

Exact Smooth Solution for General Form of Navier-Stokes Equations

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ABSTRACT

In Wikipedia “Navier-Stokes existence and smoothness”, we discover the exact smooth solution for general form of Navier-Stokes Equations by Newton potential and time-function.

PACS Number:04,04.90.+e

Key words:General form of Navier-Stokes Equations;

Exact smooth solutions;

Newton potential;

Time function

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1. Introduction

We discover the exact solution for general form of the Navier-Stokes equation by Newton potential and time function in Wikipedia “Navier-Stokes existence and smoothness”.

According Wikipedia’s general form of Navier-Stokes Equations(3-dimensional),

$$\frac{\partial \vec{v}}{\partial t} + (\vec{v} \cdot \nabla) \vec{v} = -\frac{1}{\rho} \nabla \rho + \nu \Delta \vec{v} + \vec{f}(\vec{x}, t) \quad (1)$$

$$\nabla \cdot \vec{v} = 0 \quad (2)$$

Where $\nu > 0$ is the kinematic viscosity, $\vec{f}(\vec{x}, t) = (f_x, f_y, f_z)$ is the external volumetric force,

∇ is the gradient operator and $\Delta = \nabla^2$ is the Laplacian operator,

Coordinate: (x, y, z) , Time: t , Pressure: p , Density: ρ

If the velocity $\vec{v} = \vec{v}(\vec{x}, t) = (u, v, w)$, Eq(1),Eq(2) are

$$\frac{\partial u}{\partial t} + (u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z})u = -\frac{1}{\rho} \frac{\partial \rho}{\partial x} + \nu (\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2})u + f_x \quad (3)$$

$$\frac{\partial v}{\partial t} + (u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z})v = -\frac{1}{\rho} \frac{\partial \rho}{\partial y} + \nu (\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2})v + f_y \quad (4)$$

$$\frac{\partial w}{\partial t} + (u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z})w = -\frac{1}{\rho} \frac{\partial \rho}{\partial z} + \nu (\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2})w + f_z \quad (5)$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0 \quad (6)$$

2. Exact Solution for General Form of 3-Dimensional Navier-Stokes Equations (Include time) in Wikipedia

For we solve equations, we use Newton potential and time function. If we think the solution of Laplace equation, if we differentiate the function g k-times by the coordinate x, y, z , it is

$$(\partial_x)^k g, (\partial_y)^k g, (\partial_z)^k g.$$

$$\text{Newton potential } g = \frac{1}{r}, g^{(k)}_x = (\partial_x)^k g, g^{(k)}_y = (\partial_y)^k g, g^{(k)}_z = (\partial_z)^k g$$

$$\vec{v} = \vec{v}(\vec{x}, t) = (u, v, w) = C_1 f(t) \nabla g^{(k)}_x \text{ or}$$

$$\vec{v} = \vec{v}(\vec{x}, t) = (u, v, w) = C_1 f(t) \nabla g^{(k)}_y \text{ or } \vec{v} = \vec{v}(\vec{x}, t) = (u, v, w) = C_1 f(t) \nabla g^{(k)}_z \quad (7)$$

In this time, we treat only $\vec{v} = \vec{v}(\vec{x}, t) = (u, v, w) = C_1 f(t) \nabla g^{(k)}_x$

$$u = C_1 f(t) \partial_x g^{(k)}_x, v = C_1 f(t) \partial_y g^{(k)}_x, w = C_1 f(t) \partial_z g^{(k)}_x, \quad (8)$$

$$\begin{aligned}\nabla^{(k)} \cdot \vec{\nabla} g &= \nabla^{(k-1)} \vec{\nabla} \cdot (g'_x i + g'_y j + g'_z k) = \nabla^{(k-1)} \nabla^2 \left(\frac{1}{r} \right) = \nabla^{(k-1)} (0) = 0 \\ &= \vec{\nabla} \cdot \vec{\nabla} (\nabla^{(k-1)} g) = \vec{\nabla} \cdot \vec{\nabla} (g^{(k-1)}_x) = \vec{\nabla} \cdot \vec{g}^{(k)} = 0\end{aligned}\quad (9)$$

