The quantum-mechanical wavefunction as a gravitational wave

22 October 2017

Jean Louis Van Belle¹, Drs, M.AEc, BAEc, BPhil

Abstract: The geometry of the elementary quantum-mechanical wavefunction \((a \cos \theta - i a \sin \theta)\) and a linearly polarized electromagnetic wave \((E + B)\) consist of two plane waves that are perpendicular to the direction of propagation: their components only differ in magnitude and – more importantly – in their relative phase (0 and 90° respectively). The physical dimension of the electric field vector is force per unit charge (N/C). It is, therefore, tempting to associate the real and imaginary component of the wavefunction with a similar physical dimension: force per unit mass (N/kg). This is, of course, the dimension of the gravitational field, which reduces to the dimension of acceleration (1 N/kg = 1 m/s²).

The results and implications are remarkably elegant and intuitive:

— Schrödinger’s wave equation, for example, can now be interpreted as an energy diffusion equation, and the wavefunction itself can be interpreted as a propagating gravitational wave.
— The energy conservation principle then gives us a physical normalization condition, as probabilities \((P = |\psi|^2)\) are then, effectively, proportional to energy densities \((u)\).
— We also get a more intuitive explanation of spin angular momentum, the boson-fermion dichotomy, and the Compton scattering radius for a particle.
— Finally, this physical interpretation of the wavefunction may also give us some clues in regard to the mechanism of relativistic length contraction.

The interpretation does not challenge the Copenhagen interpretation of quantum mechanics: interpreting probability amplitudes as traveling field disturbances does not explain why a particle hits a detector as a particle (not as a wave). As such, this interpretation respects the complementarity principle.

Contents:

Introduction .................................................................................................................................................. 1
I. Energy as a two-dimensional oscillation of mass ...................................................................................... 3
II. The wavefunction as a two-dimensional oscillation ................................................................................. 5
III. Mass as a scalar field ................................................................................................................................ 7
IV. Schrödinger’s equation as an energy diffusion equation ........................................................................ 9
V. Energy densities and flows ..................................................................................................................... 12
VI. The de Broglie wavelength and relativistic length contraction ............................................................. 14
VII. Schrödinger’s equation, the dispersion relation and the 1/2 factor .................................................... 19
VIII. Explaining spin ..................................................................................................................................... 25
IX. The boson-fermion dichotomy .............................................................................................................. 27
X. Concluding remarks .............................................................................................................................. 29
Appendix: The elementary wavefunction as a finite string ........................................................................ 30
References .................................................................................................................................................. 34

¹ Website: https://readingfeynman.org, Email: jeanlouisvanbelle@yahoo.co.uk.
Introduction

This paper offers a physical interpretation of wave mechanics. We do not challenge the complementarity principle: the interpretation of the wavefunction that is offered here explains the wave nature of matter only. Hence, it will explain diffraction and interference of amplitudes but it does not explain why a particle will hit the detector as a particle—i.e. as a blob of energy, instead of some spread-out wave front. Hence, the Copenhagen interpretation of the wavefunction remains relevant: we just push its boundaries.

The basic ideas in this paper stem from a simple observation: the geometry of the elementary quantum-mechanical wavefunction and a plane electromagnetic wave is remarkably similar. The components of both waves are orthogonal to the direction of propagation and to each other. Only the relative phase differs: the electric and magnetic field vectors (E and B) have the same phase. In contrast, the phase of the real and imaginary part of the (elementary) wavefunction (\(\psi = a \cdot e^{-i\theta} = a \cdot \cos \theta - a \cdot i \cdot \sin \theta\)) differ by 90 degrees (\(\pi/2\)).

Pursuing the analogy, we explore the following question: if the oscillating electric and magnetic field vectors of an electromagnetic wave carry the energy that one associates with the wave, can we analyze the real and imaginary part of the wavefunction in a similar way?

This paper suggests the answer to this question may be positive. The analysis is straightforward and intuitive: if the physical dimension of the electromagnetic field is expressed in newton per coulomb (force per unit charge), then the physical dimension of the components of the wavefunction may be associated with force per unit mass (newton per kg).

Of course, force over some distance is energy. The question then becomes: what is the energy concept here? Kinetic? Potential? Both?

This classical distinction is, perhaps, not very relevant in this context. The similarity between the energy of a (one-dimensional) linear oscillator (\(E = m \cdot a^2 \cdot \omega^2 / 2\)) and Einstein’s relativistic energy equation \(E = m \cdot c^2\) inspires us to interpret the energy as a two-dimensional oscillation of mass. To assist the reader, we construct a two-piston engine metaphor.

We then adapt the formula for the electromagnetic energy density to calculate the energy densities for the wave function. The results are elegant and intuitive: the energy densities are proportional to the square of the absolute value of the wavefunction and, hence, to the probabilities. Schrödinger’s wave equation may then, effectively, be interpreted as a diffusion equation for energy itself. As an added bonus, concepts such as the Compton scattering radius for a particle and spin angular, as well as the boson-fermion dichotomy can be explained in a fully intuitive way.

Finally, we show the interpretation may lead to a natural explanation of relativistic length contraction.

Of course, such interpretation is also an interpretation of the wavefunction itself, and the immediate reaction of the reader is predictable: the electric and magnetic field vectors are, somehow, to be looked

---

2 Of course, an actual particle is localized in space and can, therefore, not be represented by the elementary wavefunction \(\psi = a \cdot e^{-i\theta} = a \cdot e^{-i(E \cdot t - p \cdot x) / \hbar} = a \cdot (\cos \theta - i \cdot a \cdot \sin \theta)\). We must build a wave packet for that: a sum of wavefunctions, each with its own amplitude \(a_k\) and its own argument \(\theta_k = (E_k \cdot t - p_k \cdot x) / \hbar\). This is dealt with in this paper as part of the discussion on the mathematical and physical interpretation of the normalization condition.

3 The N/kg dimension immediately, and naturally, reduces to the dimension of acceleration \((m/s^2)\), thereby facilitating a direct interpretation in terms of Newton’s force law.

4 In physics, a two-spring metaphor is more common. Hence, the pistons in the author’s perpetuum mobile may be replaced by springs.

5 The author re-derives the equation for the Compton scattering radius in section VIII of the paper, and discusses the boson-fermion dichotomy in section IX.
at as real vectors. In contrast, the real and imaginary components of the wavefunction are not. However, this objection needs to be phrased much more carefully. First, we should not forget that the magnetic force is a pseudovector itself.\textsuperscript{6} Second, a suitable choice of coordinates may make quantum-mechanical rotation matrices irrelevant.\textsuperscript{7}

Therefore, we are of the opinion that this paper may provide some fresh perspective on the question, thereby further exploring Einstein’s basic sentiment in regard to quantum mechanics, which may be summarized as follows: there must be some physical explanation for the calculated probabilities.\textsuperscript{8}

We will, therefore, start with Einstein’s relativistic energy equation ($E = mc^2$) and wonder what it could possibly tell us.

\textsuperscript{6} The magnetic force can be analyzed as a relativistic effect (see Feynman II-13-6), and is definitely a pseudovector: $\mathbf{F} = q(\mathbf{v} \times \mathbf{B})$. However, we may note that the dichotomy between the electric force as a polar vector and the magnetic force as an axial vector disappears in the relativistic four-vector representation of electromagnetism. This observation makes the objection even less relevant.

\textsuperscript{7} For example, when using Schrödinger’s equation in a central field (think of the electron around a proton), the use of polar coordinates is recommended, as it ensures the symmetry of the Hamiltonian under all rotations (see Feynman III-19-3).

\textsuperscript{8} This sentiment is usually summed up in the apocryphal quote: “God does not play dice.” The actual quote comes out of one of Einstein’s private letters to Cornelius Lanczos, another scientist who had also emigrated to the US. The full quote is as follows: “You are the only person I know who has the same attitude towards physics as I have: belief in the comprehension of reality through something basically simple and unified... It seems hard to sneak a look at God’s cards. But that He plays dice and uses 'telepathic' methods... is something that I cannot believe for a single moment.” (Helen Dukas and Banesh Hoffman, \textit{Albert Einstein, the Human Side: New Glimpses from His Archives}, 1979)
I. Energy as a two-dimensional oscillation of mass

The mathematical similarity between the relativistic energy formula, the formula for the total energy of an oscillator, and the kinetic energy of a moving body, is striking, and suggest a more fundamental underlying unity for a geometric or physical interpretation of the formulas:

1. \( E = mc^2 \)
2. \( E = m\omega^2/2 \)
3. \( E = mv^2/2 \)

In these formulas, \( \omega, v \) and \( c \) all describe some velocity.\(^9\) Of course, there is the 1/2 factor in the \( E = m\omega^2/2 \) formula,\(^10\) but that is exactly the point we are going to explore here: can we think of an oscillation in two dimensions, so it stores an amount of energy that is equal to \( E = 2m\cdot\omega^2/2 = m\cdot\omega^2? \)

That is easy enough. Think, for example, of a V-2 engine with the pistons at a 90-degree angle, as illustrated below. The 90° angle makes it possible to perfectly balance the counterweight and the pistons, thereby ensuring smooth travel at all times. With permanently closed valves, the air inside the cylinder compresses and decompresses as the pistons move up and down. It provides, therefore, a restoring force. As such, it will store potential energy, just like a spring. In fact, the motion of the pistons will also reflect that of a mass on a spring: it is described by a sinusoidal function, with the zero point at the center of each cylinder. We can, therefore, think of the moving pistons as harmonic oscillators, just like mechanical springs.\(^11\)

![Figure 1: Oscillations in two dimensions](image)

If we assume there is no friction, we have a perpetuum mobile here. The compressed air and the rotating counterweight (which, combined with the crankshaft, acts as a flywheel) store the potential energy. The moving masses of the pistons store the kinetic energy of the system.\(^12\)

---

\(^9\) Of course, both are different velocities: \( \omega \) is an angular velocity, while \( v \) is a linear velocity: \( \omega \) is measured in radians per second, while \( v \) is measured in meter per second. However, the definition of a radian implies radians are measured in distance units. Hence, the physical dimensions are, effectively, the same. As for the formula for the total energy of an oscillator, we should actually write: \( E = m\cdot a^2\cdot\omega^2/2 \). The additional factor (\( a \)) is the (maximum) amplitude of the oscillator. This factor remains relevant in the analysis. We will further elaborate in the next sections of this paper.

