# On the modified Emden-type equation with quadratic damping 

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#### Abstract

We exhibit in this paper a complex-valued solution for a modified Emden-type equation with quadratic damping. We show also the conditions of existence of periodic solution and calculate it for the first time.


Keywords: Modified Emden-type equation, quadratic damping, general solution, exact periodic solution

## Introduction

Recently, it is observed that many nonlinear differential equations claimed by certain authors in the literature to be nonlinear conservative oscillators are rather pseudo-oscillators, since these can exhibit non-oscillatory behavior for the same numerical parameters. Gadella and coworkers [1] were the first to raise this problem for the truly nonlinear differential equation

$$
\begin{equation*}
\ddot{x}+\frac{1}{x}=0 \tag{1}
\end{equation*}
$$

The authors were able to show that the general solutions of the equation are nonoscillatory so that they conclude that the equation (1) is in fact a pseudooscillator even if it has a constant time-independent Hamiltonian. After this, Doutètien and coworkers [2] confirmed the results obtained in [1] by successfully calculating explicitly the two general non-periodic solutions predicted in [1]. The same pseudo-oscillator feature was observed for many others nonlinear differential equations mentioned to be conservative oscillators. A remarkable case is the so-called Mathews-Lakshmanan equation [3]. This equation has been widely studied in the literature as a unique nonlinear oscillator having harmonic periodic solution but with amplitude-dependent frequency. However, it has been recently shown in a lot of papers that there exists a number of such equations that can exhibit sinusoidal periodic solutions [4, 5]. In [6, 7] the authors have shown even the existence of quadratic Lienard type equation

[^0]exhibiting the harmonic periodic solution with amplitude-independent frequency for the first time. In other words these equations have the linear harmonic oscillator solution. On the other hand Akande et al. [8] have shown recently the existence of real-valued and complex-valued solutions of the MathewsLakshmanan equation. They concluded then the Mathews-Lakshmanan equation is in fact a pseudo-oscillator. Another interesting case is the generalized Emden type equation presented by Chandrasekar and his group [9] as a Lienard type nonlinear oscillator in 2005. Later this equation has been widely studied in the literature as a conservative oscillator [10, 11]. However, in [12] the authors succeeded to calculate an unbounded periodic solution for the so-called Lienard type nonlinear oscillator. Also these authors [12] concluded that the generalized Emden type equation claimed to be a Lienard type nonlinear oscillator is in fact a pseudo-oscillator. In this context it is reasonable to ask whether the modified Emden-type equation with quadratic damping.
\[

$$
\begin{equation*}
\ddot{x}+k x \dot{x}^{2}+k_{1} x+k_{2} x^{3}=0 \tag{2}
\end{equation*}
$$

\]

where $k, k_{1}$ and $k_{2}$ are constants, and the overdot means derivative with respect to time, introduced by Ghosh et al. [13] is effectively a conservative oscillator as claimed by the authors. The equation belongs to the also of quadratic Lienard type equations intensively investigated in the literature [14]. However, the authors [13] were unable to prove their claim by a presentation of exact periodic solutions. Instead of exact periodic solutions, the authors [13] used qualitative theory of differential equation in the phase space to conclude to the conservative oscillator feature of this equation. They have been only able to calculate approximate analytical solution for the equation. In [15] the equation (2) is also investigated using symmetry methods, but no exact periodic solution has been exhibited by the author. In this work we exhibit for the first time the exact and general periodic solution of this equation when $\frac{k_{2}}{k_{1}}<0$, as well as the complexvalued solutions, to conclude that such a modified Emden-type equation could not be a conservative oscillator but rather a pseudo-oscillator. In this perspective we show that the equation (2) belongs to a general class of quadratic Lienard type equations introduced recently in the literature by Monsia and his group (section 2) and exhibit its general solutions (section 3). We present finally a conclusion for the work.

## 2- The statement of the equation (2)

To establish the equation (2) let us consider the general class of quadratic Lienard type equations [16-18]

$$
\begin{equation*}
\ddot{x}+\frac{1}{2} \frac{g^{\prime}(x)}{g(x)} \dot{x}^{2}+\frac{a}{2} \frac{f^{\prime}(x)}{g(x)}=0 \tag{3}
\end{equation*}
$$

associated to the corresponding first-order differential equation

$$
\begin{equation*}
g(x) \dot{x}^{2}+a f(x)=b \tag{4}
\end{equation*}
$$

where the prime denotes differentiation with respect to the argument, $a$ and $b$ are arbitrary parameters, and $f(x)$ and $g(x) \neq 0$, are arbitrary functions of the variable $x$. Now let $g(x)=e^{k x^{2}}$, and $f(x)=\left(c_{1}+c_{2} x^{2}\right) e^{k x^{2}}$. Then one may obtain $f^{\prime}(x)=2\left[\left(c_{1} k+c_{2}\right) x+c_{2} k x^{3}\right] e^{k x^{2}}$, so that the equation (3) reduces to the equation

$$
\begin{equation*}
\ddot{x}+k x \dot{x}^{2}+a\left(c_{1} k+c_{2}\right) x+a c_{2} k x^{3}=0 \tag{5}
\end{equation*}
$$

which becomes the equation (2) when $k_{1}=a\left(c_{2}+c_{1} k\right)$, and $k_{2}=a c_{2} k . c_{1}$ and $c_{2}$ are arbitrary constants. In this regard the equation (4) transforms into

$$
\begin{equation*}
e^{k x^{2}} \dot{x}^{2}+a\left(c_{1}+c_{2} x^{2}\right) e^{k x^{2}}=b \tag{6}
\end{equation*}
$$

Using the equation (6) one may get the general solutions of the equation (2).

