

Laws of General Solutions of Partial Differential Equations

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Abstract

In this paper, four kinds of Z Transformations are used to get many laws of general solutions of m th-order linear and nonlinear partial differential equations with n variables. Some general solutions of first-order linear partial differential equations, which cannot be obtained by using the characteristic equation method, can be solved by the Z Transformations. By comparing, we find that the general solutions of some first-order partial differential equations got by the characteristic equation method are not complete.

keywords:

Z Transformations; banal PDEs; non-banal PDEs; general solutions; the characteristic equation method.

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Introduction

In recent years, some numerical methods have been developed to solve linear partial differential equations (PDEs), such as Finite integration method [1, 2], Bernoulli matrix method [3], Chebyshev matrix method [4] and so on, the existence [5], uniqueness [6, 7] and stability [8] of their solutions are also the focus of research.

In [9], we used new analytical methods to preliminarily study some laws of general solutions of the m th-order linear PDEs with n variables. In this paper, we will use four kinds of Z Transforms to further study the m th-order linear and nonlinear PDEs with n variables.

1. New principles and methods

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In order to obtain the general solutions of PDEs in various orthogonal coordinate systems, we proposed the concepts and laws of the independent variable transformational equations (IVTEs) and the dependent variable transformational equations (DVTEs) in [9]. About the IVTEs, there is an important new theorem:

Theorem 1. *In the domain D , ($D \subset \mathbb{R}^n$), if $G(y_1, y_2, \dots, y_n, u, u_{y_1}, u_{y_2}, \dots, u_{y_n}, u_{y_1 y_2}, u_{y_1 y_3}, \dots) = 0$ is an arbitrary independent variable transformational equation of a m th-order PDE $F(x_1, x_2, \dots, x_n, u, u_{x_1}, u_{x_2}, \dots, u_{x_n}, u_{x_1 x_2}, u_{x_1 x_3}, \dots) = 0$, so*

1.If $F=0$ is a linear PDE, then $G=0$ is an m th-order linear PDE.

2.If $F=0$ is a nonlinear PDE, then $G=0$ is an m th-order nonlinear PDE.

Proof. Since

$$u_{x_i} = \sum_{p=1}^n u_{y_p} \frac{\partial y_p}{\partial x_i}, \quad (1)$$

$$u_{x_i x_j} = \sum_{p=1}^n u_{y_p} \frac{\partial^2 y_p}{\partial x_i \partial x_j} + \sum_{p=1}^n \sum_{q=1}^n u_{y_p y_q} \frac{\partial y_p}{\partial x_i} \frac{\partial y_q}{\partial x_j}, \quad (2)$$

$$\begin{aligned} u_{x_i x_j x_k} &= \sum_{p=1}^n u_{y_p} \frac{\partial^3 y_p}{\partial x_i \partial x_j \partial x_k} + \sum_{p=1}^n \sum_{q=1}^n u_{y_p y_q} \left(\frac{\partial^2 y_p}{\partial x_i \partial x_j} \frac{\partial y_q}{\partial x_k} + \frac{\partial^2 y_p}{\partial x_i \partial x_k} \frac{\partial y_q}{\partial x_j} + \frac{\partial y_p}{\partial x_i} \frac{\partial^2 y_q}{\partial x_j \partial x_k} \right) \\ &\quad + \sum_{p=1}^n \sum_{q=1}^n \sum_{r=1}^n u_{y_p y_q y_r} \frac{\partial y_p}{\partial x_i} \frac{\partial y_q}{\partial x_j} \frac{\partial y_r}{\partial x_k}, \end{aligned} \quad (3)$$

...

where $i, j, k, p, q, r \in \{1, 2, \dots, n\}$, namely $u_{x_i}, u_{x_i x_j}, u_{x_i x_j x_k}, \dots$ are linear relationship with $u_{y_p}, u_{y_p y_q}, u_{y_p y_q y_r}, \dots$, and the highest order of the partial derivatives on both sides of the equations are equal. Therefore each linear term in $F = 0$ is transformed into a new linear term; every nonlinear term in $F = 0$ is transformed into a new nonlinear term; and the highest order of the partial derivative of the dependent variable of each term is constant. So the independent variable transformation not only does not change the linearity or non-linearity of the original PDEs, but also does not change their order. Then Theorem 1 is proved. \square

For the DVTEs, the specific l th-order transformation $v = h(x_1, \dots, x_n, u, u_{x_1}, \dots, u_{x_n}, u_{x_1 x_2}, \dots)$ may be linear or non-linear. For the linear transformation, each linear term of an m th-order linear PDE is transformed into a new linear term, so a $(l+m)$ th-order linear PDE will be transformed. For an m th-order nonlinear PDE, each nonlinear term will transform a new nonlinear term, normally it will be transformed a $(l+m)$ th-order nonlinear PDE.

For the nonlinear transformation, an m th-order linear PDE is usually transformed into a $(l+m)$ th-order nonlinear PDE, an m th-order nonlinear PDE may be transformed into a $(l+m)$ th-order nonlinear PDE or a $(l+m)$ th-order linear PDE.

In \mathbb{R}^n whose independent variables are x_1, x_2, \dots, x_n , if the solution of a PDE contains an arbitrary function, the number of independent variables of the arbitrary function is generally not equal to n , unless the essence of the PDE is $0 = 0$, such as

$$u_{x_i} - u_{x_i} = 0. \quad (4)$$

It is obvious that the general solution of Eq. (4) can be an arbitrary first differentiable function with n variables, but this PDE has no practical meaning. We call a PDE whose essence is $0 = 0$ a **banal PDE**, and a PDE whose nature is not $0 = 0$ a **non-banal PDE**.

For non-banal PDEs, we propose a conjecture:

Conjecture 1. *In $\mathbb{R}^n, (n \geq 2)$, if the solution of a non-banal PDE contains an arbitrary function, the number l of independent variables of the arbitrary function satisfies $1 \leq l \leq n - 1$.*

In [10], we presented $Z_1 - Z_3$ transformations with the following contents.

Z_1 Transformation. *In the domain $D, (D \subset \mathbb{R}^n)$, any established m th-order PDE with n space variables $F(x_1, \dots, x_n, u, u_{x_1}, \dots, u_{x_n}, u_{x_1x_2}, \dots) = 0$, set $y_i = y_i(x_1, \dots, x_n)$ and $u = f(y_1, \dots, y_l)$ are both undetermined m th-differentiable functions ($u, y_i \in C^m(D), 1 \leq i \leq l \leq n$), y_1, y_2, \dots, y_l are independent of each other, then substitute $u = f(y_1, \dots, y_l)$ and its partial derivatives into $F = 0$,*

1. *In case of working out $y_i = y_i(x_1, \dots, x_n)$ and $f(y_1, \dots, y_l)$, then $u = f(y_1, \dots, y_l)$ is the solution of $F = 0$,*
2. *In case of dividing out $u = f(y_1, \dots, y_l)$ and its partial derivative, also working out $y_i = y_i(x_1, \dots, x_n)$, then $u = f(y_1, \dots, y_l)$ is the solution of $F = 0$, and f is an arbitrary m th-differentiable function,*
3. *In case of dividing out $u = f(y_1, \dots, y_l)$ and its partial derivative, also getting $k = 0$, but in fact $k \neq 0$, then $u = f(y_1, \dots, y_l)$ is not the solution of $F = 0$, and f is an arbitrary m th-differentiable function.*

Z_2 Transformation. *In the domain $D, (D \subset \mathbb{R}^n)$, any established m th-order PDE with n space variables $F(x_1, \dots, x_n, u, u_{x_1}, \dots, u_{x_n}, u_{x_1x_2}, \dots) = 0$, set $y_i = y_i(x_1, \dots, x_n)$ known and $u = f(y_1, \dots, y_l)$ undetermined ($u, y_i \in C^m(D), 1 \leq i \leq l \leq n$), y_1, y_2, \dots, y_l are independent of each other, then substitute $u = f(y_1, \dots, y_l)$ and its partial derivatives into $F = 0$*

1. *In case of working out $f(y_1, \dots, y_l)$, then $u = f(y_1, \dots, y_l)$ is the solution of $F = 0$,*
2. *In case of dividing out $u = f(y_1, \dots, y_l)$ and its partial derivative, also getting $0 = 0$, then $u = f(y_1, \dots, y_l)$ is the solution of $F = 0$, and f is an arbitrary m th-differentiable function,*
3. *In case of dividing out $u = f(y_1, \dots, y_l)$ and its partial derivative, also getting $k = 0$, but in fact $k \neq 0$, then $u = f(y_1, \dots, y_l)$ is not the solution of $F = 0$, and f is an arbitrary m th-differentiable function.*

Z_3 Transformation. *In the domain $D, (D \subset \mathbb{R}^n)$, any established m th-order PDE with n space variables $F(x_1, \dots, x_n, u, u_{x_1}, \dots, u_{x_n}, u_{x_1x_2}, \dots) = 0$, setting $g(x_1, \dots, x_n), h(y_1, \dots, y_l)$ and $y_i = y_i(x_1, \dots, x_n)$ are all undetermined function, y_1, y_2, \dots, y_l are independent of each other, ($g, h, y_i \in C^m(D), 1 \leq i \leq l \leq n$), then substitute $u = gh(y_1, \dots, y_l)$ and its partial derivatives into $F = 0$,*

1. *In case of working out h, g and y_i , then $u = gh(y_1, \dots, y_l)$ is the solution of $F = 0$,*
2. *In case of dividing out h and its partial derivative, also working out g and y_i , then $u = gh(y_1, \dots, y_l)$ is the solution of $F = 0$, and h is an arbitrary m th-differentiable function,*
3. *In case of getting $k = 0$, but in fact $k \neq 0$, then $u = gh(y_1, \dots, y_l)$ is not the solution of $F = 0$.*

In order to obtain general solutions or exact solutions of some PDEs, we further propose Z_4 transformation.