\(^10\) We also have a 1/2 factor in the \( E = mv^2/2 \) formula. Two remarks may be made here. First, it may be noted this is a non-relativistic formula and, more importantly, incorporates kinetic energy only. Using the Lorentz factor (\( \gamma \)), we can write the relativistically correct formula for the kinetic energy as \( K.E. = E - E_0 = m_0c^2 - m_0\nu c^2 = m_0\gamma c^2 - m_0c^2 = m_0c^2(\gamma - 1) \). As for the exclusion of the potential energy, we may note that we may choose our reference point for the potential energy such that the kinetic and potential energy mirror each other. The energy concept that then emerges is the one that is used in the context of the Principle of Least Action: it equals \( E = mv^2 \). This is further explained in Section VII of this paper.

\(^11\) Instead of two cylinders with pistons, one may also think of connecting two springs with a crankshaft.

\(^12\) It is interesting to note that we may look at the energy in the rotating flywheel as potential energy because it is energy that is associated with motion, albeit circular motion. In physics, one will usually associate a rotating object with kinetic energy using the rotational equivalent of mass and linear velocity, i.e. rotational inertia (\( I \)) and angular velocity \( \omega \). The kinetic energy of a rotating object is then given by \( K.E. = (1/2)\cdot I\cdot\omega^2 \).
At this point, it is probably good to briefly review the relevant math. If the magnitude of the oscillation is equal to \( a \), then the motion of the piston (or the mass on a spring) will be described by \( x = a \cdot \cos(\omega \cdot t + \Delta) \). Needles to say, \( \Delta \) is just a phase factor which defines our \( t = 0 \) point, and \( \omega \) is the natural angular frequency of our oscillator. Because of the 90° angle between the two cylinders, \( \Delta \) would be 0 for one oscillator, and \( -\pi/2 \) for the other. Hence, the motion of one piston is given by \( x = a \cdot \cos(\omega \cdot t) \), while the motion of the other is given by \( x = a \cdot \cos(\omega \cdot t - \pi/2) = a \cdot \sin(\omega \cdot t) \).

The kinetic and potential energy of one oscillator – think of one piston or one spring only – can then be calculated as:

1. K.E. = \( T = \frac{1}{2} \cdot m \cdot v^2 = \frac{1}{2} \cdot m \cdot \omega^2 \cdot a^2 \cdot \sin^2(\omega \cdot t + \Delta) \)
2. P.E. = \( U = \frac{1}{2} \cdot k \cdot x^2 = \frac{1}{2} \cdot k \cdot a^2 \cdot \cos^2(\omega \cdot t + \Delta) \)

The coefficient \( k \) in the potential energy formula characterizes the restoring force: \( F = -k \cdot x \). From the dynamics involved, it is obvious that \( k \) must be equal to \( m \cdot \omega^2 \). Hence, the total energy is equal to:

\[
E = T + U = \frac{1}{2} \cdot m \cdot \omega^2 \cdot a^2 \cdot [\sin^2(\omega \cdot t + \Delta) + \cos^2(\omega \cdot t + \Delta)] = m \cdot a^2 \cdot \omega^2 / 2
\]

Hence, adding the energy of the two oscillators, we have a perpetuum mobile storing an energy that is equal to twice this amount: \( E = m \cdot a^2 \cdot \omega^2 \).

We have a great metaphor here. Somehow, in this beautiful interplay between linear and circular motion, energy is borrowed from one place and then returns to the other, cycle after cycle. However, we still have to prove this engine is, effectively, a perpetuum mobile. Let’s do that now.

To facilitate the calculations that follow, we will briefly assume \( k \) and \( a \) are equal to 1. The motion of our first oscillator is given by the \( \cos(\omega \cdot t) = \cos \theta \) function (\( \theta = \omega \cdot t \)), and its kinetic energy will be equal to \( \sin^2 \theta \). Hence, the (instantaneous) change in kinetic energy at any point in time will be equal to:

\[
d(\sin^2 \theta)/d\theta = 2 \cdot \sin \theta \cdot d(\sin \theta)/d\theta = 2 \cdot \sin \theta \cdot \cos \theta
\]

Let us look at the second oscillator now. Just think of the second piston going up and down in the V-2 engine. Its motion is given by the \( \sin \theta \) function, which is equal to \( \cos(\theta - \pi /2) \). Hence, its kinetic energy is equal to \( \sin^2(\theta - \pi /2) \), and how it changes – as a function of \( \theta \) – will be equal to:

\[
2 \cdot \sin(\theta - \pi /2) \cdot \cos(\theta - \pi /2) = -2 \cdot \cos \theta \cdot \sin \theta = -2 \cdot \sin \theta \cdot \cos \theta
\]

We have our perpetuum mobile! While transferring kinetic energy from one piston to the other, the crankshaft will rotate with a constant angular velocity: linear motion becomes circular motion, and vice versa, and the total energy that is stored in the system is \( T + U = m \cdot a^2 \cdot \omega^2 \). As mentioned, we have a great metaphor here. Somehow, in this beautiful interplay between linear and circular motion, energy is borrowed from one place and then returns to the other, cycle after cycle.

We know the wavefunction consist of a sine and a cosine: the cosine is the real component, and the sine is the imaginary component. Could they be equally real? Could each represent half of the total energy of our particle? Should we think of the \( c \) in our \( E = mc^2 \) formula as an angular velocity?

These are sensible questions. Let us explore them.

---

13 Because of the sideways motion of the connecting rods, the sinusoidal function will describe the linear motion only approximately, but the reader can easily imagine the idealized limit situation.
14 Both are independent and, hence, this assumption does not introduce any additional constraint. It is, therefore, not problematic.
II. The wavefunction as a two-dimensional oscillation

The elementary wavefunction is written as:

\[ \psi = a \cdot e^{-i(E \cdot t - p \cdot x)/\hbar} = a \cdot \cos(p \cdot x/\hbar - E \cdot t/\hbar) + i \cdot a \cdot \sin(p \cdot x/\hbar - E \cdot t/\hbar) \]

When considering a particle at rest \((p = 0)\) this reduces to:

\[ \psi = a \cdot e^{-iE \cdot t/\hbar} = a \cdot \cos(-E \cdot t/\hbar) + i \cdot a \cdot \sin(-E \cdot t/\hbar) = a \cdot \cos(E \cdot t/\hbar) - i \cdot a \cdot \sin(E \cdot t/\hbar) \]

Let us remind ourselves of the geometry involved, which is illustrated below. Note that the argument of the wavefunction rotates clockwise with time, while the mathematical convention for measuring the phase angle \((\varphi)\) is counter-clockwise. Of course, we should be suspicious of any suggestion that Nature has a built-in preference for any of our mathematical conventions and we will, therefore, come back to this rather subtle point.\(^{15}\)

**Figure 2:** Euler’s formula

![Euler's formula](image)

If we assume the momentum \(p\) is all in the \(x\)-direction, then the \(p\) and \(x\) vectors will have the same direction, and \(p \cdot x/\hbar\) reduces to \(p \cdot x/\hbar\). Most illustrations – such as the one below – will either freeze \(x\) or, else, \(t\).\(^{16}\) Alternatively, one can google web animations varying both. The point is: we also have a two-dimensional oscillation here. These two dimensions are perpendicular to the direction of propagation of the wavefunction. For example, if the wavefunction propagates in the \(x\)-direction, then the oscillations are along the \(y\)- and \(z\)-axis, which we may refer to as the real and imaginary axis. Note how the phase difference between the cosine and the sine – the real and imaginary part of our wavefunction – appear to give some spin to the whole. We will come back to this.

**Figure 3:** Geometric representation of the wavefunction

\[ \quad \]

\(^{15}\) We leave this to a later section of this paper as we first want to familiarize the reader with the essential geometric characteristics of the wavefunction. The more sophisticated approach will follow later.

