The Time-Neutral Exterior Schwarzschild Metric in Polynomial Form

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The time-neutral metric is introduced and the time-neutral exterior Schwarzschild metric is converted to polynomial form in r and total mass M. The polynomials are found to be cubic with no constant term, which allows the two non-zero roots of each to be extracted from the reduced quadratic form.

Keywords: general relativity, time dilation, neutral metric, metric engineering, quantum gravity

THE TIME-NEUTRAL METRIC

A time-neutral metric is an exact solution to the Einstein field equations [1] multiplied by the inverse length scalar $1/c^2 dt^2$, and set equal to one. The time-neutral metric with signature (+, -, -, -) is given by:

$$\frac{ds^2}{c^2 dt^2} = \frac{d\tau^2}{dt^2} = 1.$$
 (1)

Multiplying the line element by this scalar is a special coordinate transformation that also converts coordinate infinitessimals to dimensionless $ratios^1$

Setting the transformed metric to one represents neutral time dilation ($\Delta t' = \Delta t$), as opposed to maximal time dilation of the zero-time metric $d\tau^2/dt^2 = 0$. That finite, real, solutions to time-neutral metrics exist with $M \neq 0$ may be surprising. It is especially counter-intuitive for the Schwarzschild metric[2], which does not have the opposite sign r_Q^2 or a^2 factors that give additional degrees of freedom[3, 4] to higher order metrics. However, these solutions do exist mathematically.

Further transforming the time-neutral metric into polynomial form has the effect of replacing the divergence at r = 0 in the standard form of the metric, with the constraint $v_r^2/c^2 \neq 0$ in the polynomial form. Even if this is not physical it might be a useful tool for quantum gravity research.

The open-source software tool knsolver[5] can be used to generate plots of solutions to the time-neutral and zerotime metrics. It uses numerical methods on the standard form of the Kerr-Newman[6] metric which is flexible but slow, especially for precision results. Converting a time-neutral metric to polynomial form may allow for fast exact solutions, depending on the degree of the polynomial.

The time-neutral metric should not be confused with metrics of neutral signature [7-11] (+, +, -, -), which are often referred to as "neutral metrics" in mathematical literature.

POLYNOMIAL FORM

As shown in the proof below, the time-neutral exterior Schwarzschild metric in spherical coordinates (t, r, θ, φ) , with test particle velocities converted to v^2/c^2 , as a polynomial in r and total mass M are given by:

$$\left(\frac{v_r^2}{c^2} + \frac{v_{\Omega}^2}{c^2}\right)r_{\rm s}r^3 + \left(1 - \frac{v_{\Omega}^2}{c^2}\right)r_{\rm s}^2r^2 - r_{\rm s}^3r = 0,\tag{2}$$

$$\frac{8G^3r}{c^6}M^3 - \left(1 - \frac{v_{\Omega}^2}{c^2}\right)\frac{4G^2r^2}{c^4}M^2 - \left(\frac{v_r^2}{c^2} + \frac{v_{\Omega}^2}{c^2}\right)\frac{2Gr^3}{c^2}M = 0,$$
(3)

$$r_{\rm s} = \frac{2GM}{c^2}, \quad (r \ge R), \quad \left(v_r^2/c^2 \ne 0\right).$$
 (4)

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¹ In metrics where angular momentum $J \neq 0$, an arbitrary finite non-zero value can be assigned to the remaining linear dt factors without affecting the neutral metric. knsolver sets this to t_P , but other values such as 1, or even -1 also work. The remaining linear $d\varphi$ factors must then be derived from $d\varphi = v_{\varphi} dt/r$.