Z_4 Transformation. *In the domain $D, (D \subset \mathbb{R}^n)$, any established m th-order PDE with n space variables $F(x_1, \dots, x_n, u, u_{x_1}, \dots, u_{x_n}, u_{x_1x_2}, \dots) = 0$, set $y_i = y_i(x_1, \dots, x_k, u)$ and $f(y_1, y_2, \dots, y_k, x_{k+1}, x_{k+2}, \dots, x_n)$ are both undetermined m th-differentiable functions ($f, y_i \in C^m(D), 1 \leq i \leq k \leq n$), y_1, y_2, \dots, y_k are independent of each other, and set $f(y_1, y_2, \dots, y_k, x_{k+1}, x_{k+2}, \dots, x_n) = 0$, then substitute $u, u_{x_1}, \dots, u_{x_n}, u_{x_1x_2}, \dots$ into $F = 0$*

1. In case of working out $y_i = y_i(x_1, \dots, x_k, u)$ and $f(y_1, y_2, \dots, y_k, x_{k+1}, x_{k+2}, \dots, x_n)$, then $f(y_1, y_2, \dots, y_k, x_{k+1}, x_{k+2}, \dots, x_n) = 0$ is the solution of $F = 0$,
2. In case of dividing out all the partial derivatives of $f(y_1, y_2, \dots, y_k, x_{k+1}, x_{k+2}, \dots, x_n)$, also working out $y_i = y_i(x_1, \dots, x_k, u)$, then $f(y_1, y_2, \dots, y_k, x_{k+1}, x_{k+2}, \dots, x_n) = 0$ is the solution of $F = 0$, and f is an arbitrary m th-differentiable function,
3. In case of dividing out all the partial derivatives of $f(y_1, y_2, \dots, y_k, x_{k+1}, x_{k+2}, \dots, x_n)$, also getting $k = 0$, but in fact $k \neq 0$, then $f(y_1, y_2, \dots, y_k, x_{k+1}, x_{k+2}, \dots, x_n) = 0$ is not the solution of $F = 0$, and f is an arbitrary m th-differentiable function.

In Z_4 Transformation, $y_i = y_i(x_1, \dots, x_k, u)$ and $f(y_1, \dots, y_k, x_{k+1}, \dots, x_n)$ are both undetermined, $y_i(x_1, \dots, x_k, u)$ may be an unknown function completely or has a determinate form with unknown constants, the solution of $f(y_1, \dots, y_k, x_{k+1}, \dots, x_n)$ may be an arbitrary or a certain m th-differentiable function, the solution of y_i and f may not be single, etc., which are determined by the PDE and the specific solving process.

According to $y_i = y_i(x_1, \dots, x_k, u)$ and $f(y_1, \dots, y_k, x_{k+1}, \dots, x_n) = 0$, we get

$$f_{x_i} = \sum_{j=1}^l f_{y_j} (y_{j x_i} + y_{j u} u_{x_i}) = 0,$$

$$f_{x_i x_k} = \sum_{j=1}^l (f_{y_j} (y_{j x_i x_k} + y_{j x_i u} u_{x_k} + y_{j u} u_{x_i x_k} + y_{j u u} u_{x_i} u_{x_k} + y_{j u x_k} u_{x_i})$$

$$+ y_{j x_i} + y_{j u} u_{x_i}) \sum_{s=1}^l f_{y_j y_s} (y_{s x_k} + y_{s u} u_{x_k}) = 0$$

So

$$u_{x_i} = - \frac{\sum_{j=1}^l f_{y_j} y_{j x_i}}{\sum_{j=1}^l f_{y_j} y_{j u}}, \quad (5)$$

$$u_{x_i x_k} = \frac{1}{\sum_{j=1}^l f_{y_j} y_{j u}} \left(- \sum_{j=1}^l f_{y_j} y_{j x_i x_k} + \frac{\sum_{j=1}^l f_{y_j} y_{j x_k}}{\sum_{j=1}^l f_{y_j} y_{j u}} \sum_{j=1}^l f_{y_j} y_{j x_i u} \right.$$

$$- \frac{\sum_{j=1}^l f_{y_j} y_{j x_i}}{\sum_{j=1}^l f_{y_j} y_{j u}} \frac{\sum_{j=1}^l f_{y_j} y_{j x_k}}{\sum_{j=1}^l f_{y_j} y_{j u}} \sum_{j=1}^l f_{y_j} y_{j u u} + \frac{\sum_{j=1}^l f_{y_j} y_{j x_i}}{\sum_{j=1}^l f_{y_j} y_{j u}} \sum_{j=1}^l f_{y_j} y_{j u x_k}$$

$$\left. - \sum_{j=1}^l \left((y_{j x_i} - y_{j u} \frac{\sum_{j=1}^l f_{y_j} y_{j x_i}}{\sum_{j=1}^l f_{y_j} y_{j u}}) \sum_{s=1}^l f_{y_j y_s} y_{s x_k} \right. \right. \quad (6)$$

$$- \left. \frac{\sum_{j=1}^l f_{y_j} y_{j x_k}}{\sum_{j=1}^l f_{y_j} y_{j u}} (y_{j x_i} - y_{j u} \frac{\sum_{j=1}^l f_{y_j} y_{j x_i}}{\sum_{j=1}^l f_{y_j} y_{j u}}) \sum_{s=1}^l f_{y_j y_s} y_{s u} \right)$$

$$u_{x_i x_k} = \frac{1}{\sum_{j=1}^l f_{y_j} y_{j u}} \left(- \sum_{j=1}^l f_{y_j} y_{j x_i x_k} + 2 \frac{\sum_{j=1}^l f_{y_j} y_{j x_k}}{\sum_{j=1}^l f_{y_j} y_{j u}} \sum_{j=1}^l f_{y_j} y_{j x_i u} - \left(\frac{\sum_{j=1}^l f_{y_j} y_{j x_i}}{\sum_{j=1}^l f_{y_j} y_{j u}} \right)^2 \sum_{j=1}^l f_{y_j} y_{j u u} \right.$$

$$- \sum_{j=1}^l \left((y_{j x_i} - y_{j u} \frac{\sum_{j=1}^l f_{y_j} y_{j x_i}}{\sum_{j=1}^l f_{y_j} y_{j u}}) \sum_{s=1}^l f_{y_j y_s} y_{s x_i} \right.$$

$$\left. - \frac{\sum_{j=1}^l f_{y_j} y_{j x_i}}{\sum_{j=1}^l f_{y_j} y_{j u}} (y_{j x_i} - y_{j u} \frac{\sum_{j=1}^l f_{y_j} y_{j x_i}}{\sum_{j=1}^l f_{y_j} y_{j u}}) \sum_{s=1}^l f_{y_j y_s} y_{s u} \right) \quad (7)$$

By Eqs. (5-7), we can preliminarily judge that using Z_4 transformation to solve the first order PDEs may be convenient, and to solve the second order or greater than the second order PDEs may encounter difficulties.