\(^{16}\) The illustration freezes \(x\) and, therefore, shows us how the real and imaginary components of \(\psi\) vary in time. Time has one direction only. In contrast, in space, the wave might be left- or right-handed.
Hence, if we would say these oscillations carry half of the total energy of the particle, then we may refer to the real and imaginary energy of the particle respectively, and the interplay between the real and the imaginary part of the wavefunction may then describe how energy propagates through space over time.

Let us consider, once again, a particle at rest. Hence, $p = 0$ and the (elementary) wavefunction reduces to $\psi = ae^{-iE\cdot t/\hbar}$. Hence, the angular velocity of both oscillations, at some point $x$, is given by $\omega = -E/\hbar$. Now, the energy of our particle includes all of the energy – kinetic, potential and rest energy – and is, therefore, equal to $E = mc^2$.

Can we, somehow, relate this to the $m\cdot a^2 \cdot \omega^2$ energy formula for our V-2 perpetuum mobile? Our wavefunction has an amplitude too. Now, if the oscillations of the real and imaginary wavefunction store the energy of our particle, then their amplitude will surely matter. In fact, the energy of an oscillation is, in general, proportional to the square of the amplitude: $E \propto a^2$. We may, therefore, think that the $a^2$ factor in the $E = m\cdot a^2 \cdot \omega^2$ energy will surely be relevant as well.

Importantly, we have an added complication here: an actual particle is localized in space and, therefore, cannot be represented by the elementary wavefunction. We must build a wave packet for that: a sum of wavefunctions, each with their own amplitude $a_i$, and their own $\omega_i = -E_i/\hbar$. Each of these wavefunctions will contribute some energy to the total energy of the wave packet. To calculate the contribution of each wave to the total, both $a_i$ as well as $E_i$ will matter.

What is $E_i$? $E_i$ varies around some average $E$, which we can associate with some average mass $m = E/c^2$. The Uncertainty Principle kicks in here. The analysis becomes more complicated, but a formula such as the one below might make sense:

$$E = \sum m_i \cdot a_i^2 \cdot \omega_i^2 = \sum \frac{E_i}{c^2} \cdot a_i^2 \cdot \frac{E_i^2}{\hbar^2}$$

We can re-write this as:

$$c^2 \hbar^2 = \sum a_i^2 \cdot \frac{E_i^3}{E} \Leftrightarrow c^2 \hbar^2 E = \sum a_i^2 \cdot E_i^3$$

What is the meaning of this equation? We may look at it as some sort of physical normalization condition when building up the Fourier sum. Of course, we should relate this to the mathematical normalization condition for the wavefunction. Our intuition tells us that the probabilities must be related to the energy densities, but how exactly? We will come back to this question in a moment. Let us first think some more about one of the central enigmas in physics: what is mass?

---

17 The value of $c^2 \hbar^2$ is about $1 \times 10^{-51} \text{N} \cdot \text{m}^4$. Let us also do a dimensional analysis: the physical dimensions of the $E = m\cdot a^2 \cdot \omega^2$ equation only make sense if we express $m$ in kg, $a$ in m, and $\omega$ in rad/s. We then get: $[E] = \text{kg} \cdot \text{m}^2 / \text{s}^2 = (\text{N} \cdot \text{s}^2 / \text{m}) \cdot \text{m}^2 / \text{s}^2 = \text{N} \cdot \text{m} = \text{J}$. The dimensions of the left- and right-hand side of this physical normalization condition are equal to $N^3 \cdot \text{m}^5$. 

6
III. Mass as a scalar field

We came up, playfully, with a possibly meaningful interpretation for energy: a two-dimensional oscillation of mass. But what is mass? A new aether theory is not an option, but then what is it that is oscillating? To understand the physics behind equations, it is always good to do an analysis of the physical dimensions in the equation. Let us start with Einstein’s energy equation once again. If we want to look at mass, we should re-write it as $m = E/c^2$:

$$[m] = [E/c^2] = J/(m/s)^2 = N\cdot m^2/s^2 = N\cdot s^2/m = kg$$

This is not very helpful. It only reminds us of Newton’s definition of a mass: mass is that which gets accelerated by a force. At this point, we may want to think of the physical significance of the absolute nature of the speed of light. Einstein’s $E = mc^2$ equation implies we can write the ratio between the energy and the mass of any particle is always the same, so we can write, for example:

$$\frac{E_{\text{electron}}}{m_{\text{electron}}} = \frac{E_{\text{proton}}}{m_{\text{proton}}} = \frac{E_{\text{photon}}}{m_{\text{photon}}} = \frac{E_{\text{any particle}}}{m_{\text{any particle}}} = c^2$$

This reminds us of the $\omega^2 = C^{-1}/L$ or $\omega^2 = k/m$ of harmonic oscillators once again. The key difference is that the $\omega^2 = C^{-1}/L$ and $\omega^2 = k/m$ formulas introduce two or more degrees of freedom. In contrast, $c^2 = E/m$ for any particle, always. However, that is exactly the point: we can modulate the resistance, inductance and capacitance of electric circuits, and the stiffness of springs and the masses we put on them, but we live in one physical space only: our spacetime. Hence, the speed of light $c$ emerges here as the defining property of spacetime – the resonant frequency, so to speak. We have no further degrees of freedom here.

The Planck-Einstein relation (for photons) and the de Broglie equation (for matter-particles) have an interesting feature: both imply that the energy of the oscillation is proportional to the frequency, with Planck’s constant as the constant of proportionality. Now, for one-dimensional oscillations – think of a

---

18 Einstein’s view on aether theories probably still holds true: “We may say that according to the general theory of relativity space is endowed with physical qualities; in this sense, therefore, there exists an aether. According to the general theory of relativity, space without aether is unthinkable – for in such space there not only would be no propagation of light, but also no possibility of existence for standards of space and time (measuring-rods and clocks), nor therefore any space-time intervals in the physical sense. But this aether may not be thought of as endowed with the quality characteristic of ponderable media, as consisting of parts which may be tracked through time. The idea of motion may not be applied to it.” The quote is taken from the Wikipedia article on aether theories, accessed on 22 October 2017. The same article also quotes Robert Laughlin, the 1998 Nobel Laureate in Physics, which said this about aether contemporary theoretical physics: “It is ironic that Einstein’s most creative work, the general theory of relativity, should boil down to conceptualizing space as a medium when his original premise [in special relativity] was that no such medium existed. [...] The word ‘aether’ has extremely negative connotations in theoretical physics because of its past association with relativity. This is unfortunate because, stripped of these connotations, it rather nicely captures the way most physicists actually think about the vacuum. [...] The modern concept of the vacuum of space, confirmed every day by experiment, is a relativistic aether. But we do not call it this because it is taboo.”

19 The $\omega^2 = 1/LC$ formula gives us the natural or resonant frequency for an electric circuit consisting of a resistor ($R$), an inductor ($L$), and a capacitor ($C$). Writing the formula as $\omega^2 = C^{-1}/L$ introduces the concept of elastance, which is the equivalent of the mechanical stiffness ($k$) of a spring.

20 The resistance in an electric circuit introduces a damping factor. When analyzing a mechanical spring, one may also want to introduce a drag coefficient. Both are usually defined as a fraction of the inertia, which is the mass for a spring and the inductance for an electric circuit. Hence, we would write the resistance for a spring as $\gamma m$ and as $R = \gamma L$ respectively.
guitar string, for example – we know the energy will be proportional to the square of the frequency. It is a remarkable observation: the two-dimensional matter-wave, or the electromagnetic wave, gives us two waves for the price of one, so to speak, each carrying half of the total energy of the oscillation but, as a result, we get an $E \propto f$ instead of an $E \propto f^2$ proportionality.

However, such reflections do not answer the fundamental question we started out with: what is mass? At this point, it is hard to go beyond the circular definition that is implied by Einstein’s formula: energy is a two-dimensional oscillation of mass, and mass packs energy, and $c$ emerges us as the property of spacetime that defines how exactly.

When everything is said and done, this does not go beyond stating that mass is some scalar field. Now, a scalar field is, quite simply, some real number that we associate with a position in spacetime. The Higgs field is a scalar field but, of course, the theory behind it goes much beyond stating that we should think of mass as some scalar field. The fundamental question is: why and how does energy, or matter, condense into elementary particles? That is what the Higgs mechanism is about but, as this paper is exploratory only, we cannot even start explaining the basics of it.

What we can do, however, is look at the wave equation again (Schrödinger’s equation), as we can now analyze it as an energy diffusion equation.

---

21 This is a general result and is reflected in the K.E. = $T = (1/2) \cdot m \cdot \omega^2 \cdot a^2 \cdot \sin^2(\omega \cdot t + \Delta)$ and the P.E. = $U = k \cdot x^2 / 2 = (1/2) \cdot m \cdot \omega^2 \cdot a^2 \cdot \cos^2(\omega \cdot t + \Delta)$ formulas for the linear oscillator.
IV. Schrödinger’s equation as an energy diffusion equation

The interpretation of Schrödinger’s equation as a diffusion equation is straightforward. Feynman (Lectures, III-16-1) briefly summarizes it as follows:

“We can think of Schrödinger’s equation as describing the diffusion of the probability amplitude from one point to the next. [...] But the imaginary coefficient in front of the derivative makes the behavior completely different from the ordinary diffusion such as you would have for a gas spreading out along a thin tube. Ordinary diffusion gives rise to real exponential solutions, whereas the solutions of Schrödinger’s equation are complex waves.”