 $\mathbf{2}$

As both are cubic with no constant term, the two non-zero roots of each can be recovered from the reduced quadratic equations:

$$\left(\frac{v_r^2}{c^2} + \frac{v_\Omega^2}{c^2}\right)r_{\rm s}r^2 + \left(1 - \frac{v_\Omega^2}{c^2}\right)r_{\rm s}^2r - r_{\rm s}^3 = 0,\tag{5}$$

$$\frac{8G^3r}{c^6}M^2 - \left(1 - \frac{v_{\Omega}^2}{c^2}\right)\frac{4G^2r^2}{c^4}M - \left(\frac{v_r^2}{c^2} + \frac{v_{\Omega}^2}{c^2}\right)\frac{2Gr^3}{c^2} = 0,$$
(6)

$$r_{\rm s} = \frac{2GM}{c^2}, \quad (r \ge R), \quad \left(v_r^2/c^2 \ne 0\right).$$
 (7)

This agrees with the two non-zero roots for each implied by plots generated from knsolver[5] when electric charge Q and angular momentum J are set to zero.

PROOF

Deriving the polynomials involves basic algebraic manipulation but special care must be taken to not lose the degrees of freedom represented by the inverse sum $\left(1 - \frac{r_s}{r}\right)^{-1}$ in the dr^2 term. This proof also uses some substitutions that are not strictly necessary here but can be used to help manage the proliferation of length factors in the higher order metrics[6, 12, 13].

We begin with the exterior $(r \ge R)$ Schwarzschild metric[2] in spherical coordinates (t, r, θ, φ) and metric signature (+, -, -, -):

$$ds^{2} = c^{2}d\tau^{2} = \left(1 - \frac{r_{s}}{r}\right)c^{2}dt^{2} - \left(1 - \frac{r_{s}}{r}\right)^{-1}dr^{2} - r^{2}d\Omega^{2}, \quad (r \ge R),$$
(8)

$$r_{\rm s} = \frac{2GM}{c^2}, \quad d\Omega^2 = d\theta^2 + \sin\theta d\varphi^2.$$
 (9)

Divide the metric by $c^2 dt^2$ and set equal to one to obtain the time-neutral metric, also convert test particle velocities to v^2/c^2 . This is the equation we will convert to polynomial form:

$$\frac{d\tau^2}{dt^2} = \left(1 - \frac{r_{\rm s}}{r}\right) - \frac{v_r^2}{c^2} \left(1 - \frac{r_{\rm s}}{r}\right)^{-1} - \frac{v_\Omega^2}{c^2} = 1, \quad (r \ge R),$$
(10)

$$\frac{v_r^2}{c^2} = \frac{dr^2}{c^2 dt^2}, \qquad \frac{v_{\Omega}^2}{c^2} = \frac{r^2 d\Omega^2}{c^2 dt^2}.$$
(11)

Multiply the dt^2 and $d\Omega^2$ terms by $\left(1 - \frac{r_s}{r}\right) / \left(1 - \frac{r_s}{r}\right)$, then simplify the denominator by dividing both sides by r. At this point we must add the constraint $v_r^2/c^2dt^2 \neq 0$ as we are combining the dr^2 term inverse length factor with the other terms in the denominator.

$$(r \ge R), \quad (v_r^2/c^2 \ne 0),$$
 (12)

$$\frac{\left(1 - \frac{r_{\rm s}}{r}\right)\left(1 - \frac{r_{\rm s}}{r}\right) - \frac{v_r^2}{c^2} - \frac{v_\Omega^2}{c^2}\left(1 - \frac{r_{\rm s}}{r}\right)}{1 - \frac{r_{\rm s}}{r}} = 1,\tag{13}$$

(14)

$$\frac{\left(1-\frac{r_{\rm s}}{r}\right)\left(1-\frac{r_{\rm s}}{r}\right)-\frac{v_{r}^{2}}{c^{2}}-\frac{v_{\Omega}^{2}}{c^{2}}\left(1-\frac{r_{\rm s}}{r}\right)}{r-r_{\rm s}}=\frac{1}{r}.$$
(15)