2. General solutions' laws of partial differential equations with variable coefficients

2.1. General solutions' laws of linear PDEs with variable coefficients

In this section, if there is no special interpretation, the acquiescent independent variables of \mathbb{R}^n are x_1, x_2, \dots, x_n . $a_i = a_i(x_1, \dots, x_k)$, $a_{j_i} = a_{j_i}(x_1, \dots, x_k)$, $a_{i_1 i_2 \dots i_k} = a_{i_1 i_2 \dots i_k}(x_1, \dots, x_k)$, $b_i = b_i(x_1, \dots, x_k)$, and $b_{j_i} = b_{j_i}(x_1, \dots, x_k)$ are arbitrary known functions. $y_i = y_i(x_1, \dots, x_k)$, $D_{x_i} \equiv \frac{\partial}{\partial x_i}$. c_i and c_{j_i} are arbitrary constants, f and f_i are arbitrary smooth functions. ($i, j = 1, 2, \dots$), ($1 \leq k \leq n$)

Proposition 1. In \mathbb{R}^n , if the exact solutions $u = y_i(x_1, \dots, x_k)$ of Eq. (8), which are independent of each other, are known, ($1 \leq i \leq l \leq k-1$),

$$a_1 u_{x_1} + a_2 u_{x_2} + \dots + a_k u_{x_k} = 0, \quad (8)$$

then the general solution of Eq. (8) is

$$u = f(y_1, y_2, \dots, y_l, x_{k+1}, x_{k+2}, \dots, x_n). \quad (9)$$

Prove. By Z_1 Transformation, set $u(x_1, \dots, x_n) = f(y_1, y_2, \dots, y_l, x_{k+1}, x_{k+2}, \dots, x_n)$, then

$$\begin{aligned} & a_1 u_{x_1} + a_2 u_{x_2} + \dots + a_k u_{x_k} \\ &= a_1 (f_{y_1} y_{1x_1} + f_{y_2} y_{2x_1} + \dots + f_{y_l} y_{lx_1}) + a_2 (f_{y_1} y_{1x_2} + f_{y_2} y_{2x_2} + \dots + f_{y_l} y_{lx_2}) + \dots \\ &+ a_k (f_{y_1} y_{1x_k} + f_{y_2} y_{2x_k} + \dots + f_{y_l} y_{lx_k}) \\ &= f_{y_1} (a_1 y_{1x_1} + a_2 y_{1x_2} + \dots + a_k y_{1x_k}) + f_{y_2} (a_1 y_{2x_1} + a_2 y_{2x_2} + \dots + a_k y_{2x_k}) + \dots \\ &+ f_{y_l} (a_1 y_{lx_1} + a_2 y_{lx_2} + \dots + a_k y_{lx_k}) = 0. \end{aligned}$$

Since $a_1 y_{ix_1} + a_2 y_{ix_2} + \dots + a_k y_{ix_k} = 0$, ($1 \leq i \leq l \leq k-1$), the above equation is correct eternally. So Proposition 1 is proved. According to the characteristic equation method and Conjecture 1 we can know: Usually $l = k-1$. \square

According to Proposition 1, if the exact solutions $u = y_i(x_1, \dots, x_n)$ of $a_1 u_{x_1} + a_2 u_{x_2} + \dots + a_n u_{x_n} = 0$, which are independent of each other, are known, ($1 \leq i \leq l \leq n-1$), then its general solution is $u = f(y_1, y_2, \dots, y_l)$.

Proposition 2. In \mathbb{R}^n , if the general solution $u = f(y_1, y_2, \dots, y_l, x_{k+1}, x_{k+2}, \dots, x_n)$ of $(b_1 D_{x_1} + b_2 D_{x_2} + \dots + b_k D_{x_k})u = 0$ is known, then

$$(b_1 D_{x_1} + b_2 D_{x_2} + \dots + b_k D_{x_k})^2 u = 0 \quad (10)$$

The general solution of Eq. (10) is

$$u = f_1(y_1, \dots, y_l, x_{k+1}, \dots, x_n) + (c_1 x_1 + c_2 x_2 + \dots + c_k x_k) f_2(y_1, \dots, y_l, x_{k+1}, \dots, x_n). \quad (11)$$

Prove. Because the general solution $u = f(y_1, y_2, \dots, y_l, x_{k+1}, x_{k+2}, \dots, x_n)$ of $(b_1 D_{x_1} + b_2 D_{x_2} + \dots + b_k D_{x_k})u = 0$ is known, apparently $u = f(y_1, y_2, \dots, y_l, x_{k+1}, x_{k+2}, \dots, x_n)$ is also the solution

of $(b_1D_{x_1} + b_2D_{x_2} + \dots + b_kD_{x_k})^2u = 0$, setting $u = g(x_1, \dots, x_k)f = c_sx_sf$ is the solution of $(b_1D_{x_1} + b_2D_{x_2} + \dots + b_kD_{x_k})^2u = 0$ too, that is $g(x_1, \dots, x_k) = c_sx_s$, and c_s are arbitrary constants, ($s = 1, 2, \dots, k$), then

$$\begin{aligned}
(b_1D_{x_1} + b_2D_{x_2} + \dots + b_kD_{x_k})^2u &= \left(\sum_{i=1}^k b_i^2 D_{x_i}^2 + 2 \sum_{i<j} b_i b_j D_{x_i} D_{x_j} \right) (gf) \\
&= \sum_{i=1}^k b_i^2 (g_{x_i x_i} f + 2g_{x_i} f_{x_i} + g f_{x_i x_i}) + 2 \sum_{i<j} b_i b_j (g_{x_i x_j} f + g_{x_i} f_{x_j} + g_{x_j} f_{x_i} + g f_{x_i x_j}) \\
&= g \left(\sum_{i=1}^k b_i^2 f_{x_i x_i} + 2 \sum_{i<j} b_i b_j f_{x_i x_j} \right) + f \left(\sum_{i=1}^k b_i^2 g_{x_i x_i} + 2 \sum_{i<j} b_i b_j g_{x_i x_j} \right) + 2 \sum_{i=1}^k b_i^2 g_{x_i} f_{x_i} \\
&\quad + 2 \sum_{i<j} b_i b_j (g_{x_i} f_{x_j} + g_{x_j} f_{x_i}) = 2 \sum_{i=1}^k b_i^2 g_{x_i} f_{x_i} + 2 \sum_{i<j} b_i b_j g_{x_i} f_{x_j} + 2 \sum_{i<j} b_i b_j g_{x_j} f_{x_i} \\
&= 2b_s^2 c_s f_{x_s} + 2c_s b_s \sum_{s<j} b_j f_{x_j} + 2c_s b_s \sum_{i<s} b_i f_{x_i} = 2c_s b_s \sum_{i=1}^k b_i f_{x_i} = 0.
\end{aligned}$$

That $u = c_sx_sf$ is the solution of $(b_1D_{x_1} + b_2D_{x_2} + \dots + b_kD_{x_k})^2u = 0$ is proved. So its general solution is (11). \square

According to Proposition 2, we present a conjecture.

Conjecture 2. In \mathbb{R}^n , if the general solution $u = f(y_1, y_2, \dots, y_l, x_{k+1}, x_{k+2}, \dots, x_n)$ of $(b_1D_{x_1} + b_2D_{x_2} + \dots + b_kD_{x_k})u = 0$ is known, then the general solution of

$$(b_1D_{x_1} + b_2D_{x_2} + \dots + b_kD_{x_k})^m u = 0 \quad (12)$$

is

$$u = \sum_{j=1}^m (c_{j1}x_1 + c_{j2}x_2 + \dots + c_{jk}x_k)^{j-1} f_j(y_1, \dots, y_l, x_{k+1}, \dots, x_n). \quad (13)$$

Theoretically Conjecture 2 can be proved by mathematical induction, we shall not analyse it further.

In \mathbb{R}^n , for the m th-order linear PDE with variable coefficients

$$\sum_{i_1+i_2+\dots+i_k=m} a_{i_1 i_2 \dots i_k} u_{x_1^{i_1} x_2^{i_2} \dots x_k^{i_k}} = 0, \quad (14)$$

where i_j are natural number, $1 \leq j \leq k \leq n$, If Eq. (14) can be translated into

$$(b_{11}D_{x_1} + b_{12}D_{x_2} + \dots + b_{1k}D_{x_k})(b_{21}D_{x_1} + b_{22}D_{x_2} + \dots + b_{2k}D_{x_k}) \dots (b_{m1}D_{x_1} + b_{m2}D_{x_2} + \dots + b_{mk}D_{x_k})u = 0. \quad (15)$$

For

$$(b_{j1}D_{x_1} + b_{j2}D_{x_2} + \dots + b_{jk}D_{x_k})u = b_{j1}u_{x_1} + b_{j2}u_{x_2} + \dots + b_{jk}u_{x_k} = 0, (j = 1, 2, \dots, m). \quad (16)$$

If the particular solutions $u = y_{j_s}(x_1, \dots, x_k)$ of Eq. (16), which are independent of each other, are all known, ($1 \leq s \leq l_j$), by Proposition 1 the general solution of Eq. (14) is

$$u = \sum_{j=1}^m f_j \left(y_{j_1}, y_{j_2}, \dots, y_{j_{l_j}}, x_{k+1}, x_{k+2}, \dots, x_n \right). \quad (17)$$

If Eq. (14) can be translated into:

$$\prod_{j=1}^q (b_{j_1} D_{x_1} + b_{j_2} D_{x_2} + \dots + b_{j_k} D_{x_k})^{p_j} u = 0, \quad (18)$$

where $\sum_{j=1}^q p_j = m$, its general solution of conjecture may be written by Conjecture 2.