Let us review the basic math. For a particle moving in free space – with no external force fields acting on it – there is no potential \( U = 0 \) and, therefore, the \( U \psi \) term disappears. Therefore, Schrödinger’s equation reduces to:

\[
\frac{\partial \psi(x, t)}{\partial t} = i\left(\frac{1}{2}\frac{\hbar}{m_{\text{eff}}}\right) \nabla^2 \psi(x, t)
\]

The ubiquitous diffusion equation in physics is:

\[
\frac{\partial \phi(x, t)}{\partial t} - D \nabla^2 \phi(x, t)
\]

The structural similarity is obvious. The key difference between both equations is that the wave equation gives us two equations for the price of one. Indeed, because \( \psi \) is a complex-valued function, with a real and an imaginary part, we get the following equations:

1. \( \text{Re}\left(\frac{\partial \psi}{\partial t}\right) = -(1/2)(\hbar/m_{\text{eff}}) \text{Im}(\nabla^2 \psi) \)
2. \( \text{Im}\left(\frac{\partial \psi}{\partial t}\right) = (1/2)(\hbar/m_{\text{eff}}) \text{Re}(\nabla^2 \psi) \)

These equations make us think of the equations for an electromagnetic wave in free space (no stationary charges or currents):

1. \( \frac{\partial \mathbf{B}}{\partial t} = -\nabla \times \mathbf{E} \)
2. \( \frac{\partial \mathbf{E}}{\partial t} = c^2 \nabla \times \mathbf{B} \)

The above equations effectively describe a propagation mechanism in spacetime, as illustrated below.

**Figure 4:** Propagation mechanisms

---

22 Feynman further formalizes this in his *Lecture on Superconductivity* (Feynman, III-21-2), in which he refers to Schrödinger’s equation as the “equation for continuity of probabilities”. The analysis is centered on the *local* conservation of energy, which confirms the interpretation of Schrödinger’s equation as an energy diffusion equation.

23 The \( m_{\text{eff}} \) is the effective mass of the particle, which depends on the medium. For example, an electron traveling in a solid (a transistor, for example) will have a different effective mass than in an atom. In free space, we can drop the subscript and just write \( m_{\text{eff}} = m \). As for the equations, they are easily derived from noting that two complex numbers \( a + i \cdot b \) and \( c + i \cdot d \) are equal if, and only if, their real and imaginary parts are the same. Now, the \( \frac{\partial \psi}{\partial t} = i\left(\frac{\hbar}{m_{\text{eff}}}\right) \nabla^2 \psi \) equation amounts to writing something like this: \( a + i \cdot b = i \cdot (c + i \cdot d) \). Now, remembering that \( i^2 = -1 \), you can easily figure out that \( i \cdot (c + i \cdot d) = i \cdot c + i^2 \cdot d = -d + i \cdot c \).
The Laplacian operator ($\nabla^2$), when operating on a *scalar* quantity, gives us a flux density, i.e. something expressed per square meter ($1/m^2$). In this case, it is operating on $\psi(x, t)$, so what is the dimension of our wavefunction $\psi(x, t)$? To answer that question, we should analyze the diffusion constant in Schrödinger’s equation, i.e. the $(1/2)\cdot(\hbar/m_{\text{eff}})$ factor:

1. *As a mathematical constant of proportionality, it will quantify* the relationship between both derivatives (i.e. the time derivative and the Laplacian);
2. *As a physical constant, it will ensure the physical dimensions* on both sides of the equation are compatible.

Now, the $\hbar/m_{\text{eff}}$ factor is expressed in $(N\cdot m)/(N\cdot s^2/m) = m^2/s$. Hence, it does ensure the dimensions on both sides of the equation are, effectively, the same: $\partial\psi/\partial t$ is a time derivative and, therefore, its dimension is $s^{-1}$ while, as mentioned above, the dimension of $\nabla^2\psi$ is $m^{-2}$. However, this does not solve our basic question: what is the dimension of the real and imaginary part of our wavefunction?

At this point, mainstream physicists will say: it does not have a physical dimension, and there is no geometric interpretation of Schrödinger’s equation. One may argue, effectively, that its argument, $(p\cdot x - E\cdot t)/\hbar$, is just a number and, therefore, that the real and imaginary part of $\psi$ is also just some number.

To this, we may object that $\hbar$ may be looked as a *mathematical* scaling constant only. If we do that, the argument of $\psi$ will, effectively, be expressed in *action* units, i.e. in $N\cdot m\cdot s$. It then does make sense to also associate a physical dimension with the real and imaginary part of $\psi$. What could it be?

We may have a closer look at Maxwell’s equations for inspiration here. The electric field vector is expressed in *newton* (the unit of force) per unit of *charge* (*coulomb*). Now, there is something interesting here. The physical dimension of the magnetic field is $N/C$ divided by $m/s$.** We may write $\textbf{B}$ as the following vector cross-product: $\textbf{B} = (1/c)\cdot \textbf{e}_x \times \textbf{E}$, with $\textbf{e}_x$ the unit vector pointing in the $x$-direction (i.e. the direction of propagation of the wave). Hence, we may associate the $(1/c)\cdot \textbf{e}_x \times$ *operator*, which amounts to a rotation by 90 degrees, with the $s/m$ dimension. Now, multiplication by $i$ also amounts to a rotation by 90° degrees. Hence, we may boldly write: $\textbf{B} = (1/c)\cdot \textbf{e}_x \times \textbf{E} = (1/c)\cdot i \cdot \textbf{E}$. This allows us to also geometrically interpret Schrödinger’s equation in the way we interpreted it above (see Figure 3).**

Still, we have not answered the question as to what the physical dimension of the real and imaginary part of our wavefunction should be. At this point, we may be inspired by the structural similarity between Newton’s and Coulomb’s force laws:

$$F = k_e \frac{q_1 \cdot q_2}{r^2}$$

$$F = G \frac{m_1 \cdot m_2}{r^2}$$

Hence, if the electric field vector $\textbf{E}$ is expressed in force per unit *charge* ($N/C$), then we may want to think of associating the real part of our wavefunction with a force per unit *mass* ($N/kg$). We can, of

---

24 The dimension of $\textbf{B}$ is usually written as $N/(m\cdot A)$, using the SI unit for current, i.e. the *ampere* ($A$). However, $1\ C = 1\ A\cdot s$ and, hence, $1\ N/(m\cdot A) = 1\ (N/C)/(m/s)$.

25 Of course, multiplication by $i$ amounts to a *counterclockwise* rotation. Hence, multiplication by $-i$ also amounts to a rotation by 90 degrees, but *clockwise*. Now, to uniquely identify the clockwise and counterclockwise directions, we need to establish the equivalent of the right-hand rule for a proper geometric interpretation of Schrödinger’s equation in three-dimensional space: if we look at a clock from the back, then its hand will be moving *counterclockwise*. When writing $\textbf{B} = (1/c)\cdot i \cdot \textbf{E}$, we assume we are looking in the *negative* $x$-direction. If we are looking in the positive $x$-direction, we should write: $\textbf{B} = -(1/c)\cdot i \cdot \textbf{E}$. Of course, Nature does not care about our conventions. Hence, both should give the same results in calculations. We will show in a moment they do.
course, do a substitution here, because the mass unit (1 kg) is equivalent to 1 N·s²/m. Hence, our N/kg dimension becomes:

\[ \text{N/kg} = \frac{\text{N}}{(\text{N·s}^2/\text{m})} = \text{m/s}^2 \]

What is this: \( \text{m/s}^2 \)? Is that the dimension of the \( a \cdot \cos \theta \) term in the \( a \cdot e^{-i \theta} = a \cdot \cos \theta - i \cdot a \cdot \sin \theta \) wavefunction? Our answer is: why not? Think of it: \( \text{m/s}^2 \) is the physical dimension of \textit{acceleration}: the increase or decrease in velocity (m/s) per second. It ensures the wavefunction for any particle – matter-particles or particles with zero rest mass (photons) – and the associated wave \textit{equation} (which has to be the same for all, as the spacetime we live in is one) are mutually consistent.

In this regard, we should think of how we would model a \textit{gravitational wave}. The physical dimension would surely be the same: force per mass unit. It all makes sense: wavefunctions may, perhaps, be interpreted as traveling distortions of spacetime, i.e. as tiny gravitational waves.
V. Energy densities and flows

Pursuing the geometric equivalence between the equations for an electromagnetic wave and Schrödinger’s equation, we can now, perhaps, see if there is an equivalent for the energy density. For an electromagnetic wave, we know that the energy density is given by the following formula:

\[ u = \frac{\varepsilon_0}{2} \mathbf{E} \cdot \mathbf{E} + \frac{\varepsilon_0 \cdot c^2}{2} \mathbf{B} \cdot \mathbf{B} \]

\( \mathbf{E} \) and \( \mathbf{B} \) are the electric and magnetic field vector respectively. The Poynting vector will give us the directional energy flux, i.e. the energy flow per unit area per unit time. We write:

\[ \frac{\partial u}{\partial t} = -\nabla \cdot \mathbf{S} \]

Needless to say, the \( \nabla \cdot \) operator is the divergence and, therefore, gives us the magnitude of a (vector) field’s source or sink at a given point. To be precise, the divergence gives us the volume density of the outward flux of a vector field from an infinitesimal volume around a given point. In this case, it gives us the volume density of the flux of \( \mathbf{S} \).