Hence, according to Eq(9),

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = C_1 f(t) \vec{\nabla} \cdot \vec{g}^{(k)} = 0 \quad (10)$$

Hence, Eq(8) satisfy the continuity equation-Eq(6)

In this case, if we solve left term of Eq(1), the left term of Eq(3) is

$$\begin{aligned}&\frac{\partial u}{\partial t} + \left(u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \right) u \\ &= C_1 \partial_x g^{(k)}_x \dot{f}(t) + f^2(t) C_1^2 [\partial_x g^{(k)}_x \partial_x \partial_x g^{(k)}_x + \partial_y g^{(k)}_x \partial_y \partial_x g^{(k)}_x + \partial_z g^{(k)}_x \partial_z \partial_x g^{(k)}_x] \\ &\quad (11)\end{aligned}$$

So, left terms of Eq(4), Eq(5) are

$$\begin{aligned}&\frac{\partial v}{\partial t} + \left(u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \right) v \\ &= C_1 \partial_y g^{(k)}_x \dot{f}(t) + f^2(t) C_1^2 [\partial_x g^{(k)}_x \partial_x \partial_y g^{(k)}_x + \partial_y g^{(k)}_y \partial_y \partial_y g^{(k)}_x + \partial_z g^{(k)}_x \partial_z \partial_y g^{(k)}_x] \\ &\quad (12)\end{aligned}$$

$$\begin{aligned}&\frac{\partial w}{\partial t} + \left(u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \right) w \\ &= C_1 \partial_z g^{(k)}_x \dot{f}(t) + f^2(t) C_1^2 [\partial_x g^{(k)}_x \partial_x \partial_z g^{(k)}_x + \partial_y g^{(k)}_x \partial_y \partial_z g^{(k)}_x + \partial_z g^{(k)}_x \partial_z \partial_z g^{(k)}_x] \\ &\quad (13)\end{aligned}$$

In this time, if $f(t)$ is,

$$\frac{1}{[f(t)]^2} \frac{d}{dt} [f(t)] = 1 \rightarrow f(t) = \frac{1}{C-t}, \quad C < 0 \text{ is constant} \quad (14)$$

Therefore, left terms of Eq(3),Eq(4),Eq(5) are

$$\begin{aligned}&\frac{\partial u}{\partial t} + \left(u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \right) u \\ &= C_1 \partial_x g^{(k)}_x \frac{1}{(C-t)^2} \\ &+ \frac{1}{(C-t)^2} C_1^2 [\partial_x g^{(k)}_x \partial_x \partial_x g^{(k)}_x + \partial_y g^{(k)}_x \partial_y \partial_x g^{(k)}_x + \partial_z g^{(k)}_x \partial_z \partial_x g^{(k)}_x] \quad (15) \\ &\frac{\partial v}{\partial t} + \left(u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \right) v\end{aligned}$$

$$\begin{aligned}
&= C_1 \partial_y g^{(k)} \frac{1}{(C-t)^2} \\
&+ \frac{1}{(C-t)^2} C_1^2 [\partial_x g^{(k)} \partial_x \partial_y g^{(k)} + \partial_y g^{(k)} \partial_y \partial_x g^{(k)} + \partial_z g^{(k)} \partial_z \partial_y g^{(k)}] \quad (16)
\end{aligned}$$

$$\begin{aligned}
&\frac{\partial W}{\partial t} + (u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z}) W \\
&= C_1 \partial_z g^{(k)} \frac{1}{(C-t)^2} \\
&+ \frac{1}{(C-t)^2} C_1^2 [\partial_x g^{(k)} \partial_x \partial_z g^{(k)} + \partial_y g^{(k)} \partial_y \partial_z g^{(k)} + \partial_z g^{(k)} \partial_z \partial_z g^{(k)}] \quad (17)
\end{aligned}$$