Proposition 3. *In \mathbb{R}^n , if the particular solution $g = g(x_1, \dots, x_k)$ of $a_1 g_{x_1} + a_2 g_{x_2} + \dots + a_k g_{x_k} + a_{k+1} g = 0$ and the exact solutions $u = y_i(x_1, \dots, x_k)$ of $a_1 u_{x_1} + a_2 u_{x_2} + \dots + a_k u_{x_k} = 0$, which are independent of each other, are all known, ($1 \leq i \leq l \leq k-1$), then*

$$a_1 u_{x_1} + a_2 u_{x_2} + \dots + a_k u_{x_k} + a_{k+1} u = 0, \quad (19)$$

then the general solution of Eq. (19) is

$$u = g(x_1, \dots, x_k) f(y_1, \dots, y_l, x_{k+1}, \dots, x_n), \quad (20)$$

Prove. By Z_3 Transformation, set $u = g(x_1, \dots, x_k) f(y_1, \dots, y_l, x_{k+1}, \dots, x_n)$, then

$$\begin{aligned} & a_1 u_{x_1} + a_2 u_{x_2} + \dots + a_k u_{x_k} + a_{k+1} u \\ &= a_1 \left(f g_{x_1} + g \sum_{i=1}^l f_{y_i} y_{i x_1} \right) + a_2 \left(f g_{x_2} + g \sum_{i=1}^l f_{y_i} y_{i x_2} \right) + \dots + a_k \left(f g_{x_k} + g \sum_{i=1}^l f_{y_i} y_{i x_k} \right) \\ &+ a_{k+1} g f \\ &= f (a_1 g_{x_1} + a_2 g_{x_2} + \dots + a_k g_{x_k} + a_{k+1} g) + g \sum_{i=1}^l f_{y_i} (a_1 y_{i x_1} + a_2 y_{i x_2} + \dots + a_k y_{i x_k}) = 0 \end{aligned}$$

Since $a_1 g_{x_1} + a_2 g_{x_2} + \dots + a_k g_{x_k} + a_{k+1} g = 0$ and $a_1 y_{i x_1} + a_2 y_{i x_2} + \dots + a_k y_{i x_k} = 0$. The above equation is correct eternally, so Proposition 3 is proved. \square

Proposition 4. *In \mathbb{R}^n , if the general solution $u = g(x_1, \dots, x_k) f(y_1, \dots, y_l, x_{k+1}, \dots, x_n)$ of $(b_1 D_{x_1} + b_2 D_{x_2} + \dots + b_k D_{x_k} + b_{k+1}) u = 0$ is known, then*

$$(b_1 D_{x_1} + b_2 D_{x_2} + \dots + b_k D_{x_k} + b_{k+1})^2 u = 0 \quad (21)$$

The general solution of Eq. (21) is

$$u = g(x_1, \dots, x_k) (f_1(y_1, \dots, y_l, x_{k+1}, \dots, x_n) + (c_1 x_1 + c_2 x_2 + \dots + c_k x_k) f_2(y_1, \dots, y_l, x_{k+1}, \dots, x_n)). \quad (22)$$

Prove. Because the general solution $u = g(x_1, \dots, x_k) f(y_1, \dots, y_l, x_{k+1}, \dots, x_n)$ of $(b_1 D_{x_1} + b_2 D_{x_2} + \dots + b_k D_{x_k} + b_{k+1}) u = 0$ is known, apparently $u = g(x_1, \dots, x_k) f(y_1, \dots, y_l, x_{k+1}, \dots, x_n)$ is also the solution of $(b_1 D_{x_1} + b_2 D_{x_2} + \dots + b_k D_{x_k} + b_{k+1})^2 u = 0$, setting

$$u = h t = c_s x_s g(x_1, \dots, x_k) f(y_1, \dots, y_l, x_{k+1}, \dots, x_n), \quad (1 \leq s \leq k), \quad (23)$$

where $h = c_s x_s, t = g(x_1, \dots, x_k) f(y_1, \dots, y_l, x_{k+1}, \dots, x_n)$, and c_s are arbitrary constants. Assuming (23) is a solution of (21), then

$$\begin{aligned}
& (b_1 D_{x_1} + b_2 D_{x_2} + \dots + b_k D_{x_k} + b_{k+1})^2 u \\
&= \left(\sum_{i=1}^k b_i^2 D_{x_i}^2 + b_{k+1}^2 + 2 \sum_{1 \leq i < j \leq k} b_i b_j D_{x_i} D_{x_j} + 2b_{k+1} \sum_{i=1}^k b_i D_{x_i} \right) (ht) \\
&= \sum_{i=1}^k b_i^2 (h_{x_i x_i} t + 2h_{x_i} t_{x_i} + ht_{x_i x_i}) + b_{k+1}^2 ht \\
&+ 2 \sum_{1 \leq i < j \leq k} b_i b_j (h_{x_i x_j} t + h_{x_i} t_{x_j} + h_{x_j} t_{x_i} + ht_{x_i x_j}) + 2b_{k+1} \sum_{i=1}^k b_i (h_{x_i} t + ht_{x_i}) \\
&= h \left(\sum_{i=1}^k b_i^2 t_{x_i x_i} + b_{k+1}^2 t + 2 \sum_{1 \leq i < j \leq k} b_i b_j t_{x_i x_j} + 2b_{k+1} \sum_{i=1}^k b_i t_{x_i} \right) + t \sum_{i=1}^k b_i^2 h_{x_i x_i} \\
&+ 2 \sum_{i=1}^k b_i^2 h_{x_i} t_{x_i} + 2t \sum_{1 \leq i < j \leq k} b_i b_j h_{x_i x_j} + 2 \sum_{1 \leq i < j \leq k} b_i b_j h_{x_i} t_{x_j} + 2 \sum_{1 \leq i < j \leq k} b_i b_j h_{x_j} t_{x_i} \\
&+ 2b_{k+1} t \sum_{i=1}^k b_i h_{x_i} \\
&= 2 \sum_{i=1}^k b_i^2 h_{x_i} t_{x_i} + 2 \sum_{1 \leq i < j \leq k} b_i b_j h_{x_i} t_{x_j} + 2 \sum_{1 \leq i < j \leq k} b_i b_j h_{x_j} t_{x_i} + 2b_{k+1} t \sum_{i=1}^k b_i h_{x_i} \\
&= 2b_s^2 h_{x_s} t_{x_s} + 2b_s h_{x_s} \sum_{1 \leq s < j \leq k} b_j t_{x_j} + 2b_s h_{x_s} \sum_{1 \leq i < s \leq k} b_i t_{x_i} + 2b_{k+1} b_s h_{x_s} t \\
&= 2b_s h_{x_s} \sum_{i=1}^k b_i t_{x_i} + 2b_{k+1} b_s h_{x_s} t = 2b_s h_{x_s} \left(\sum_{i=1}^k b_i t_{x_i} + b_{k+1} t \right) = 0.
\end{aligned}$$

That (23) is a solution of (21) is proved. So its general solution is (22). \square

According to Proposition 4, we present Conjecture 3.

Conjecture 3. In \mathbb{R}^n , if the general solution $u = g(x_1, \dots, x_k) f(y_1, \dots, y_l, x_{k+1}, \dots, x_n)$ of $(b_1 D_{x_1} + b_2 D_{x_2} + \dots + b_k D_{x_k} + b_{k+1})u = 0$ is known, then the general solution of

$$(b_1 D_{x_1} + b_2 D_{x_2} + \dots + b_k D_{x_k} + b_{k+1})^m u = 0 \quad (24)$$

is

$$u = g(x_1, \dots, x_k) \sum_{j=1}^m (c_{j_1} x_1 + c_{j_2} x_2 + \dots + c_{j_n} x_n)^{j-1} f_j(y_1, \dots, y_l, x_{k+1}, \dots, x_n), \quad (m \geq 2). \quad (25)$$

In \mathbb{R}^n , for the m th-order linear PDE with variable coefficients

$$\sum_{0 \leq i_1 + i_2 + \dots + i_k \leq m} a_{i_1 i_2 \dots i_k} u_{x_1^{i_1} x_2^{i_2} \dots x_k^{i_k}} = 0, \quad (26)$$

where i_j are natural number, $1 \leq j \leq k \leq n$. If Eq. (26) can be translated into

$$(b_{1_1} D_{x_1} + b_{1_2} D_{x_2} + \dots + b_{1_k} D_{x_k} + b_{1_{k+1}}) (b_{2_1} D_{x_1} + b_{2_2} D_{x_2} + \dots + b_{2_k} D_{x_k} + b_{2_{k+1}}) \dots (b_{m_1} D_{x_1} + b_{m_2} D_{x_2} + \dots + b_{m_k} D_{x_k} + b_{m_{k+1}}) u = 0. \quad (27)$$

If the particular solution $u = g_j(x_1, \dots, x_k)$ of $(b_{j_1}D_{x_1} + b_{j_2}D_{x_2} + \dots + b_{j_k}D_{x_k} + b_{j_{k+1}})u = 0$ and the exact solutions $u = y_{j_s}(x_1, \dots, x_k)$ of $(b_{j_1}D_{x_1} + b_{j_2}D_{x_2} + \dots + b_{j_k}D_{x_k})u = 0$, which are independent of each other, are all known, ($1 \leq j \leq m, 1 \leq s \leq l_j$), by Proposition 3 the general solution of Eq. (26) is

$$u(x_1, \dots, x_n) = \sum_{j=1}^m \left(g_j(x_1, \dots, x_k) f_j(y_{j_1}, y_{j_2}, \dots, y_{j_{l_j}}, x_{k+1}, x_{k+2}, \dots, x_n) \right). \quad (28)$$

If Eq. (26) can be translated into:

$$\prod_{j=1}^q (b_{j_1}D_{x_1} + b_{j_2}D_{x_2} + \dots + b_{j_n}D_{x_n} + b_{j_{n+1}})^{p_j} u = 0, \quad (29)$$

where $\sum_{j=1}^q p_j = m$, its general solution of conjecture may be written by Conjecture 3.

