Motivating Abstract with Elementary Algebra

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Abstract

There are natural lead-ins to abstract algebra that occur in elementary algebra. We explore function composition using linear functions and permutations on letters in misspellings of words. Groups and the central idea of abstract algebra, proving 5th degree and greater polynomials are unsolvable, are put into focus for college students.

Introduction

You like math and are a math major. You've picked up a book on abstract algebra and are feeling a little bit queasy by what you see. Relax. This is a tutorial for you to make the transition from algebra 2, pre-calc, and the like to abstract algebra less anxiety provoking. We'll motivate groups in particular and show how they fit into the grand scheme of abstract algebra.

Linear functions

Groups look at the properties that composition of functions have. You have noticed that functions can have inverses, for example, and that sometimes $f \circ g \neq g \circ f$; see [1], sections 2.6 and 2.7. Consider linear functions, y = f(x) = mx + b with $m \neq 0$.

Definition 1. Let

$$LF[x] = \{f(x) | f(x) = mx + b, \text{ with } m \neq 0\}.$$

LF[x] is closed, meaning the composition of two elements is itself in the set.

Theorem 1. LF[x] is closed under function composition.

Proof. Suppose $f_1(x) = m_1x + b_1$ and $f_2(x) = m_2x + b_2$ and m_1 and m_2 are not zero, i.e. $f_1, f_2 \in LF[x]$. Then

$$f_1(f_2(x)) = m_1(m_2x + b_2) + b_1$$

= $m_1m_2x + m_1b_2 + b_1$
= $m_3x + b_3 \in LF[x].$

Easy enough. We might mention that the slopes m are any non-zero reals. We could limit m to non-zero rationals or natural numbers and maintain this closure property. This is a common theme of abstract algebra. Change the coefficients involved and see what properties are maintained or lost. The next theorem gives a another property of LF[x].

Theorem 2. If $f(x) \in LF[x]$ then it has an inverse function and $f^{-1}(x) \in LF[x]$.

Proof. We use the technique of interchanging x and y, solving for y, and substituting $f^{-1}(x)$ for the result. Suppose f(x) = y = mx + b, then switching

$$x = my + b$$

and solving for y gives

$$f^{-1}(x) = \frac{1}{m}x - \frac{b}{m}.$$

We confirm this result with

$$f(f^{-1}(x)) = m(\frac{1}{m}x - \frac{b}{m}) + b = x$$

and

$$f^{-1}(f(x)) = \frac{1}{m}(mx+b) - \frac{b}{m} = x.$$

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This is more abstract than what you've experienced in previous algebra courses. Before you were given sets, like \mathbb{N} and \mathbb{Q} , the natural and rational numbers and they did have such closure properties and, with the latter, inverses. But now our set LF[x] consists of functions, a more abstract idea than numbers. The equivalent of the multiplicative identity, the one, 1 of \mathbb{N} and \mathbb{Q} is now x, the identity function in LF[x]. The binary operations on sets of numbers, the arithmetic operations of addition, subtraction, multiplication, division are now reduced to just the operation of composition. Composition is associative, but it is not commutative (you saw examples of this in your algebra class), and distribution (using two operations) makes no sense with composition. So in a way groups are easy objects – just one operation, composition.

Applied

You may have done a section of your algebra two book involving variation problems; see [1], Section 3.7. The set of functions LF[x] has a subset that consists of direct variation functions, things of the form y = kx. This will be a subgroup of LF[x], call it DV[x], as in direct variation linear functions; it has by itself the properties of a group. Unlike LF[x], it is commutative (or Abelian): $k_1(k_2x) = k_2(k_1x) = k_1k_2x$. It is a theorem of group theory that one can check for a subgroup by confirming an element of the subgroup's inverse is in the subgroup. It is one line: if $f(x) = kx \in DV[x]$,

$$f^{-1}(x) = \frac{1}{k}x \in DV[x] \text{ and } f(f^{-1}(x)) = k\frac{1}{k}(x) = x.$$

Knowing that inverses exists in DV[x] one knows that the reverse problem of finding an x given a y value can be solved. Variation problems are big in physics. The function F = ma says that acceleration varies directly with F. The universal law of gravitation is a variation problem, albeit involving joint and inverse variation; $e = mc^2$ is a variation problem with a square variation. The general challenge of finding or constructing classes of functions that can model phenomena is a major theme of applied (and pure) math.

