 345
 346 Now, we look at all four transformations, NTx', NTt', NTx, NTt and conditions in SC2.
 347 NTx', SC2:
 348 NTx': $x' = (x - vt)K$
 349 $(x, t) = (0, t)$
 350 $(x', t') = (-twv / (w - v), tw / (w - v))$
 351 $t' = tw / (w - v)$
 352 $t = t'(w - v) / w$
 353 →

354 $- twv / (w - v) = (0 - vt)K \rightarrow$
 355 $- twv / (w - v) = - vtw / (w - v) \rightarrow$
 356 $\mathbf{0} = \mathbf{0} \rightarrow \mathbf{ok}$
 357
 358 NTt', SC2:
 359 NTt': $t' = (t - x/w)K$
 360 $(x, t) = (0, t)$
 361 $(x', t') = (- twv / (w - v), tw / (w - v))$
 362 $t' = tw / (w - v)$
 363 $t = t'(w - v) / w$
 364 \rightarrow
 365 $tw / (w - v) = (0 + t)K \rightarrow$
 366 $tw / (w - v) = tw / (w - v) \rightarrow$
 367 $\mathbf{0} = \mathbf{0} \rightarrow \mathbf{ok}$
 368
 369 NTx, SC2:
 370 NTx: $x = x' + vt'$
 371 $(x, t) = (0, t)$
 372 $(x', t') = (- twv / (w - v), tw / (w - v))$
 373 $t' = tw / (w - v)$
 374 $t = t'(w - v) / w$
 375 \rightarrow
 376 $0 = - twv / (w - v) + vtw / (w - v) \rightarrow$
 377 $\mathbf{0} = \mathbf{0} \rightarrow \mathbf{ok}$
 378
 379 NTt, SC2:
 380 NTt: $t = t' + x' / w$
 381 $(x, t) = (0, t)$
 382 $(x', t') = (- twv / (w - v), tw / (w - v))$
 383 $t' = tw / (w - v)$
 384 $t = t'(w - v) / w$
 385 \rightarrow
 386
 387 $t = (1/w)(- twv / (w - v) + tw / (w - v)) \rightarrow$
 388 $t = t(- v / (w - v) + w / (w - v))$
 389 $t = t(w - v) / (w - v) \rightarrow$
 390 $\mathbf{0} = \mathbf{0} \rightarrow \mathbf{ok}$
 391
 392 **6. Conclusions**
 393 We have derived four transformations, equations, using two thought experiments.
 394 In each experiment, we calculated the value of the event coordinates for the two
 395 inertial reference systems.
 396
 397 We have verified the four equations using the value of the event coordinates from the

398 two experiments.

399 **Each verification has given us the result $0 = 0$, an equality!**

400

401 Remember that this does not happen when we verify Lorentz transformations from
402 SR. There we only get **one equality** of six verifications! See [A2], pages 53-54:

403 LTx' , SC1 $\rightarrow 0 = 0$ OK

404 LTt' , SC1 $\rightarrow t' = t/\gamma$

405 LTx' , SC2 $\rightarrow t' = t\gamma$

406 LTt' , SC2 $\rightarrow t' = t\gamma$

407 LTx' , SC3 $\rightarrow t' = t\gamma(c - v)/c$

408 LTt' , SC3 $\rightarrow t' = t\gamma(c - v)/c$

409

410 **Why? How is that possible?**

411 **My only answer is that you have made a mistake somewhere!**

412

413 All my verifications of Lorentz transformations in SR give the conclusion that Lorentz
414 transformations only applies to $v = 0$!

415 Therefore, my conclusion in all my research ends with the sentence that

416 **Special Relativity is nonsense!**

417

418 **7. Comparisons between the derivation of Lorentz transformations within SR
419 and this work**

420 In this work I use only **two** thought experiments while in SR **three** are used!

421 How is it possible that I managed to derive the constants A, B, C and D only with **two**
422 thought experiments and I get all verification as **equalities** while within SR **three**
423 thought experiments are used and you do not get all verifications as **equalities**?

424 Think about this!

425

426 Here we show once again two pairs of transformations we got in this work:

427 $NTx': x' = (x - vt)w / (w - v)$

428 $NTt': t' = (t - x/w)w / (w - v)$

429

430 $NTx: x = x' + vt'$

431 $NTt: t = t' + x'/w$

432

433 If we replace x' from NTx' and t' from NTt' in NTx and NTt we get **equalities**!

434 This is another verification that shows that our calculations are correct!

435

436 In the two thought experiments we have obtained relations between the value of the
437 t- and t'-coordinates.

438

439 SC1 $t = t'(w + v) / w$

440 $t' = tw / (w + v)$

441

442 SC2 $t' = tw / (w - v)$
443 $t = t'(w - v) / w$
444
445 When the carrier of the information between the two observers comes from the right
446 (as it approaches S' from the front), the conversion factor is $(w + v) / w$.
447 When the carrier of the information between the two observers comes from the left (as
448 it approaches S' from behind), the conversion factor is $(w - v) / w$.
449
450 This does not mean that we have some time dilation! This means that the value for
451 time coordinate in one reference system can be calculated using the value for time
452 coordinate in the other reference system!
453
454 **The time in the two reference systems runs at the same rate!**
455 Think about how we did our two thought experiments!
456 Both distance and the time we use are **mathematical quantities**.
457 We used the math to calculate them!
458
459 **We have used current mathematics, simple ones, current logic, and current**
460 **classical physics!**
461
462 **Note that there are so many Lorentz transformations between S and S' how**
463 **many definitions of (x, t) and (x', t') there are!**
464
465 **References**
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