In \mathbb{R}^n , for the m th-order linear PDE with variable coefficients

$$\sum_{0 \leq i_1 + i_2 + \dots + i_k \leq m} a_{i_1 i_2 \dots i_k} u_{x_1^{i_1} x_2^{i_2} \dots x_k^{i_k}} = A(x_1, x_2, \dots, x_n), \quad (30)$$

where $A(x_1, x_2, \dots, x_n)$ is an arbitrary known function. In general, we need to solve the particular solution of (30) first, and then use the general solution of its homogeneous equation to obtain its general solution. For some PDEs, we can get the general solution by Z Transformation directly, such as

Proposition 5. In \mathbb{R}^n , if the particular solutions $u = y_i(x_1, \dots, x_k)$ of $a_1 u_{x_1} + a_2 u_{x_2} + \dots + a_k u_{x_k} = 0$ are all known, ($1 \leq i \leq k-1$), then

$$a_1 u_{x_1} + a_2 u_{x_2} + \dots + a_k u_{x_k} + a_{k+1} = 0, \quad (31)$$

the general solution of Eq. (31) is

$$u = f(y_1, \dots, y_{k-1}, x_{k+1}, \dots, x_n) + \frac{\int a_{k+1}(y_1, \dots, y_k, x_{k+1}, \dots, x_n) dy_k}{a_1 y_{k_{x_1}} + a_2 y_{k_{x_2}} + \dots + a_k y_{k_{x_k}}}, \quad (32)$$

where y_1, y_2, \dots, y_k are independent of each other, and $x_j = x_j(y_1, y_2, \dots, y_k)$ can be solved, ($1 \leq j \leq k$).

Prove. By Z_1 Transformation, set $u(x_1, x_2, \dots, x_n) = u(y_1, y_2, \dots, y_k, x_{k+1}, x_{k+2}, \dots, x_n)$ and $a_i(x_1, x_2, \dots, x_n) = a_i(y_1, y_2, \dots, y_k, x_{k+1}, x_{k+2}, \dots, x_n)$, where $y_t = y_t(x_1, x_2, \dots, x_k)$, ($t = 1, 2, \dots, k$), and y_1, y_2, \dots, y_k are independent of each other, then

$$\begin{aligned} a_1 u_{x_1} + a_2 u_{x_2} + \dots + a_k u_{x_k} + a_{k+1} &= a_1 \sum_{t=1}^k y_{t_{x_1}} u_{y_t} + a_2 \sum_{t=1}^k y_{t_{x_2}} u_{y_t} + \dots + a_k \sum_{t=1}^k y_{t_{x_k}} u_{y_t} + a_{k+1} \\ &= \left(a_1 y_{1_{x_1}} + a_2 y_{1_{x_2}} + \dots + a_k y_{1_{x_k}} \right) u_{y_1} + \left(a_1 y_{2_{x_1}} + a_2 y_{2_{x_2}} + \dots + a_k y_{2_{x_k}} \right) u_{y_2} + \dots \\ &+ \left(a_1 y_{k_{x_1}} + a_2 y_{k_{x_2}} + \dots + a_k y_{k_{x_k}} \right) u_{y_k} + a_{k+1} = 0. \end{aligned} \quad (33)$$

If the particular solutions $u = y_i(x_1, \dots, x_k)$ of $a_1 u_{x_1} + a_2 u_{x_2} + \dots + a_k u_{x_k} = 0$ are all known ($1 \leq i \leq k-1$), then Eq. (33) can be translated into

$$\left(a_1 y_{k_{x_1}} + a_2 y_{k_{x_2}} + \dots + a_k y_{k_{x_k}} \right) u_{y_k} + a_{k+1} = 0. \quad (34)$$

A particular solution of Eq. (34) is

$$u = \frac{\int a_{k+1}(y_1, \dots, y_k, x_{k+1}, \dots, x_n) dy_k}{a_1 y_{kx_1} + a_2 y_{kx_2} + \dots + a_k y_{kx_k}}. \quad (35)$$

To compute (35) we need to find a first differentiable $y_k = y_k(x_1, x_2, \dots, x_k)$ and make y_1, y_2, \dots, y_k independent of each other, and can solve $x_j = x_j(y_1, y_2, \dots, y_k)$, then the general solution of (31) is (32). So the proposition is proved. \square

Proposition 6. In \mathbb{R}^n , if the particular solutions $y_i = y_i(x_1, x_2, \dots, x_k, u)$ of $a_1 y_{x_1} + a_2 y_{x_2} + \dots + a_k y_{x_k} - a_{k+1} y_u = 0$, which are independent of each other, are all known, ($1 \leq i \leq k \leq n$), then

$$a_1 u_{x_1} + a_2 u_{x_2} + \dots + a_k u_{x_k} + a_{k+1} = 0, \quad (36)$$

the general solution of Eq. (36) is

$$f(y_1, y_2, \dots, y_k, x_{k+1}, x_{k+2}, \dots, x_n) = 0, \quad (37)$$

where $a_j = a_j(x_1, x_2, \dots, x_k, u)$ are arbitrary known functions ($1 \leq j \leq k+1$).

Prove. By Z_4 Transformation, set $f(y_1, y_2, \dots, y_k, x_{k+1}, x_{k+2}, \dots, x_n) = 0$ and

$$y_i = y_i(x_1, x_2, \dots, x_k, u), \quad (1 \leq i \leq k \leq n) \quad (38)$$

y_1, y_2, \dots, y_k are independent of each other. According to (5), we get

$$\begin{aligned} & a_1 u_{x_1} + a_2 u_{x_2} + \dots + a_k u_{x_k} + a_{k+1} \\ &= -a_1 \frac{\sum_{i=1}^k f_{y_i} y_{ix_1}}{\sum_{i=1}^k f_{y_i} y_{iu}} - a_2 \frac{\sum_{i=1}^k f_{y_i} y_{ix_2}}{\sum_{i=1}^k f_{y_i} y_{iu}} - \dots - a_k \frac{\sum_{i=1}^k f_{y_i} y_{ix_k}}{\sum_{i=1}^k f_{y_i} y_{iu}} + a_{k+1} = 0 \\ &\implies a_1 \sum_{i=1}^k f_{y_i} y_{ix_1} + a_2 \sum_{i=1}^k f_{y_i} y_{ix_2} + \dots + a_k \sum_{i=1}^k f_{y_i} y_{ix_k} - a_{k+1} \sum_{i=1}^k f_{y_i} y_{iu} \\ &= (a_1 y_{1x_1} + a_2 y_{1x_2} + \dots + a_k y_{1x_k} - a_{k+1} y_{1u}) f_{y_1} \\ &+ (a_1 y_{2x_1} + a_2 y_{2x_2} + \dots + a_k y_{2x_k} - a_{k+1} y_{2u}) f_{y_2} + \dots \\ &+ (a_1 y_{kx_1} + a_2 y_{kx_2} + \dots + a_k y_{kx_k} - a_{k+1} y_{ku}) f_{y_k} = 0. \end{aligned}$$

Set

$$a_1 y_{ix_1} + a_2 y_{ix_2} + \dots + a_k y_{ix_k} - a_{k+1} y_{iu} = 0, \quad (i = 1, 2, \dots, k). \quad (39)$$

For

$$a_1 y_{x_1} + a_2 y_{x_2} + \dots + a_k y_{x_k} - a_{k+1} y_u = 0. \quad (40)$$

If the particular solutions $y_i = y_i(x_1, x_2, \dots, x_k, u)$ of (40), which are independent of each other, are all known, then the general solution of (36) is (37). So the proposition is proved. \square