We can analyze the dimensions of the equation for the energy density as follows:

1. \( \mathbf{E} \) is measured in newton per coulomb, so \([\mathbf{E} \cdot \mathbf{E}] = [\mathbf{E}^2] = N^2/C^2\).
2. \( \mathbf{B} \) is measured in (N/C)/(m/s), so we get \([\mathbf{B} \cdot \mathbf{B}] = [\mathbf{B}^2] = (N^2/C^2)\cdot(s^2/m^2)\). However, the dimension of our \( c^2 \) factor is \((m^2/s^2)\) and so we are also left with \( N^2/C^2 \).
3. The \( \varepsilon_0 \) is the electric constant, aka as the vacuum permittivity. As a physical constant, it should ensure the dimensions on both sides of the equation work out, and they do: \([\varepsilon_0] = C^2/(N\cdot m^2)\) and, therefore, if we multiply that with \( N^2/C^2 \), we find that \( u \) is expressed in \( J/m^3 \).\(^{26}\)

Replacing the newton per coulomb unit \((N/C)\) by the newton per kg unit \((N/kg)\) in the formulas above should give us the equivalent of the energy density for the wavefunction. We just need to substitute \( \varepsilon_0 \) for an equivalent constant. We may give it a try. If the energy densities can be calculated – which are also mass densities, obviously – then the probabilities should be proportional to them.

Let us first see what we get for a photon, assuming the electromagnetic wave represents its wavefunction. Substituting \( \mathbf{B} \) for \((1/c) \cdot i\mathbf{E}\) or for \(-(1/c) \cdot i\mathbf{E}\) gives us the following result:

\[ u = \frac{\varepsilon_0}{2} \mathbf{E} \cdot \mathbf{E} + \frac{\varepsilon_0 \cdot c^2}{2} \mathbf{B} \cdot \mathbf{B} = \frac{\varepsilon_0}{2} \mathbf{E} \cdot \mathbf{E} + \frac{\varepsilon_0 \cdot c^2 \cdot i \cdot \mathbf{E} \cdot \mathbf{E}}{c} = \frac{\varepsilon_0}{2} \mathbf{E} \cdot \mathbf{E} - \frac{\varepsilon_0}{2} \mathbf{E} \cdot \mathbf{E} = 0 \]

Zero. An unexpected result? Perhaps not. We have no stationary charges and no currents: only an electromagnetic wave in free space. Hence, the local energy conservation principle needs to be respected at all points in space and in time. The geometry makes sense of the result: for an electromagnetic wave, the magnitudes of \( \mathbf{E} \) and \( \mathbf{B} \) reach their maximum, minimum and zero point simultaneously, as shown below.\(^{27}\) This is because their phase is the same.

---

\(^{26}\) In fact, when multiplying \( C^2/(N\cdot m^2) \) with \( N^2/C^2 \), we get \( N/m^2 \), but we can multiply this with \( 1 = m/m \) to get the desired result. It is significant that an energy density (joule per unit volume) can also be measured in newton (force per unit area).

\(^{27}\) The illustration shows a linearly polarized wave, but the obtained result is general.
Should we expect a similar result for the energy densities that we would associate with the real and imaginary part of the matter-wave? For the matter-wave, we have a phase difference between \( a \cos \theta \) and \( a \sin \theta \), which gives a different picture of the propagation of the wave (see Figure 3).\(^{28}\) In fact, the geometry of the suggestion suggests some inherent spin, which is interesting. We will come back to this. Let us first guess those densities. Making abstraction of any scaling constants, we may write:

\[
u = a^2 (\cos \theta)^2 + a^2 (-i \cdot \sin \theta)^2 = a^2 (\cos^2 \theta + \sin^2 \theta) = a^2
\]

We get what we hoped to get: the absolute square of our amplitude is, effectively, an energy density!

\[
|\psi|^2 = |a \cdot e^{-iE\tau/\hbar}|^2 = a^2 = \nu
\]

This is very deep. A photon has no rest mass, so it borrows and returns energy from empty space as it travels through it. In contrast, a matter-wave carries energy and, therefore, has some (rest) mass. It is therefore associated with an energy density, and this energy density gives us the probabilities. Of course, we need to fine-tune the analysis to account for the fact that we have a wave packet rather than a single wave, but that should be feasible.

As mentioned, the phase difference between the real and imaginary part of our wavefunction (a cosine and a sine function) appear to give some spin to our particle. We do not have this particularity for a photon. Of course, photons are bosons, i.e. spin-zero particles, while elementary matter-particles are fermions with spin-1/2. Hence, our geometric interpretation of the wavefunction suggests that, after all, there may be some more intuitive explanation of the fundamental dichotomy between bosons and fermions, which puzzled even Feynman:

“Why is it that particles with half-integral spin are Fermi particles, whereas particles with integral spin are Bose particles? We apologize for the fact that we cannot give you an elementary explanation. An explanation has been worked out by Pauli from complicated arguments of quantum field theory and relativity. He has shown that the two must necessarily go together, but we have not been able to find a way of reproducing his arguments on an elementary level. It appears to be one of the few places in physics where there is a rule which can be stated very simply, but for which no one has found a simple and easy explanation. The explanation is deep down in relativistic quantum mechanics. This probably means that we do not have a complete understanding of the fundamental principle involved.” (Feynman, Lectures, III-4-1)

The physical interpretation of the wavefunction, as presented here, may provide some better understanding of ‘the fundamental principle involved’: the physical dimension of the oscillation is just very different. That is all: it is force per unit charge for photons, and force per unit mass for matter-particles. We will examine the question of spin somewhat more carefully in section VII. Let us first examine the matter-wave some more.

\(^{28}\) The sine and cosine are essentially the same functions, except for the difference in the phase: \( \sin \theta = \cos(\theta - \pi/2) \).
VI. The de Broglie wavelength and relativistic length contraction

The matter-wave effectively travels through space and time, but what is traveling, exactly? It is the pulse – or the signal – only: the phase velocity of the wave is just a mathematical concept. In fact, because the wave packet consists of elementary waves, even the group velocity – which corresponds to the classical velocity of our particle – is, first and foremost, a mathematical concept only: nothing actually moves with our particle.

Indeed, we do not attempt to answer the question as to what is oscillating up and down and/or sideways: we only associated a physical dimension with the components of the wavefunction – newton per kg (force per unit mass), to be precise. We were inspired to do so because of the physical dimension of the electric and magnetic field vectors (newton per coulomb, i.e. force per unit charge) we associate with electromagnetic waves, which, for all practical purposes, we currently treat as the wavefunction for a photon. This made it possible to calculate the associated energy densities and a Poynting vector for energy dissipation. In addition, we showed that Schrödinger’s equation itself then becomes a diffusion equation for energy. Let us, now, examine the geometry of the elementary wavefunction in more detail.

We will want to focus in particular on the asymmetry which is introduced by the phase difference between the real and the imaginary part of the wavefunction.

Let us, once again, carefully look at the mathematical shape of the elementary wavefunction:

\[ \psi = a \cdot e^{-[E \cdot t - p \cdot x]/\hbar} = a \cdot \cos(p \cdot x/\hbar - E \cdot t/\hbar) + i \cdot a \cdot \sin(p \cdot x/\hbar - E \cdot t/\hbar) \]

The direction of travel – i.e. the direction of propagation of the wavefunction – is perpendicular to the real and imaginary components of the wavefunction. The minus sign in the argument of our sine and cosine function defines the direction of travel: an \( F(x - v \cdot t) \) wavefunction will always describe some wave that is traveling in the positive x-direction (with \( c \) the wave velocity), while an \( F(x + v \cdot t) \) wavefunction will travel in the negative x-direction.

Of course, for a geometric interpretation of the wavefunction in three dimensions, we need to agree on how to define \( i \) or, what amounts to the same, a convention on how to define clockwise and counterclockwise directions: if we look at a clock from the back, then its hand will be moving counterclockwise. So we need to establish the equivalent of the right-hand rule. However, let us not worry about that now. Let us focus on the interpretation. To ease the analysis, we will assume we are looking at a particle at rest. Hence, \( p = 0 \), and the wavefunction reduces to:

\[ \psi = a \cdot e^{-iE \cdot t/\hbar} = a \cdot \cos(-E \cdot t/\hbar) + i \cdot a \cdot \sin(-E_0 \cdot t/\hbar) = a \cdot \cos(E_0 \cdot t/\hbar) - i \cdot a \cdot \sin(E_0 \cdot t/\hbar) \]

\( E_0 \) is, of course, the rest mass of our particle and, now that we are here, we should probably wonder what time \( t \) we are talking about: is it our time, or is the proper time of our particle? It is obvious that, when the particle is at rest, \( t \) is, effectively, the proper time. Hence, we should write it as \( t' \). However, because this may confuse the reader, we will write \( t' \) just as \( t \) for the time being.