In this case, if we solve right term of Eq(1), the right term of Eq(3) is

$$-\frac{1}{\rho_0} \frac{\partial}{\partial x} \rho + \nu (\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}) u + f_x, \quad \nu > 0, \quad \rho = \rho_0 \quad (18)$$

In this time, according to Eq(9),

$$\nabla^2 u = C_1 \frac{1}{(C-t)} \nabla^2 \partial_x g^{(k)} = C_1 \frac{1}{(C-t)} \partial_x \nabla^2 g^{(k)} = 0 \quad (19)$$

So,

$$\nabla^2 v = \nabla^2 w = 0 \quad (20)$$

Hence, right terms of Eq(3),Eq(4),Eq(5) are

$$-\frac{1}{\rho_0} \frac{\partial}{\partial x} \rho + \nu (\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}) u + f_x = -\frac{1}{\rho_0} \frac{\partial \rho}{\partial x} + f_x \quad (21)$$

$$-\frac{1}{\rho_0} \frac{\partial}{\partial y} \rho + \nu (\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}) v + f_y = -\frac{1}{\rho_0} \frac{\partial \rho}{\partial y} + f_y \quad (22)$$

$$-\frac{1}{\rho_0} \frac{\partial}{\partial z} \rho + \nu (\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}) w + f_z = -\frac{1}{\rho_0} \frac{\partial \rho}{\partial z} + f_z \quad (23)$$

In this time, if $\vec{f}(\vec{x}, t) = 0$ is for smooth function $\rho(\vec{x}, t)$. Hence, if we solve Eq(1),

$$\begin{aligned}
&C_1 \partial_x g^{(k)} \frac{1}{(C-t)^2} \\
&+ \frac{1}{(C-t)^2} C_1^2 [\partial_x g^{(k)} \partial_x \partial_x g^{(k)} + \partial_y g^{(k)} \partial_y \partial_x g^{(k)} + \partial_z g^{(k)} \partial_z \partial_x g^{(k)}] \\
&= -\frac{1}{\rho_0} \frac{\partial \rho}{\partial x} \quad (24)
\end{aligned}$$

$$C_1 \partial_x g^{(k)} \frac{1}{(C-t)^2}$$

$$\begin{aligned}
& + \frac{1}{(C^1-t)^2} C_1^2 [\partial_x g^{(k)} \partial_x \partial_y g^{(k)} + \partial_y g^{(k)} \partial_y \partial_x g^{(k)} + \partial_z g^{(k)} \partial_z \partial_y g^{(k)}] \\
& = -\frac{1}{\rho_0} \frac{\partial \rho}{\partial y}
\end{aligned} \tag{25}$$

$$\begin{aligned}
& C_1 \partial_z g^{(k)} \frac{1}{(C^1-t)^2} \\
& + \frac{1}{(C^1-t)^2} C_1^2 [\partial_x g^{(k)} \partial_x \partial_z g^{(k)} + \partial_y g^{(k)} \partial_y \partial_z g^{(k)} + \partial_z g^{(k)} \partial_z \partial_z g^{(k)}] \\
& = -\frac{1}{\rho_0} \frac{\partial \rho}{\partial z}
\end{aligned} \tag{26}$$

Hence,

$$\rho(\vec{x}, t) = -\rho_0 C_1 g^{(k)} \frac{1}{(C^1-t)^2} - \frac{1}{2} \rho_0 C_1^2 [(\partial_x g^{(k)})^2 + (\partial_y g^{(k)})^2 + (\partial_z g^{(k)})^2] \frac{1}{(C^1-t)^2} \tag{27}$$