2.2. General solutions' laws of some nonlinear partial differential equations with variable coefficients

Methods for solving exact solutions of nonlinear PDEs are complex and diverse, such as homogeneous balance method [11-13], multiple exp-function method [14,15], tanh-sech method [16-18] and so on. For certain seemingly complex nonlinear PDEs, we can obtain their general solution by using algebraic algorithm and some conclusions in the previous section. For example, according to Proposition 1 we can get Proposition 7 directly:

Proposition 7. In \mathbb{R}^n , if the general solutions $u = f_i(y_{i_1}, y_{i_2}, \dots, y_{i_{l_i}}, x_{k+1}, x_{k+2}, \dots, x_n)$ of $a_{i_1}u_{x_1} + a_{i_2}u_{x_2} + \dots + a_{i_k}u_{x_k} = 0$ are known, ($1 \leq i \leq m, 1 \leq l_i \leq k-1$), then

$$\begin{aligned} & (a_{1_1}u_{x_1} + a_{1_2}u_{x_2} + \dots + a_{1_k}u_{x_k})^{c_1} (a_{2_1}u_{x_1} + a_{2_2}u_{x_2} + \dots + a_{2_k}u_{x_k})^{c_2} \dots \\ & (a_{m_1}u_{x_1} + a_{m_2}u_{x_2} + \dots + a_{m_k}u_{x_k})^{c_m} = 0, \end{aligned} \quad (41)$$

the general solution of Eq. (41) is

$$\prod_{i=1}^m \left(u - f_i \left(y_{i_1}, y_{i_2}, \dots, y_{i_{l_i}}, x_{k+1}, x_{k+2}, \dots, x_n \right) \right) = 0. \quad (42)$$

According to Proposition 3 we can obtain directly Proposition 8:

Proposition 8. In \mathbb{R}^n , if the general solutions $u = g_i(x_1, \dots, x_k) f_i(y_{i_1}, y_{i_2}, \dots, y_{i_{l_i}}, x_{k+1}, x_{k+2}, \dots, x_n)$ of $a_{i_1}u_{x_1} + a_{i_2}u_{x_2} + \dots + a_{i_k}u_{x_k} + a_{i_{k+1}}u = 0$ are known, ($1 \leq i \leq m, 1 \leq l_i \leq k-1$), then

$$\begin{aligned} & (a_{1_1}u_{x_1} + a_{1_2}u_{x_2} + \dots + a_{1_k}u_{x_k} + a_{i_{k+1}}u)^{c_1} (a_{2_1}u_{x_1} + a_{2_2}u_{x_2} + \dots + a_{2_k}u_{x_k} + a_{2_{k+1}}u)^{c_2} \\ & \dots (a_{m_1}u_{x_1} + a_{m_2}u_{x_2} + \dots + a_{m_k}u_{x_k} + a_{m_{k+1}}u)^{c_m} = 0, \end{aligned} \quad (43)$$

the general solution of Eq. (43) is

$$\prod_{i=1}^m \left(u - g_i(x_1, \dots, x_k) f_i \left(y_{i_1}, y_{i_2}, \dots, y_{i_{l_i}}, x_{k+1}, x_{k+2}, \dots, x_n \right) \right) = 0. \quad (44)$$

According to Proposition 6 we can get directly Proposition 9:

Proposition 9. In \mathbb{R}^n , if the general solutions $f_i(y_{i_1}, y_{i_2}, \dots, y_{i_k}, x_{k+1}, x_{k+2}, \dots, x_n) = 0$ of $a_{i_1}u_{x_1} + a_{i_2}u_{x_2} + \dots + a_{i_k}u_{x_k} + a_{i_{k+1}}u = 0$ are known, where $a_{i_j} = a_{i_j}(x_1, x_2, \dots, x_k, u)$ are arbitrary known functions ($1 \leq i \leq m, 1 \leq j \leq k+1$), then

$$\begin{aligned} & (a_{1_1}u_{x_1} + a_{1_2}u_{x_2} + \dots + a_{1_k}u_{x_k} + a_{i_{k+1}}u)^{c_1} (a_{2_1}u_{x_1} + a_{2_2}u_{x_2} + \dots + a_{2_k}u_{x_k} + a_{2_{k+1}}u)^{c_2} \\ & \dots (a_{m_1}u_{x_1} + a_{m_2}u_{x_2} + \dots + a_{m_k}u_{x_k} + a_{m_{k+1}}u)^{c_m} = 0, \end{aligned} \quad (45)$$

the general solution of Eq. (45) is

$$\prod_{i=1}^m f_i \left(y_{i_1}, y_{i_2}, \dots, y_{i_k}, x_{k+1}, x_{k+2}, \dots, x_n \right) = 0. \quad (46)$$

3. General solutions laws of partial differential equations with constant coefficients

Here we will research the general solutions' laws of PDEs with constant coefficients, which are the special cases of PDEs with variable coefficients. In this section, if there is no special interpretation, the acquiescent independent variables of \mathbb{R}^n are x_1, x_2, \dots, x_n , ($2 \leq k \leq n$), $D_{x_i} \equiv \frac{\partial}{\partial x_i}$. a_i, b_i, b_{i_j} and $a_{i_1 i_2 \dots i_n}$ are arbitrary known constants, $c_i, c_{i_j}, c_{i_s j}, l_i$ and l_{j_i} are arbitrary constants, f and f_i are arbitrary smooth functions ($i, j, s = 1, 2, \dots$).

Proposition 10. In \mathbb{R}^n ,

$$a_1 u_{x_1} + a_2 u_{x_2} + \dots + a_k u_{x_k} = A(x_1, x_2, \dots, x_n), \quad (2 \leq k \leq n), \quad (47)$$

the general solution of Eq. (47) is

$$u = f(y_1, y_2, \dots, y_{k-1}, x_{k+1}, x_{k+2}, \dots, x_n) + \frac{\int A(y_1, y_2, \dots, y_k, x_{k+1}, x_{k+2}, \dots, x_n) dy_k}{a_1 c_{k1} + a_2 c_{k2} + \dots + a_k c_{kk}}, \quad (48)$$

where

$$y_i = c_{i1}x_1 + c_{i2}x_2 + \dots + c_{ik}x_k, \quad (1 \leq i \leq k), \quad (49)$$

$$\frac{\partial(y_1, y_2, \dots, y_k, x_{k+1}, x_{k+2}, \dots, x_n)}{\partial(x_1, x_2, \dots, x_n)} = \frac{\partial(y_1, y_2, \dots, y_k)}{\partial(x_1, x_2, \dots, x_k)} \neq 0, \quad (50)$$

$$c_{i1} = \frac{-a_2 c_{i2} - a_3 c_{i3} - \dots - a_k c_{ik}}{a_1}, \quad (1 \leq i \leq k-1). \quad (51)$$

Prove. According to Z_1 Transformation, set $u(x_1, x_2, \dots, x_n) = u(y_1, y_2, \dots, y_k, x_{k+1}, x_{k+2}, \dots, x_n)$, $A(x_1, x_2, \dots, x_n) = A(y_1, y_2, \dots, y_k, x_{k+1}, x_{k+2}, \dots, x_n)$ and

$$\begin{cases} y_1 = c_{11}x_1 + c_{12}x_2 + \dots + c_{1k}x_k \\ y_2 = c_{21}x_1 + c_{22}x_2 + \dots + c_{2k}x_k, \\ \dots \\ y_k = c_{k1}x_1 + c_{k2}x_2 + \dots + c_{kk}x_k \end{cases} \quad (52)$$

and

$$\frac{\partial(y_1, y_2, \dots, y_k)}{\partial(x_1, x_2, \dots, x_k)} \neq 0, \quad (50)$$

where c_{ij} are undetermined constants. According to (50, 52), $x_i = x_i(y_1, y_2, \dots, y_k)$ always has a unique solution ($1 \leq i, j \leq k$). So

$$\begin{aligned} a_1 u_{x_1} + a_2 u_{x_2} + \dots + a_k u_{x_k} &= a_1 \sum_{i=1}^k c_{i1} u_{y_i} + a_2 \sum_{i=1}^k c_{i2} u_{y_i} + \dots + a_k \sum_{i=1}^k c_{ik} u_{y_i} \\ &= (a_1 c_{11} + a_2 c_{12} + \dots + a_k c_{1k}) u_{y_1} + (a_1 c_{21} + a_2 c_{22} + \dots + a_k c_{2k}) u_{y_2} + \dots \\ &\quad + (a_1 c_{k1} + a_2 c_{k2} + \dots + a_k c_{kk}) u_{y_k}. \end{aligned}$$

Set

$$a_1 c_{11} + a_2 c_{12} + \dots + a_k c_{1k} = a_1 c_{21} + a_2 c_{22} + \dots + a_k c_{2k} = a_1 c_{(k-1)1} + a_2 c_{(k-1)2} + \dots + a_k c_{(k-1)k} = 0.$$