## 3- The general solutions of the equation (2)

We calculate the complex-valued solution (3.1) and secondly exhibit the exact and general periodic solution (3.2).

### 3.1 Complex-valued solutions

From the equation (6) one may, after variables separation, write

$$
\begin{equation*}
\frac{d x}{\sqrt{b e^{-k x^{2}}-a c_{1}-a c_{2} x^{2}}}= \pm d t \tag{7}
\end{equation*}
$$

Letting $b=0$, reduces the equation (7) to

$$
\begin{equation*}
\frac{d x}{\sqrt{-\left(a c_{1}+a c_{2} x^{2}\right)}}= \pm d t \tag{8}
\end{equation*}
$$

which may be written as

$$
\begin{equation*}
\frac{d x}{\sqrt{1+\frac{c_{2}}{c_{1}} x^{2}}}= \pm \sqrt{-a c_{1}} d t \tag{9}
\end{equation*}
$$

As $k, k_{1}$ and $k_{2}$, are positive constants for the equation introduced by Ghosh et al. [13], then $\frac{c_{2}}{c_{1}}>0$ and $a>0$. In this case, by integration, one may, from (8) obtain

$$
\begin{equation*}
\operatorname{sh}^{-1}\left(\frac{\sqrt{c_{1} c_{2}}}{c_{2}} x\right)= \pm \sqrt{-a c_{2}}(t+\gamma) \tag{10}
\end{equation*}
$$

where $\gamma$ is a constant of integration, such that

$$
\begin{equation*}
x(t)=\frac{\sqrt{c_{1} c_{2}}}{c_{1}} \operatorname{sh}\left[ \pm \sqrt{-a c_{2}}(t+\gamma)\right] \tag{11}
\end{equation*}
$$

As $a>0$, then $c_{1}>0$ and $c_{2}>0$, so that the solution (11) becomes

$$
\begin{equation*}
x(t)=i \frac{\sqrt{c_{1} c_{2}}}{c_{2}} \sin \left[ \pm \sqrt{a c_{2}}(t+\gamma)\right] \tag{12}
\end{equation*}
$$

which may be rearranged in the form

$$
\begin{equation*}
x(t)=i \frac{\sqrt{k k_{2}\left(k k_{1}-k_{2}\right)}}{k k_{2}} \sin \left[ \pm \frac{\sqrt{k k_{2}}}{k}(t+\gamma)\right] \tag{13}
\end{equation*}
$$

As may be seen, the general solution of the equation (2) is a complex-valued function for $k, k_{1}$ and $k_{2}$ positive. Now the objective is to show that when
$\frac{c_{2}}{c_{1}}<0$, that is $\frac{k_{2}}{k_{1}}<0$, the equation (2) may exhibit periodic solution.

### 3.2 Periodic solution

This case corresponds to $\frac{c_{2}}{c_{1}}<0$, that is $\frac{k_{2}}{k_{1}}<0$, when we choose $a>0$. In this way from the equation (9) one may get

$$
\begin{equation*}
\sin ^{-1}\left(\sqrt{-\frac{c_{2}}{c_{1}} x}\right)= \pm \sqrt{a c_{2}}\left(t+\gamma_{1}\right) \tag{14}
\end{equation*}
$$

so that
$x(t)=\sqrt{-\frac{c_{1}}{c_{2}}} \sin \left[ \pm \sqrt{a c_{2}}\left(t+\gamma_{1}\right)\right]$
where $\quad c_{2}>0$, and $\gamma_{1}$ is a constant of integration. The solution (15) may be written in the form

$$
\begin{equation*}
x(t)=\frac{\sqrt{k k_{2}^{2}-k^{2} k_{1} k_{2}}}{k k_{2}} \sin \left[ \pm \frac{\sqrt{k k_{2}}}{k}\left(t+\gamma_{1}\right)\right] \tag{16}
\end{equation*}
$$

The above shows that the general solution of the equation (2) is periodic when $\frac{k_{2}}{k_{1}}<0$, with $k_{2}>0$. It is worth to notice that the equation (2) may be generalized as

$$
\begin{equation*}
\ddot{x}+(m+1) k x^{2 m+1} \dot{x}^{2}+(m+1) k_{1} x^{2 m+1}+(m+1) k_{2} x^{4 m+3}=0 \tag{17}
\end{equation*}
$$

when $f(x)=\left(c_{1}+c_{2} x^{2 m+2}\right) e^{k x^{2 m+2}}$ and $g(x)=e^{k x^{2 m+2}}$. But this will be studied in the subsequent work.

## Conclusion

We have shown in this work that a modified Emden-type equation introduced in the literature by some authors as a Lienard type nonlinear oscillator may exhibit complex-valued solution so that such an equation could not be a conservative oscillator but rather a pseudo-oscillator. We finally have shown the conditions of existence of periodic solution and calculate it for the first time.

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