Multiply out the dt^2 term product, then simplify the numerator by multiplying both sides by r^2 , then group by terms of r being especially careful with signs of combined factors:

$$\frac{1 - \frac{2r_{\rm s}}{r} + \frac{r_{\rm s}^2}{r^2} - \frac{v_r^2}{c^2} - \frac{v_{\Omega}^2}{c^2} \left(1 - \frac{r_{\rm s}}{r}\right)}{r - r_{\rm s}} = \frac{1}{r},\tag{16}$$

$$\frac{r^2 - 2r_{\rm s}r + r_{\rm s}^2 - \frac{v_r^2}{c^2}r^2 - \frac{v_\Omega^2}{c^2}\left(r^2 - r_{\rm s}r\right)}{r - r_{\rm s}} = r,\tag{17}$$

$$\frac{\left(1 - \frac{v_r^2}{c^2} - \frac{v_\Omega^2}{c^2}\right)r^2 - \left(2 - \frac{v_\Omega^2}{c^2}\right)r_{\rm s}r + r_{\rm s}^2}{r - r_{\rm s}} = r.$$
(18)

At this point we introduce temporary variables X, Y, to help capture the extra degrees of freedom in the inverse sum. Let X be the numerator on the left side of equation 18:

$$\frac{X}{r-r_{\rm s}} = r,\tag{19}$$

$$X = \left(1 - \frac{v_r^2}{c^2} - \frac{v_\Omega^2}{c^2}\right)r^2 - \left(2 - \frac{v_\Omega^2}{c^2}\right)r_{\rm s}r + r_{\rm s}^2.$$
(20)

The denominator sum is now split between numerators X and Y:

$$\frac{X}{r-r_{\rm s}} = \frac{X}{r} + \frac{Y}{r_{\rm s}},\tag{21}$$

$$\frac{X}{r-r_{\rm s}} = \frac{Xr_{\rm s} + Yr}{r_{\rm s}r}.$$
(22)

It is now safe to multiply both sides by $(r - r_s) r_s r$, then we group by terms of X and Y:

$$Xr_{\rm s}r = (Xr_{\rm s} + Yr)(r - r_{\rm s}), \qquad (23)$$

$$Xr_{\rm s}r = Xr_{\rm s}r - Xr_{\rm s}^2 + Yr^2 - Yr_{\rm s}r,$$
(24)

$$Xr_{\rm s}^2 = Y\left(r^2 - r_{\rm s}r\right). \tag{25}$$

Substitute symbols X_f , Y_f , for length factors associated with X and Y, then solve for Y:

$$XX_f = YY_f, (26)$$

$$X_f = r_s^2, \quad Y_f = r^2 - r_s r,$$
 (27)

$$Y = \frac{XX_f}{Y_f}.$$
(28)

With equations 19 and 22, multiply by $r_s r$ and substitute for Y using equation 28:

$$\frac{Xr_{\rm s} + Yr}{r_{\rm s}r} = r,\tag{29}$$

$$Xr_{\rm s} + \frac{XX_f r}{Y_f} = r_{\rm s} r^2. \tag{30}$$

Multiply by Y_f , then group by terms of X:

$$XY_f r_s + XX_f r = Y_f r_s r^2, aga{31}$$

$$X(Y_f r_s + X_f r) - Y_f r_s r^2 = 0.$$
 (32)

Substitute symbols F_1, F_2, F_3 , for the combined length factors:

$$X(F_1 + F_2) - F_3 = 0, (33)$$

$$F_1 = Y_f r_s, \quad F_2 = X_f r, \quad F_3 = Y_f r_s r^2.$$
 (34)