We obtain

$$c_{i1} = \frac{-a_2 c_{i2} - a_3 c_{i3} - \dots - a_k c_{ik}}{a_1}, \quad (1 \leq i \leq k-1). \quad (51)$$

Then

$$a_1 u_{x_1} + a_2 u_{x_2} + \dots + a_k u_{x_k} = (a_1 c_{k1} + a_2 c_{k2} + \dots + a_k c_{kk}) u_{y_k} = A(y_1, y_2, \dots, y_k, x_{k+1}, x_{k+2}, \dots, x_n). \quad (52)$$

The particular solution of (52) is $u = \frac{\int A(y_1, y_2, \dots, y_k, x_{k+1}, x_{k+2}, \dots, x_n) dy_k}{a_1 c_{k1} + a_2 c_{k2} + \dots + a_k c_{kk}}$, so the general solution of Eq. (47) is (48). \square

According to Proposition 10, in \mathbb{R}^n ,

$$a_1 u_{x_1} + a_2 u_{x_2} + \dots + a_n u_{x_n} = A(x_1, x_2, \dots, x_n), \quad (53)$$

the general solution of Eq. (53) is

$$u = f(y_1, y_2, \dots, y_{n-1}) + \frac{\int A(y_1, y_2, \dots, y_n) dy_n}{a_1 c_{n1} + a_2 c_{n2} + \dots + a_n c_{nn}}, \quad (54)$$

where

$$y_i = c_{i1}x_1 + c_{i2}x_2 + \dots + c_{in}x_n, \quad (55)$$

$$c_{i1} = \frac{-a_2 c_{i2} - a_3 c_{i3} - \dots - a_k c_{ik}}{a_1}, \quad (1 \leq i \leq n-1). \quad (56)$$

According to Proposition 10 we can get Proposition 11:

Proposition 11. In \mathbb{R}^n ,

$$a_1 u_{x_1} + a_2 u_{x_2} + \dots + a_k u_{x_k} = 0, \quad (57)$$

the general solution of Eq. (57) is

$$u = f(y_1, y_2, \dots, y_{k-1}, x_{k+1}, x_{k+2}, \dots, x_n), \quad (58)$$

where y_i satisfy (49-51).

The proof of Proposition 11 is not complicated, the readers can try it.

According to Proposition 2 and 11, we can get directly Proposition 12:

Proposition 12. In \mathbb{R}^n , if the general solution $u = f(y_1, y_2, \dots, y_{k-1}, x_{k+1}, x_{k+2}, \dots, x_n)$ of $(b_1 D_{x_1} + b_2 D_{x_2} + \dots + b_k D_{x_k})u = 0$ is known, $y_i = y_i(x_1, \dots, x_k)$, ($i = 1, 2, \dots, k-1$), then

$$(b_1 D_{x_1} + b_2 D_{x_2} + \dots + b_k D_{x_k})^2 u = 0 \quad (59)$$

the general solution of Eq. (59) is

$$u = f_1(y_1, \dots, y_{k-1}, x_{k+1}, \dots, x_n) + (c_1 x_1 + c_2 x_2 + \dots + c_k x_k) f_2(y_1, \dots, y_{k-1}, x_{k+1}, \dots, x_n). \quad (60)$$

According to Conjecture 2, we may present Conjecture 4:

Conjecture 4. In \mathbb{R}^n , if the general solution $u = f(y_1, \dots, y_{k-1}, x_{k+1}, \dots, x_n)$ of $(b_1 D_{x_1} + b_2 D_{x_2} + \dots + b_k D_{x_k})u = 0$ is known, then the general solution of

$$(b_1 D_{x_1} + b_2 D_{x_2} + \dots + b_k D_{x_k})^m u = 0 \quad (61)$$

is

$$u = \sum_{i=1}^m (c_{i1}x_1 + c_{i2}x_2 + \dots + c_{ik}x_k)^{i-1} f_i(y_1, \dots, y_{k-1}, x_{k+1}, \dots, x_n). \quad (62)$$

In \mathbb{R}^n , for the m th-order linear PDE with constant coefficients

$$\sum_{i_1+i_2+\dots+i_k=m} a_{i_1 i_2 \dots i_k} u_{x_1^{i_1} x_2^{i_2} \dots x_k^{i_k}} = 0, \quad (63)$$

where i_j are natural number, $1 \leq j \leq k \leq n$. If Eq. (63) can be translated into

$$(b_{1_1}D_{x_1} + b_{1_2}D_{x_2} + \dots + b_{1_k}D_{x_k})(b_{2_1}D_{x_1} + b_{2_2}D_{x_2} + \dots + b_{2_k}D_{x_k}) \dots (b_{m_1}D_{x_1} + b_{m_2}D_{x_2} + \dots + b_{m_k}D_{x_k})u = 0. \quad (64)$$

According to Proposition 11, we can get the general solution of Eq. (63) is

$$u = \sum_{r=1}^m f_r(y_{r_1}, y_{r_2}, \dots, y_{r_{k-1}}, x_{k+1}, \dots, x_n), \quad (1 \leq r \leq m), \quad (65)$$

where

$$y_{r_s} = c_{r_{s1}}x_1 + c_{r_{s2}}x_2 + \dots + c_{r_{sk}}x_k, \quad (1 \leq s \leq k-1), \quad (66)$$

$$c_{r_{s1}} = \frac{-b_{s2}c_{r_{s1}} - b_{s3}c_{r_{s2}} - \dots - b_{sk}c_{r_{sk}}}{b_{s1}}. \quad (67)$$

If Eq. (63) can be translated into:

$$\prod_{j=1}^q (b_{j_1}D_{x_1} + b_{j_2}D_{x_2} + \dots + b_{j_k}D_{x_k})^{p_j}u = 0, \quad (68)$$

where $\sum_{j=1}^q p_j = m$, its general solution of conjecture may be written by Conjecture 3.

Proposition 13. In \mathbb{R}^n ,

$$a_1u_{x_1} + a_2u_{x_2} + \dots + a_ku_{x_k} + a_{k+1}u = 0 \quad (69)$$

the general solution of Eq. (69) is

$$u = f(y_1, y_2, \dots, y_{k-1}, x_{k+1}, x_{k+2}, \dots, x_n) \sum_{i=1}^k l_i e^{\frac{-a_{k+1}x_i}{a_i}}, \quad (70)$$

where l_i are arbitrary constants, and y_i satisfy (49-51).

Prove. According to Z_3 Transformation, set $u(x_1, \dots, x_n) = g(x_1, \dots, x_k)h(y_1, y_2, \dots, y_k, x_{k+1}, x_{k+2}, \dots, x_n)$, $y_i = c_{i1}x_1 + c_{i2}x_2 + \dots + c_{ik}x_k$ and

$$\frac{\partial(y_1, y_2, \dots, y_k)}{\partial(x_1, x_2, \dots, x_k)} \neq 0. \quad (50)$$

So

$$\begin{aligned} & a_1u_{x_1} + a_2u_{x_2} + \dots + a_ku_{x_k} + a_{k+1}u \\ &= a_1g_{x_1}h + a_1g \sum_{i=1}^k c_{i1}h_{y_i} + a_2g_{x_2}h + a_2g \sum_{i=1}^k c_{i2}h_{y_i} + \dots + a_kg_{x_k}h + a_kg \sum_{i=1}^k c_{ik}h_{y_i} + a_{k+1}gh \\ &= (a_1c_{11} + a_2c_{12} + \dots + a_kc_{1k})gh_{y_1} + (a_1c_{21} + a_2c_{22} + \dots + a_kc_{2k})gh_{y_2} + \dots \\ &+ (a_1c_{k1} + a_2c_{k2} + \dots + a_kc_{kk})gh_{y_k} + (a_1g_{x_1} + a_2g_{x_2} + \dots + a_kg_{x_k} + a_{k+1}g)h = 0. \end{aligned}$$

Set

$$c_{i1} = \frac{-a_2c_{i2} - a_3c_{i3} - \dots - a_kc_{ik}}{a_1}, \quad (1 \leq i \leq k-1). \quad (51)$$

And set

$$a_1g_{x_1} + a_2g_{x_2} + \dots + a_kg_{x_k} + a_{k+1}g = 0, \quad (71)$$

And set $g(x_1, \dots, x_k) = g(x_i)$, ($i = 1, 2, \dots, k$), Then

$$a_1 g_{x_1} + a_2 g_{x_2} + \dots + a_k g_{x_k} + a_{k+1} g = a_i g_{x_i} + a_{k+1} g = 0 \implies g(x_i) = l_i e^{\frac{-a_{k+1} x_i}{a_i}}, \quad (72)$$

where l_i are arbitrary constants. Namely $g(x_1, \dots, x_k) = \sum_{i=1}^k l_i e^{\frac{-a_{k+1} x_i}{a_i}}$ is a particular solution of $a_1 g_{x_1} + a_2 g_{x_2} + \dots + a_k g_{x_k} + a_{k+1} g = 0$, Thus

$$a_1 u_{x_1} + a_2 u_{x_2} + \dots + a_k u_{x_n} + a_{k+1} u = (a_1 c_{k1} + a_2 c_{k2} + \dots + a_k c_{kk}) g h_{y_k} = 0 \implies h_{y_k} = 0.$$