---

29 When thinking about the wave nature of elementary particles, the term wavicle comes to mind. Sir Arthur Eddington used this term in his famous book, The Nature of the Physical World, which was written in 1929 – one year after Heisenberg, Born and Schrödinger published the key quantum-mechanical papers, and five years after de Broglie published his thesis on the de Broglie equations. However, academics and physicists have not embraced the term.

30 It is very easy to show how the argument of the wavefunction transforms relativistically. The \( E \) and \( p \) in the argument of the wavefunction \((\Theta = \omega \cdot t - k \cdot x = (E/\hbar) \cdot t - (p/\hbar) \cdot x = (E \cdot t - p \cdot x)/\hbar)\) is, of course, the energy and momentum as the energy and momentum as measured in our frame of reference. Hence, we will want to write
The point to note is that $E_0/h$ pops up as the natural frequency of our matter-particle: $(E_0/h)\cdot t = \omega \cdot t$. Remembering the $\omega = 2\pi f = 2\pi/T$ and $T = 1/f$ formulas (and noting that $h = h/2\pi$), we can write the following:

$$T = 2\pi (h/E_0) = h/E_0 \Leftrightarrow f = E_0/h = m_0c^2/h$$

This is interesting, because we can look at the period as a natural unit of time for our particle.

What about the wavelength? Textbooks will usually distinguish between the group and phase velocity of the wave here. The group velocity ($v_g$) corresponds to the classical velocity of our particle and, hence, should be equal to zero here, because we assume our particle does not move. What about the phase velocity? The phase velocity is given by $v_p = \lambda f = (2\pi/k) \cdot (\omega/2\pi) = \omega/k$. We get a weird result here, because the wavenumber $k = p/h$ is zero (if the particle is at rest, $p = 0$ and, therefore, $k$ must be zero). Hence, we have a division by zero here, which is rather strange. Now, $\omega = E_0/h = m_0c^2/h$ is not zero and, therefore, should we conclude that the phase velocity is infinite here?

What do we get assuming the particle is not at rest? Let us recall the basic wave equations: $E/h = \omega$ gives the frequency in time (expressed in radians per second), while $p/h = k$ gives us the wavenumber, or the frequency in space (expressed in radians per meter). Of course, we may write: $f = \omega/2\pi$ and $\lambda = 2\pi/k$, which gives us the two de Broglie relations:

1. $E = h \cdot \omega = h \cdot f$
2. $p = h \cdot k = h/\lambda$

The frequency in time is easy to interpret. The wavefunction of a particle with more energy, or more mass, will have a higher density in time than a particle with less energy. Of course, relativity comes into play: it will have a higher density in our time: its natural frequency $f_0 = E_0/h = m_0c^2/h$ remains the same. But let us look at the second de Broglie relation. First, we should note it is relevant only in our frame of reference, because the measured momentum is relative to our frame of reference. Having noted this, let us now try to interpret $\lambda$ geometrically.

According to the $p = h/\lambda$ relation, the wavelength is inversely proportional to the momentum: $\lambda = h/p$. For example, the velocity of a photon (which has zero rest mass: $m_0 = 0$), is $c$ and, therefore, we find that $p = m_0v = m_0c = m_0c$ (all of the energy is kinetic). Hence, we can write: $p \cdot c = m_0c^2 = E$, which we may also write as: $E/p = c$. Hence, for a particle with zero rest mass, the wavelength can be written as:

$$\lambda = h/p = h c/E = h m c$$

However, this is a limiting situation – applicable to photons only.\(^3\) Real-life matter-particles should have some mass\(^2\) and, therefore, their velocity will never be $c$.\(^3\)
Hence, if $p$ goes to zero, then the wavelength becomes infinitely long: if $p \to 0$ then $\lambda \to \infty$. How should we interpret this inverse proportionality between $\lambda$ and $p$? To answer this question, let us first see what this wavelength $\lambda$ actually represents.

If we look at the $\psi = a \cdot \cos(p \cdot x/\hbar - E \cdot t/\hbar) - i \cdot a \cdot \sin(p \cdot x/\hbar - E \cdot t/\hbar)$ once more, and if we write $p \cdot x/\hbar$ as $\Delta$, then we can look at $p \cdot x/\hbar$ as a phase factor, and so we will be interested to know for what $x$ this phase factor $\Delta = p \cdot x/\hbar$ will be equal to $2\pi$. So we write:

$$\Delta = p \cdot x/\hbar = 2\pi \iff x = 2\pi \cdot \hbar / p = \hbar / p = \lambda$$

So now we get a meaningful interpretation for that wavelength. It is the distance between the crests (or the troughs) of the wave, so to speak, as illustrated below.\textsuperscript{34}

**Figure 6:** The de Broglie wavelength

Now we know what $\lambda$ actually represent for our one-dimensional elementary wavefunction. Now, the time that is needed for one cycle is equal to $T = 1/f = 2\pi \cdot (\hbar / E)$. Hence, we can now calculate the wave velocity:

$$v = \lambda / T = (\hbar / p) / [2\pi \cdot (\hbar / E)] = E / p$$

Unsurprisingly, we get the phase velocity we get when applying the classical wave equation:

$$v = v_p = \omega / k = E / p$$

If $v = \lambda / T = \omega / k = E / p$ is the phase velocity, can we relate it to the group velocity? Of course, the concept of the group velocity only makes sense in the context of a wave packet. To put it simply, if there is no wave group, then there is no group velocity. Hence, we should, preferably, build a wave packet: a sum of wavefunctions, each with their own amplitude $a_i$ and their own $\omega_i = -E_i / \hbar$. Indeed, in section II, we showed that each of these wavefunctions will contribute some energy to the total energy of the wave packet and that, to calculate the contribution of each wave to the total, both $a_i$ as well as $E_i$ matter.

\textsuperscript{32} Even neutrinos have some (rest) mass. This was first confirmed by the US-Japan Super-Kamiokande collaboration in 1998. Neutrinos oscillate between three so-called flavors: electron neutrinos, muon neutrinos and tau neutrinos. Recent data suggests that the sum of their masses is less than a millionth of the rest mass of an electron. Hence, they propagate at speeds that are very near to the speed of light.

\textsuperscript{33} Using the Lorentz factor ($\gamma$), we can write the relativistically correct formula for the kinetic energy as $KE = E - E_0 = m_0 c^2 - m c^2 = m_0 \gamma c^2 - m_0 c^2 = m_0 c^2 (\gamma - 1)$. As $v$ approaches $c$, $\gamma$ approaches infinity and, therefore, the kinetic energy would become infinite as well.

\textsuperscript{34} Of course, this two-dimensional wave has no real crests or troughs: we measure crests and troughs against the $y$-axis here. Hence, our definition of crests and troughs also depend on the frame of reference.
We can then calculate the group velocity assuming some meaningful *dispersion relation*. We can write this relation as \( \omega = v = \omega(k) \). The group velocity will then be calculated as \( v_g = \frac{\partial \omega}{\partial k} = \frac{\partial (E/\hbar)}{\partial (p/\hbar)} = \frac{\partial (E_i)}{\partial (p_i)} \). It is relatively easy to show that Schrödinger’s equation yields the following dispersion relation:

\[
\omega = \frac{\hbar k^2}{2m}\]

However, we will analyze this relation separately – in the next section – because the derivation is actually not so straightforward as it appears to be. Let us first see where we get when doing some more substitutions. The \( p = m \cdot v = m \cdot c \cdot v \) relation is relativistically correct. We may, therefore, re-write the \( v = v_p \) = \( \omega / k = E / p \) as:

\[
v_p = E / p = m \cdot c^2 / m \cdot v_g = c^2 / v_g = c / \beta
\]

\( \beta = v_g / c \) is, of course, the relative (classical) velocity of our particle \( \beta \). Now, this relation tells us that the *phase* velocities will effectively be superluminal (\( \beta < 1 \) and, therefore, \( 1 / \beta > 1 \)). It also establishes a reciprocal relation between the *relative* phase and group velocity, which we will write as \( \beta_p = v_g / c \) and \( \beta_g = v_g / c \) respectively:

\[
\beta_p = 1 / \beta_g
\]

We may also re-write this as:

\[
v_p \cdot v_g = c^2
\]

This reminds us of the relationship between the electric and magnetic constant \( (1 / \varepsilon_0) \cdot (1 / \mu_0) = c^2 \). This is interesting in light of the fact we can re-write this as \( (c \cdot \varepsilon_0) \cdot (c \cdot \mu_0) = 1 \), which shows electricity and magnetism are just two sides of the same coin, so to speak.\(^{35}\) Likewise, the \( (c \cdot v_p) \cdot (c \cdot v_g) = 1 \) identity also points at an underlying unity which we may not immediately understand – *intuitively*, that is. Indeed, the question is: how do we interpret the math?

The \( v_p \cdot v_g = c^2 \) relation gives a new and interesting perspective to the question of what happens to the phase velocity when \( p \) goes to zero – or, what amounts to the same – if the group velocity goes to zero. Something times zero \( (v_g = 0) \), or something times infinity \( (v_p = \infty) \), cannot be equal to some finite value \( (c^2) \). As such, this relation tells us a *particle is actually never really at rest*.