With equations 27, and 34, solve $F_1 + F_2$, and with equation 20, $X(F_1 + F_2)$:

$$F_1 = r_{\rm s} r^2 - r_{\rm s}^2 r, \quad F_2 = r_{\rm s}^2 r, \tag{35}$$

$$F_1 + F_2 = r_{\rm s} r^2, (36)$$

$$X(F_1 + F_2) = \left[\left(1 - \frac{v_r^2}{c^2} - \frac{v_\Omega^2}{c^2} \right) r^2 - \left(2 - \frac{v_\Omega^2}{c^2} \right) r_s r + r_s^2 \right] r_s r^2,$$
(37)

$$X(F_1 + F_2) = \left(1 - \frac{v_r^2}{c^2} - \frac{v_\Omega^2}{c^2}\right) r_{\rm s} r^4 - \left(2 - \frac{v_\Omega^2}{c^2}\right) r_{\rm s}^2 r^3 + r_{\rm s}^3 r^2.$$
(38)

Solve F_3 and $X(F_1 + F_2) - F_3$:

$$F_3 = r_{\rm s} r^4 - r_{\rm s}^2 r^3, \tag{39}$$

$$X\left(F_{1}+F_{2}\right)-F_{3}=\left(1-\frac{v_{r}^{2}}{c^{2}}-\frac{v_{\Omega}^{2}}{c^{2}}\right)r_{s}r^{4}-\left(2-\frac{v_{\Omega}^{2}}{c^{2}}\right)r_{s}^{2}r^{3}+r_{s}^{3}r^{2}-r_{s}r^{4}+r_{s}^{2}r^{3}.$$
(40)

With equations 33 and 40, divide by r as the smallest degree of r is 2:

$$\left(1 - \frac{v_r^2}{c^2} - \frac{v_\Omega^2}{c^2}\right) r_{\rm s} r^4 - \left(2 - \frac{v_\Omega^2}{c^2}\right) r_{\rm s}^2 r^3 + r_{\rm s}^3 r^2 - r_{\rm s} r^4 + r_{\rm s}^2 r^3 = 0,\tag{41}$$

$$\left(1 - \frac{v_r^2}{c^2} - \frac{v_\Omega^2}{c^2}\right) r_{\rm s} r^3 - \left(2 - \frac{v_\Omega^2}{c^2}\right) r_{\rm s}^2 r^2 + r_{\rm s}^3 r - r_{\rm s} r^3 + r_{\rm s}^2 r^2 = 0.$$
(42)

Convert to standard polynomial form in r by grouping terms by r, then inverting the sign of each term, and applying the constraints from equation 12:

$$\left(-\frac{v_r^2}{c^2} - \frac{v_\Omega^2}{c^2}\right)r_{\rm s}r^3 - \left(1 - \frac{v_\Omega^2}{c^2}\right)r_{\rm s}^2r^2 + r_{\rm s}^3r = 0,\tag{43}$$

$$\left(\frac{v_r^2}{c^2} + \frac{v_\Omega^2}{c^2}\right) r_{\rm s} r^3 + \left(1 - \frac{v_\Omega^2}{c^2}\right) r_{\rm s}^2 r^2 - r_{\rm s}^3 r = 0, \quad \left(r \ge R, \ v_r^2/c^2 \ne 0\right)$$
(44)

Convert to standard polynomial form in M by substituting $r_s = \frac{2GM}{c^2}$, then grouping terms by M and inverting signs again:

$$\left(\frac{v_r^2}{c^2} + \frac{v_\Omega^2}{c^2}\right)\frac{2GM}{c^2}r^3 + \left(1 - \frac{v_\Omega^2}{c^2}\right)\frac{4G^2M^2}{c^4}r^2 - \frac{8G^3M^3}{c^6}r = 0,$$
(45)

$$\frac{8G^3r}{c^6}M^3 - \left(1 - \frac{v_{\Omega}^2}{c^2}\right)\frac{4G^2r^2}{c^4}M^2 - \left(\frac{v_r^2}{c^2} + \frac{v_{\Omega}^2}{c^2}\right)\frac{2Gr^3}{c^2}M = 0, \quad \left(r \ge R, \ v_r^2/c^2 \ne 0\right)$$
(46)

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