Namely

$$h = f(y_1, y_2, \dots, y_{k-1}, x_{k+1}, x_{k+2}, \dots, x_n),$$

where f is an arbitrary first differentiable function, so the general solution of Eq. (69) is

$$u = g h = f(y_1, y_2, \dots, y_{k-1}, x_{k+1}, x_{k+2}, \dots, x_n) \sum_{i=1}^k l_i e^{\frac{-a_{k+1} x_i}{a_i}}.$$

□

According to Proposition 4 and 13, we can get Proposition 14 directly:

Proposition 14. In \mathbb{R}^n ,

$$(b_1 D_{x_1} + b_2 D_{x_2} + \dots + b_k D_{x_k} + b_{k+1})^2 u = 0, \quad (73)$$

the general solution of Eq. (73) is

$$u = \left(\sum_{j=1}^2 (s_{j1} x_1 + s_{j2} x_2 + \dots + s_{jk} x_k)^{j-1} f_j(y_1, \dots, y_{k-1}, x_{k+1}, \dots, x_n) \right) \sum_{i=1}^k l_i e^{\frac{-b_{k+1} x_i}{b_i}}, \quad (74)$$

where l_i, s_{jr} are arbitrary constants ($1 \leq r, i \leq k$), and y_i satisfy (49-51).

According to Proposition 14, we may present Conjecture 5:

Conjecture 5. In \mathbb{R}^n ,

$$(b_1 D_{x_1} + b_2 D_{x_2} + \dots + b_k D_{x_k} + b_{k+1})^m u = 0 \quad (75)$$

the general solution of Eq. (75) is

$$u = \left(\sum_{j=1}^m (s_{j1} x_1 + s_{j2} x_2 + \dots + s_{jk} x_k)^{j-1} f_j(y_1, \dots, y_{k-1}, x_{k+1}, \dots, x_n) \right) \sum_{i=1}^k l_i e^{\frac{-b_{k+1} x_i}{b_i}}, \quad (76)$$

where l_i, s_{jr} are arbitrary constants ($1 \leq r, i \leq k$), and y_i satisfy (49-51).

In \mathbb{R}^n , for the m th-order linear PDE with constant coefficients

$$\sum_{0 \leq i_1 + i_2 + \dots + i_k \leq m} a_{i_1 i_2 \dots i_k} u_{x_1^{i_1} x_2^{i_2} \dots x_k^{i_k}} = 0, \quad (77)$$

where i_j are natural number, $1 \leq j \leq k \leq n$. If Eq. (77) can be translated into

$$\begin{aligned} & (b_{1_1}D_{x_1} + b_{1_2}D_{x_2} + \dots + b_{1_k}D_{x_k} + b_{1_{k+1}}) (b_{2_1}D_{x_1} + b_{2_2}D_{x_2} + \dots + b_{2_k}D_{x_k} + b_{2_{k+1}}) \\ & \dots (b_{m_1}D_{x_1} + b_{m_2}D_{x_2} + \dots + b_{m_k}D_{x_k} + b_{m_{k+1}}) u = 0. \end{aligned} \quad (78)$$

By Proposition 13, the general solution of Eq. (77) is

$$u = \sum_{r=1}^m \left(f_r (y_{r_1}, y_{r_2}, \dots, y_{r_{k-1}}, x_{k+1}, \dots, x_n) \sum_{i=1}^k l_{j_i} e^{\frac{-b_{j_{k+1}} x_i}{b_{j_i}}} \right), \quad (79)$$

where y_{r_s} satisfies (66-67), ($1 \leq s \leq k-1$).

If Eq. (77) can be translated into:

$$\prod_{j=1}^q (b_{j_1}D_{x_1} + b_{j_2}D_{x_2} + \dots + b_{j_k}D_{x_k} + b_{j_{k+1}})^{p_j} u = 0, \quad (80)$$

where $\sum_{j=1}^q p_j = m$, its general solution of conjecture may be written by Conjecture 5.

Proposition 15. In \mathbb{R}^n ,

$$a_1 u_{x_1} + a_2 u_{x_2} + \dots + a_k u_{x_k} = A(u) \quad (81)$$

the general solution of Eq. (81) is

$$f(y_1, y_2, \dots, y_k, x_{k+1}, x_{k+2}, \dots, x_n) = 0, \quad (37)$$

where $A(u)$ is an arbitrary known function, and

$$y_i = c_{i1}x_1 + c_{i2}x_2 + \dots + c_{ik}x_k - \int \frac{a_i c_{i1} + a_2 c_{i2} + \dots + a_k c_{ik}}{A(u)} du, \quad (82)$$

$$\frac{\partial (y_1, y_2, \dots, y_k)}{\partial (x_1, x_2, \dots, x_k)} \neq 0, \quad (50)$$

c_{ij} which satisfy (50) are relatively arbitrary constants ($i, j \in \{1, 2, \dots, k\}$).

Prove. According to Z_4 Transformation, set $f(y_1, y_2, \dots, y_k, x_{k+1}, x_{k+2}, \dots, x_n) = 0$ and

$$y_i = c_{i1}x_1 + c_{i2}x_2 + \dots + c_{ik}x_k + B_i(u), \quad (i = 1, 2, \dots, k), \quad (83)$$

y_1, y_2, \dots, y_k are independent of each other. According to (5), we get

$$\begin{aligned} a_1 u_{x_1} + a_2 u_{x_2} + \dots + a_k u_{x_k} &= -a_1 \frac{\sum_{i=1}^k c_{i1} f_{y_i}}{\sum_{i=1}^k B_{i_u} f_{y_i}} - a_2 \frac{\sum_{i=1}^k c_{i2} f_{y_i}}{\sum_{i=1}^k B_{i_u} f_{y_i}} - \dots - a_k \frac{\sum_{i=1}^k c_{ik} f_{y_i}}{\sum_{i=1}^k B_{i_u} f_{y_i}} = A(u) \\ \implies a_1 \sum_{i=1}^k c_{i1} f_{y_i} + a_2 \sum_{i=1}^k c_{i2} f_{y_i} + \dots + a_k \sum_{i=1}^k c_{ik} f_{y_i} + A(u) \sum_{i=1}^k B_{i_u} f_{y_i} \\ &= (a_1 c_{11} + a_2 c_{12} + \dots + a_k c_{1k} + B_{1_u} A) f_{y_1} + (a_1 c_{21} + a_2 c_{22} + \dots + a_k c_{2k} + B_{2_u} A) f_{y_2} + \dots \\ &+ (a_1 c_{k1} + a_2 c_{k2} + \dots + a_k c_{kk} + B_{k_u} A) f_{y_k} = 0, \end{aligned} \quad (84)$$

where $B_{i_u} \equiv \frac{dB_i}{du}$, set

$$a_i c_{i1} + a_2 c_{i2} + \dots + a_k c_{ik} + B_{i_u} A = 0, \quad (i = 1, 2, \dots, k). \quad (85)$$

Then

$$B_i(u) = - \int \frac{a_i c_{i1} + a_2 c_{i2} + \dots + a_k c_{ik}}{A(u)} du. \quad (86)$$

So the general solution of Eq. (81) is (37)

$$f(y_1, y_2, \dots, y_k, x_{k+1}, x_{k+2}, \dots, x_n) = 0, \quad (37)$$

where y_i satisfy (50, 82). \square

It is not difficult to verify that the incomplete general solution of (81) only be got by using the characteristic equation method.

For some special nonlinear PDEs with constant coefficients, their general solutions can be obtained by similar methods in 2.2 section, we will not specifically study here.

4. Conclusions

In this paper, we first prove a new theorem for the independent variable transformational equations, that is, the independent variable transformation not only does not change the linearity or non-linearity of the original PDEs, but also does not change their order.

We propose the concept of the banal PDE and the non-banal PDE, and then use the proposed four kinds of Z Transformations to obtain the plentiful laws of general solutions of the linear PDEs with variable coefficient and constant coefficients, and get some laws of general solutions of the nonlinear PDEs, and present five new guesses.

The characteristic equation method is a basic method to solve first order linear and quasilinear PDEs. By comparing with the Z Transformations, we can find that it has many limitations, such as using it cannot get the general solutions of the first order linear PDEs (31.47), cannot obtain the complete general solutions of (57,81) and so on.

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