Such interpretation is consistent with the Uncertainty Principle: if \( \Delta x \cdot \Delta p \geq \hbar \), then *neither \( \Delta x \) nor \( \Delta p \) can be zero*. In other words, the Uncertainty Principle tells us that the idea of some particle *being* at some *specific* point in time and in space is nonsensical: it *has* to move. Hence, it tells us that our concept of dimensionless points in time and space are *mathematical* notions only. *Actual* particles – including photons – are always a bit spread out, so to speak, and – more importantly – they *have to move*.\(^{36}\)

The title of this section is: *the de Broglie wavelength and relativistic length contraction*. We surely spent enough time on the geometric interpretation of the *de Broglie* wavelength now, but how could we possibly relate it to relativistic length contraction? Our intuition here is sketchy, but we hope the reader of this paper may find it interesting enough to further develop it. The idea is the following.

---

\(^{35}\) I must thank a physics blogger for re-writing the \( 1 / (\varepsilon_0 \cdot \mu_0) = c^2 \) equation like this. See: http://reciprocal.systems/phpBB3/viewtopic.php?t=236 (retrieved on 29 September 2017).

\(^{36}\) Again, for a photon, this is self-evident. It has no rest mass, no rest energy, and, therefore, it is going to move at the speed of light itself. We write: \( p = m \cdot c = m \cdot c^2 / c = E / c \). Using the relationship above, we get: \( v_g = \omega / k = \frac{(E/\hbar)}{(p/\hbar)} = E / p = c \Rightarrow v_g = c^2 / v_p = c^2 / c = c \). For a matter-particle, the interpretation is less self-evident.
If the oscillations of the wavefunction pack energy, then the wave train which represents our particle cannot be infinitely long. Why? Because the energy of our particle is finite, and we can, therefore, not have an infinitely long wave train. Hence, if the wave train consists of a more or less precise number of oscillations, then the string of oscillations will be shorter as $\lambda$ decreases. Now, $\lambda$ decreases as the momentum – and, therefore, its classical velocity – increases. Hence, if the velocity of our wavicle increases, it will still pack the same number of oscillations, but each of these oscillations will occupy a smaller space. The wave train will, therefore, be shorter. Hence, the physical interpretation of the wavefunction that is offered in this paper may explain relativistic length contraction.
VII. Schrödinger’s equation, the dispersion relation and the 1/2 factor

Let us re-visit the group velocity. We already mentioned that, if we would want to calculate the group velocity, we must assume that some meaningful $v_g = \partial \omega_i / \partial k_i = \partial (E_i / \hbar) / \partial (p_i / \hbar) = \partial (E_i) / \partial (p_i)$ relation exists. We mentioned such relation could be derived from Schrödinger’s equation. However, the derivation is somewhat less straightforward than casual writers on the topic suggest.

For starters, we must also think about the phase velocities of the component waves: these must, obviously, be the same, as the component waves should all travel at the same phase velocity $v_p = \omega_i / k_i$. This is an interesting constraint, which reinforces the idea of associating the component waves with component magnitudes ($a_i$), component energies ($E_i$) and, finally, component momenta ($p_i$). We will come back to this. Let us first derive the mentioned $\omega = \hbar \cdot k^2 / (2m_{\text{eff}})$ relation.

There is, of course, more than one way to go about it, but one way of doing it is to re-write Schrödinger’s equation as we did, i.e. by distinguishing the real and imaginary parts of the $\partial \psi / \partial t = i \cdot [\hbar / (2m_{\text{eff}})] \cdot \nabla^2 \psi$ wave equation and, hence, re-write it as the following pair of two equations:

1. $\text{Re}(\partial \psi / \partial t) = -[\hbar / (2m_{\text{eff}})] \cdot \text{Im}(\nabla^2 \psi) \iff \omega \cdot \cos(kx - \omega t) = k^2 \cdot [\hbar / (2m_{\text{eff}})] \cdot \cos(kx - \omega t)$
2. $\text{Im}(\partial \psi / \partial t) = [\hbar / (2m_{\text{eff}})] \cdot \text{Re}(\nabla^2 \psi) \iff \omega \cdot \sin(kx - \omega t) = k^2 \cdot [\hbar / (2m_{\text{eff}})] \cdot \sin(kx - \omega t)$

Both equations imply the following dispersion relation:

$$\omega = \hbar \cdot k^2 / (2m_{\text{eff}})$$

Of course, we need to think about the subscripts now: we have $\omega_i$, $k_i$, but... What about $m_{\text{eff}}$ or, dropping the subscript, $m$? Do we write it as $m_i$? If so, what is it? Well... It is the equivalent mass of $E_i$, obviously, and so we get it from the mass-energy equivalence relation: $m_i = E_i / c^2$. It is a fine point, but one most people forget about: they usually just write $m$. However, if there is uncertainty in the energy, then Einstein’s mass-energy relation tells us we must have some uncertainty in the (equivalent) mass too. Here, we should refer back to Section II: $E_i$ varies around some average energy $E$ and, therefore, the Uncertainty Principle kicks in.

The analysis is further complicated by the concept of the effective mass. It is a rather enigmatic concept: it, obviously, depends on the particle itself but, crucially, it also depends on the medium. For example, an electron traveling in a solid (a transistor, for example) will have a different effective mass than in an atom. It is only in free space that we can drop the subscript and simply write: $m_{\text{eff}} = m$. Let us think about these things.

Let us analyze Schrödinger’s equation as a diffusion equation once more. Including potential ($V$), you will usually see it written as:

$$\frac{i \hbar}{\partial t} \psi = -\frac{\hbar^2}{2m_{\text{eff}}} \nabla^2 \psi + V \psi$$

The structural similarity with a physical diffusion equation which, including the flux from some sink or source ($S$), we would generally write as:

$$\frac{\partial \phi}{\partial t} = D \nabla^2 \phi + S$$
At this point, it may be good to remind ourselves of the basics by using the example of the heat diffusion equation which, without a source or sink term, we can write as:\[ k \frac{\partial T}{\partial t} = \kappa \nabla^2 T \]

The constant on the left-hand side \((k)\) is just the (volume) heat capacity of the substance, which is expressed in \(J/(m^3 \cdot K)\). Hence, the dimension of \(k \cdot (\partial T/\partial t)\) is \(J/(m^3 \cdot s)\). On the right-hand side we have the Laplacian again, whose dimension is \(K/m^2\) multiplied by the thermal conductivity \((\kappa)\), whose dimension is \(W/(m \cdot K) = J/(m \cdot s \cdot K)\). Hence, the dimension of the product is the same as the left-hand side: \(J/(m^3 \cdot s)\).

The structural similarities between the wave equations and the (heat) diffusion equation can also be illustrated by writing them in differential form. Indeed, let me first remind you that the \(k \cdot (\partial T/\partial t) = \partial q/\partial t = \kappa \cdot \nabla^2 T\) equation can also be written as:

\[
\frac{\partial q}{\partial t} = -\nabla \cdot \mathbf{h}
\]

This, of course, is entirely similar to the equation for the Poynting vector, which we had introduced in section V.

The \(h\) in the differential heat diffusion equation above is, obviously, not Planck’s constant, but the heat flow vector, i.e. the heat that flows through a unit area in a unit time, and \(h\) is, obviously, equal to \(h = -\kappa \nabla T\). Both equations – regardless in what form we write them (with a \(-\nabla \cdot \mathbf{h}\) term of with the \(\nabla^2 T\) term) – both embody the energy conservation principle.

This paper argues that the similarity between Schrödinger’s equation and the heat diffusion equation is not only structural. There is more to it: both equations model an energy flow in space and in time. This point is easily made for the heat diffusion equation, because the temperature \(T\) is expressed in Kelvin (K), which – as we all know – is a measure of the (average) kinetic energy of the atoms or molecules of the substance involved.

Let us do a similar dimensional analysis of Schrödinger’s equation. To do so, we will re-write it as follows:

\[
\frac{\partial \psi}{\partial t} + \frac{V}{\hbar} \psi = i \frac{\hbar}{2m_{\text{eff}}} \nabla^2 \psi
\]

This looks unfamiliar, but all we did was to divided both sides of the equation by \(i \cdot \hbar\) coefficient to the other side (noting that \(1/i = -i\)), and then we moved the \(- (i/\hbar) \cdot V \cdot \psi\) to the left-hand side of the equation. The physical dimension of the left-hand side of the equation can now be analyzed as follows:

- The \(\partial \psi/\partial t\) term gives us a flow in time: something expressed per second.

---

\[37\] This expression assumes the heat per unit volume \((q)\) is proportional to the temperature \((T)\), which is the case when expressing \(T\) in degrees Kelvin (K), so we can write \(q = k \cdot T\).

\[38\] Needless to say, the J, K, W units stands for joule, Kelvin, and watt respectively.

\[39\] These equations are expressions of Gauss’ flux theorem, which can be expressed both in differential as well as in integral form.

\[40\] The Poynting vector \(S\) is, obviously, not to be confused with the sink (or source) term \(S\) we mentioned previously.

\[41\] The dot in the \(\nabla \cdot\) operator is essential. One should review vector calculus here, if necessary: \(\nabla \cdot\) is the divergence operator.
• The dimension of $V/\hbar$ is $(N\cdot m)/(N\cdot m\cdot s) = 1/s$. Hence, this term also gives us the same $1/s$ dimension. Both terms combined effectively gives us a **flow**: something per second.