3. Hypotheses and Growth Conditions(Smoothness)

The initial condition $\vec{V}_0(x) = C_1(\partial_x g^{(k)}, \partial_y g^{(k)}, \partial_z g^{(k)}) \frac{1}{C} = C_2 \vec{\nabla} g^{(k)}$ is, for every multi-index α and any $K > 0$, there exist a constant $C = C(\alpha, K) > 0$ such that

$$|\partial^\alpha \vec{V}_0(x)| = |C_2 \partial^{\alpha_1 \dots \alpha_n} \partial_x (\vec{\nabla} g^{(k)})| < \frac{C}{(1+|x|)^K}, \text{ for all } x \in R^3,$$

$$\partial^\alpha = \partial^{\alpha_1 \alpha_2 \dots \alpha_n}, \tag{28}$$

The external force $\vec{f}(x, t) = 0$ is

$$|\partial^\alpha \vec{f}(x)| = 0 \leq \frac{C}{(1+|x|+t)^K}, \text{ for all } (x, t) \in R^3 \times [0, \infty) \tag{29}$$

More precisely, the following assumptions are made:

$$1. \vec{v}(x, t) = C_1(\partial_x g^{(k)}, \partial_y g^{(k)}, \partial_z g^{(k)}) \frac{1}{(C^1-t)} \in [C^\infty(R^3 \times [0, \infty))]^3,$$

$$C^1 < 0, \tag{30}$$

Hence,

$$\begin{aligned}
\rho(\vec{x}, t) & = -\rho_0 C_1 g^{(k)} \frac{1}{(C^1-t)^2} - \frac{1}{2} \rho_0 C_1^2 [(\partial_x g^{(k)})^2 + (\partial_y g^{(k)})^2 + (\partial_z g^{(k)})^2] \frac{1}{(C^1-t)^2} \\
& \in [C^\infty(R^3 \times [0, \infty))]^3, C^1 < 0
\end{aligned} \tag{31}$$

2. There exists a constant $E \in (0, \infty)$ such that

$$\vec{v}(x, t) = C_1(\partial_x g^{(k)}_x, \partial_y g^{(k)}_x, \partial_z g^{(k)}_x) \frac{1}{(C-t)}$$

$$\int_{\mathbb{R}^3} |\vec{v}(x, t)|^2 dx = \int_{\mathbb{R}^3} C_1^2 \frac{1}{(C-t)^2} [(\partial_x g^{(k)}_x)^2 + (\partial_y g^{(k)}_x)^2 + (\partial_z g^{(k)}_x)^2] dx$$

$$< E, \text{ for all } t \geq 0. \text{ if } C < 0 \quad (32)$$

*The Millennium Prize Conjectures in the Whole Space

(A) Existence and smoothness of the Navier-Stokes solution in \mathbb{R}^3 .

Let $\vec{f}(x, t) \equiv 0$. For any initial condition $\vec{v}_0(x)$ satisfying the above hypotheses there exist smooth and globally defined solutions to the Navier-Stokes equations, i.e. there is a velocity vector $\vec{v}(x, t)$ and a pressure $p(x, t)$ satisfying conditions 1 and 2 above.

4. Conclusion

Therefore, the exact smooth solution of Navier-Stokes equations in Wikipedia(3-dimensional) is

Density: $\rho = \rho_0$,

Velocity Components: $\vec{v}(x, t) = C_1(\partial_x g^{(k)}_x, \partial_y g^{(k)}_x, \partial_z g^{(k)}_x) \frac{1}{(C-t)}, C < 0$

The external volumetric force: $\vec{f}(\vec{x}, t) = 0$

Pressure:

$$p(\vec{x}, t) = -\rho_0 C_1 g^{(k)}_x \frac{1}{(C-t)^2} - \frac{1}{2} \rho_0 C_1^2 [(\partial_x g^{(k)}_x)^2 + (\partial_y g^{(k)}_x)^2 + (\partial_z g^{(k)}_x)^2] \frac{1}{(C-t)^2}$$

$$C < 0$$

References

[1]Wikipedia," Navier-Stokes existence and smoothness"