All of this points to real analysis. Fourier analysis uses a lot of trigonometric functions to expand what can be modeled. As it turns out polynomials, of which linear functions are an example, are potent, but limited. One needs infinite series, a thing studied first in calculus, to broaden the modeling range to include more complex phenomena of advanced physics and astrophysics. Trigonometric functions are themselves expressed with infinite series. Polynomials are approximations to infinite series. What is the set of functions (so models) that can be given as an infinite series using the trigonometric functions sin and cos?

With LF[x] one gets the easiest means of contemplating in the abstract such questions.

Research

Look up the evolution to the symbol $\mathscr{L}^2(\mu)$ in [3]. That is trace in the last chapter of the cited book the sequence of sets giving functions that ends with $\mathscr{L}^2(\mu)$.

General polynomial functions

Note that quadratics, like $f(x) = ax^2 + bx + c$ will not be closed under composition and will not have inverses. LF[x] is a group under composition because it is closed, with an identity, is associative, and its elements have inverses: CIA I. Repeating: groups are a generalization of the integers under addition and the rationals under multiplication. A class of functions are now included within this algebraic structure.

Solving polynomials

We can solve x + 3 = 5 in the integers and we can solve 3x - 5 = 7 in the rational numbers; these involve linear functions, polynomials of degree one. Which polynomials can we solve? We can solve the quadratics with integer coefficients with complex numbers. This is the purport of the quadratic formula. Having contemplated the set LF[x], how can we frame the general question of solving a polynomial. We need to specify the coefficients allowed, what set they are from, as well as where we will look for roots. In the case of the linear function 3x - 5 = 0 the coefficients are from the integers and the roots are from the rationals. For the quadratic the coefficients can be from the integers, but the roots, for some quadratics, can only be found in the complex numbers. We have to expand the coefficient set way up to get a quadratic's roots. This is a general theme; coefficients are in one space and roots tend to be in a superset of that space.

What about the details of getting to a root for any polynomial? As we see with the linear and quadratic cases we insist that a finite number of steps involving algebraic manipulations are the means. There are three sets involved in this pattern: polys = 0 through *means* yields *roots*. The *means*

are a finite number of steps. How can we specify all the possible steps we allow? This is a major theme of abstract algebra.

The fast answer is to first note that a field, you've seen fields $\mathbb{Q}, \mathbb{R}, \mathbb{C}$, has arithmetic operations we allow. Next a permutation of a finite set of these operations, if it gives all roots, is what is sought. Witness the algebraic steps necessary to solve ax + b = 0 and $ax^2 + bx + c = 0$ use field operations. The number of steps and the complexity of the operations goes up with the increasing degree, so we might expect that the problem gets harder and harder. Actually, there is a formula for the cubic, quartic cases, but not the general quintic (degree 5) case. One can get a real feel for how hard the problem gets by reverse engineering the situation from the solution back. Consider a factored polynomial and its relationship to its coefficients:

$$p(x) = (x - r_1)(x - r_2) \dots (x - r_n) =$$
(1)
$$x^n - \sum [1]x^{n-1} + \sum [2]x^{n-2} - \dots \pm r_1 r_2 \dots r_n,$$

where [j] means products of roots taken j at a time. Try this with n = 2 and 3 to convince yourself of the general pattern. So to go from the coefficients back to the roots involves more and more work; the number of coefficients goes up and the number of sums and products goes up too. One might imagine that at some point it will be impossible to decode coefficients and get all the roots. All roots are found when we have the factored form (1).

We've considered LF[x] and its subgroup DV[x]. These are both infinite groups. Part of the puzzle of proving that G5[x], greater than 5th degree polynomials with integer coefficients can't in general be solved requires learning about finite groups – permutations. You most likely studied permutations sometime in high school within a chapter on probability [1], Section 11.6, so there is a natural door into making permutations functions.

Permutations as functions

Are there finite groups which consist of functions? The functions would need to be one-to-one to insure that they have inverses. This is a limitation for real valued functions defined on \mathbb{R} . But remember those little diagrams giving examples of functions between two sets; see [1], pages 200-1. These can be one-to-one and onto easily and we can compose with them. They will have inverses and as with all functions, with the right domains and ranges, be associative; there is hope.

Spelling corrections

Consider the misspelled version of 'the', say 'eht.' The function 321(eht) corrects it: it moves the letter in the third position of its argument to the first, the letter in the second position stays in the second position, and the letter in the first position goes to the third position. Thus 321(eht) = the. What's the inverse of 321. Well what gives 123, the identity function. Well 321(321) = 123. Permutations can be thought of as functions on strings of a given length; you rearrange or permute the letters making up the string; in the case of correcting a spelling typo the permutation gives gives the correct spelling. Table 1 gives the permutation of three objects – the objects t, h, and e. We generate all the typos for 'the.'

123(the)	the
132(the)	teh
213(the)	hte
231(the)	hte
312(the)	eth
321(the)	eht

Table 1: The 3!=6 permutations of three objects considered as functions.

123(123)	123	same
132(123)	132	flip last two f_1
213(123)	213	flip first two f_3
231(123)	231	conveyor belt 1 r_1
312(123)	312	conveyor belt 2 r_2
321(123)	321	flip outer f_2

Table 2: The flip function subscript gives which to hold constant. 'r' stands for rotate forward and wrap around to back.

In Table 2 we replace 'the' with '123' and give a phrase that guides the function. In combination we can speak the corrections. So when confronted with 'teh' we wish to flip the last two for 'the'; 'eth' needs a conveyor belt 1 for 'the'. We could tell an editor for the last to transpose the first two letters and then transpose the resulting last two for 'teh' first and then 'the.' Are all

permutations expressible as sequences of transposition? Yes. That's in the group theory chapter of Herstein's classic Topics in Algebra [2].

It is easy to see that a permutation of a permutation is a permutation. These functions are closed under composition. A flip of a flip is back to 123 and three rotations, 123 to 231 to 312 to 123, yields 123 as well. Each permutation function, henceforth just permutation, has an inverse. One can see this group quickly by labeling a triangle's vertices with 1, 2, and 3 – label vertices from southwest 1 and going counter-clockwise with 2 and 3. Flip vertex labels and rotate them and you get the three flips and rotations given in Table 2. Note the flips are their own inverses and form a subgroup of order 2. The rotations also this way, closed and with inverses, so that's another subgroup of order 3. The order of 3 subgroups is 2 and one is 3. Is it true that subgroups are divisors of the grand group? Yes. This is a named theorem in Herstein, Lagrange's theorem. Given a prime divides the order of a group (the number in its set), is there necessarily a subgroup of that order? Yes. Subgroups of all possible divisor orders? No. Finite groups are as fascinating as prime numbers, maybe more so! They model many things.

Permutation functions on a set of objects is a group: they are closed, have an identity, are associative (CIA) and also each has an inverse (I). We've seen five instances of groups: LF[x], DV[x], typo corrections, and call them rigid triangle transformations and permutation groups; the last three all seem identical – they are all permutations. Cayley's theorem says that all finite groups are subgroups of permutation groups. You can see why; permutations give all possible functions, so naturally any set of functions that stays closed will have to be in these big sets of functions.

Permutations and symmetric functions

The relationship between the factored form of a polynomial and its coefficients as given by (1) is telling. If we define a function using the roots of a polynomial, say

$$f(r_1, r_2, \dots, r_n) = p(x)$$
 see (1)

then we suspect that all permutations of the arguments gives the same coefficient form of p(x). This is true the connection between the roots and the coefficients are given by what are known as the elementary symmetric functions. Symmetric functions are those that add up the same thing when the arguments to the functions are permuted. One can see this immediately in the easiest case:

$$f(r_1, r_2) = x^2 - (r_1 + r_2)x + r_1r_2 = f(r_2, r_1) = x^2 - (r_2 + r_1)x + r_2r_1,$$

just using additive and multiplicative commutativity. As permutation functions are groups, it is conceivable that we can prove which polynomials are solvable by understanding permutation groups. As roots are combined to form coefficients and every polynomial has roots is there a way to find a group associated with the roots that have the property that matches solvability; we'd like to get a group associated with a polynomial that is solvable what ever that might mean when the polynomial is solvable.

Language

Hopefully at this point you are becoming more and more intrigued by groups. But wait there's more. You should sense that we can have permutation groups of more with more than just three elements – but any finite number. We can make regular polygons and rotate and flip them to generate groups. The natural numbers, the integers, the reals, and the complex numbers all have groups with addition for one, sometimes multiplication. Consider roots of unity as given by roots of $z^n - 1 = 0$. The roots will be points in the complex plane and if you multiple them, using complex multiplication, they rotate and go to another point; this is a cyclic group, like the subgroup of rotations of regular polygons – the triangle we mentioned above. There are lots of types of groups generated by disparate phenomena. How on earth can we get all possible groups of a certain order? That's an intriguing puzzle.

There is a theorem of group theory that gives an answer for the subclass of groups, the Abelian groups. A quick way to understand the idea is to consider a product of cyclic groups. Say A, B, and C are three cyclic groups of order a, b, and c. We can view this situation with time and status frames within the context of a sentence, a thing of language. 'The cat is big' has three parts a subject, a verb, and an adjective; each particular word can, dependent on the situation be located in time. Time itself is cyclic, so each idea is within a circle giving its status in various senses. All finite Abelian groups are isomorphic to products of cyclic groups [2].

Abstract algebra

If you are about to take a course in abstract algebra you should take linear algebra first. The grand theme of abstract algebra is well anticipated by linear algebra. Linear algebra itself is well anticipated by solving linear equations taught in high school algebra. Blitzer has a chapters on solving systems of linear (and non-linear) equations and matrices [1], Chapters 8 and 9. Linear algebra broadens these elementary algebra themes by considering inverses of a matrix as well as how matrices give transformations. Transformations themselves allow for proving that two *spaces* are isomorphic. This theme of proving two spaces, think groups of one type and another, isomorphic is really about showing they are the same. So Cayley's theorem says all finite groups are isomorphic (the same) as a subgroup of some permutation group. Linear algebra is more concrete than group theory. Study it first.

Abstract algebra has as its grand goal proving that general fifth and greater degree polynomials over the rationals (having rational coefficients) are not solvable by root taking. The fundamental theorem algebra (mentioned not proven in Blitzer) says all roots occur in \mathbb{C} . Root taking means all the arithmetic operations you are used to (addition, subtraction, multiplication, and division), plus power and root taking. There is no quadratic formula for polynomials over degree four. The proof of this requires groups, rings, fields, and vector spaces. It is a hard slog.

References

- [1] R. Blitzer, *Algebra and Trigonometry*, 4th ed., Upper Saddle, NJ, 2010.
- [2] I. N. Herstein, *Topics in Algebra*, 2nd ed., John Wiley, New York, 1975.
- [3] W. Rudin, *Principles of Mathematical Analysis*, 3rd ed., McGraw-Hill, New York, 1976.