On the right-hand side of the equation, we get the following:

• The $\hbar/2m_{\text{eff}}$ factor gives us $(N\cdot m\cdot s)/(N\cdot s^2/m) = m^2/s$.
• The Laplacian ($\nabla^2$) will always gives us some quantity per $m^2$. Both factors combined give us what we wanted to get: something per second on both sides of the equation.

Now, when thinking about Schrödinger’s equation as a diffusion equation, we may want to remind ourselves that a potential is always given in terms of some unit: a unit charge when discussing electromagnetic phenomena and – in our interpretation of the wavefunction – probably something per unit mass. It is, therefore, tempting to bring the $1/m_{\text{eff}}$ to the other side as well. We may also want to re-write $m_{\text{eff}}$ as $E_{\text{eff}}/c^2$. In free space (no potential), Schrödinger’s equation then becomes:

$$E_{\text{eff}} \frac{\partial \psi}{\partial t} = \frac{1}{2} \hbar c^2 \nabla^2 \psi$$

This formulation represents our intuitive interpretation of Schrödinger’s equation as an energy diffusion equation best. Indeed, the product of Planck’s constant ($\hbar$) and the squared velocity of light ($c^2$) appears as a physical proportionality constant: besides ensuring the numbers come out alright, it also ensures the physical dimension of the left- and right-hand side of our equation are the same.

What about the $\frac{1}{2}$ factor? We may want to think $\hbar/2$ is – somehow – more fundamental than $\hbar$, but that is not very satisfactory as an interpretation. To see this, we should just substitute the $a\cdot e^{-i(E/\hbar)\cdot t - p/\hbar \cdot x}/\hbar$ for $\psi$ in the equation and do the calculations:

• $\frac{\partial \psi}{\partial t} = -i a \cdot (E/\hbar) \cdot e^{-i(E/\hbar)\cdot t - (p/\hbar) \cdot x}$
• $\nabla^2 \psi = \partial^2 [a \cdot e^{-i(E/\hbar)\cdot t - (p/\hbar) \cdot x}]/\partial x^2$

Hence, in free space ($E_{\text{eff}} = E = m_{\text{eff}} c^2$), we get the following condition:

$$-i a (E^2/\hbar) e^{-i(E/\hbar)\cdot t - (p/\hbar) \cdot x} = -i a (1/2) \cdot (\hbar c^2) \cdot (p^2/\hbar^2) \cdot e^{-i(E/\hbar)\cdot t - (p/\hbar) \cdot x}$$

The exponentials and the $-i a/\hbar$ coefficients cancel, so this condition becomes:

$$E^2 = \frac{1}{2} p^2 c^2 \iff E = \sqrt{\frac{1}{2} pc}$$

The $\frac{1}{2}$ factor in Schrödinger’s equation gives us a nonsensical relation between energy and momentum. Remember: the energy-momentum relation for a photon – and, we presume, for any particle with zero rest mass – is equal to $E = pc$, or – for particles with a non-zero rest mass:

$$p \cdot c = E \cdot v/c$$

We can only solve the problem by re-defining a **new** effective mass, which should be equal to two times the **old** effective mass. Hence, we write: $m_{\text{eff}}^{\text{NEW}} = 2 \cdot m_{\text{eff}}^{\text{OLD}}$.

We also get a weird energy formula when analyzing the dispersion relation $\omega_i = \hbar \cdot k_i^2/(2m)$:

---

42 Potential energy is energy. We may, therefore, associate it with its N·m dimension.
43 $\psi = \psi(x, y, z, t) = \psi(x, t)$ simplifies to $\psi = \psi(x, t)$ in our one-dimensional analysis. Hence, $\nabla^2 \psi$ reduces to $\partial^2 \psi/\partial x^2$.

44 Note we use the $i^2 = -1$ identity in the derivation of $\nabla^2 \psi$.

45 When substituting $E$ for $mc^2$ and $p$ for $p = mv$, one can easily see this reduces to the definition of momentum: $pc^2 = mc^2 v \iff p = mv$. Hence, this formula is proven easily. For more detail, see, for example, Feynman, I-16-1.
\[ \omega_i = \frac{1}{2} \frac{\hbar \cdot k^2}{m_i} \Rightarrow E_i = \frac{1}{2} \frac{\hbar^2}{m_i} \Rightarrow E_i = \frac{1}{2} \frac{m_i v_i^2}{m_i} \Rightarrow E_i = \frac{1}{2} m_i v_i^2 \Rightarrow c^2 = \frac{1}{2} v_i^2 \]

The energy formula, and its implication \( (c^2 = v_i^2/2) \), does not make much sense – if any at all – and is also inconsistent with the requirement of all component waves having one single phase velocity \( v_p = \omega / k_i = E / p_i \).

We get the same paradoxes when doing some substitutions using the de Broglie relations. Indeed, if we combine both, we also get another another nonsensical formula:

1. \( E = \hbar \cdot f \) and \( p = h / \lambda \). Therefore, \( f = E / h \) and \( \lambda = p / h \).
2. \( v = f \cdot \lambda = (E / h) \cdot (p / h) = E / p \)
3. \( p = m \cdot v \). Therefore, \( E = v \cdot p = m \cdot v^2 \)

\( E = m \cdot v^2 \)? This resembles the \( E = mc^2 \) equation and, therefore, one may be enthused by the discovery, especially because the \( m \cdot v^2 \) also pops up when working with the Least Action Principle in classical mechanics, which states that the path that is followed by a particle will minimize the following integral:

\[ S = \int_{t_1}^{t_2} (KE - PE) \, dt \]

Now, we can choose any reference point for the potential energy but, to reflect the energy conservation law, we can select a reference point that ensures the sum of the kinetic and the potential energy is zero throughout the time interval. If the force field is uniform, then the integrand will, effectively, be equal to \( KE - PE = m \cdot v^2 \).

However, that is classical mechanics and, therefore, not so relevant in the context of the de Broglie equations. The apparent paradox is, obviously, to be solved by distinguishing between the group and the phase velocity of the matter wave. However, the analysis is less straightforward than one might expect, as evidenced by the following remarks.

The \( p = m \cdot v \) is the relativistically correct formula for the momentum of an object if \( v = v_g \), i.e. the group velocity \( (v_g) \) of the wave packet, which corresponds to the classical velocity of our particle. Hence, we can write:

\[ p = m \cdot v_g = (E / c^2) \cdot v_g \Rightarrow v_g = p / m = p \cdot c^2 / E \]

This gives us the relativistic energy-momentum formula we mentioned above: \( p \cdot c = E \cdot v / c \Leftrightarrow p \cdot c^2 / E = v \). It is also just another way of writing the formula we have already derived in our paper: \( v_g = (p / E) \cdot c^2 = c^2 / v_p \) or \( v_g = c^2 / v_p \). Let us substitute this in the formula for the de Broglie wavelength:

\[ \lambda = v_p / f = v_p \cdot T = v_p \cdot (h / E) = (c^2 / v_g) \cdot (h / E) = h / (m \cdot v_g) = h / p \]

This gives us the second de Broglie relation: \( \lambda = h / p \). It is interesting to think about it. The \( f = E / h \) relation is intuitive: higher energy, higher frequency. In contrast, the \( \lambda = h / p \) relation tells us we get an infinitely long wavelength for a stationary particle. As the \( E = m \cdot v^2 \) is only correct if \( v = c \), the \( \lambda = h / p \) relation may describe a photon, or a theoretical massless fermion only. For particles with a non-zero rest mass, the relation may only convey an idea or, at the very least, requires a better definition of the velocity variable.

---

45 We detailed the mathematical framework and detailed calculations in the following online article: https://readingfeynman.org/2017/09/15/the-principle-of-least-action-re-visited.
As we mentioned above, these paradoxes may be solved if we would define a new effective mass, which would be twice the old concept: \( m_{\text{eff}}^{\text{NEW}} = 2 \cdot m_{\text{eff}}^{\text{OLD}} \). Such re-definition would, possibly, be justified by our interpretation of energy as a two-dimensional oscillation of mass but, of course, raises new questions. For starters, we know Schrödinger’s equation – with the \( \frac{\hbar}{2} \) factor – gives us the correct energy levels for the electron orbitals. Hence, we will obviously need a much more thorough justification for our proposed re-definition of the effective mass.

Let us put this rather complicated discussion on group versus phase velocities, and the mysterious \( \frac{\hbar}{2} \) factor, aside to focus on something more obvious. Let us look at the geometry of the situation once more. If you look at the illustrations above, you see we can sort of distinguish (1) a linear velocity – the speed with which those wave crests (or troughs) move – and (2) some kind of circular or tangential velocity – the velocity along the red contour line above. We’ll need the formula for a tangential velocity: \( v_t = a \cdot \omega \).

**Figure 7:** Linear versus circular velocity

Now, if \( \lambda \) is zero, then \( v_t = a \cdot \omega = a \cdot E/\hbar \) is just all there is. We may double-check this as follows: the distance traveled in one period will be equal to \( 2\pi a \), and the period of the oscillation is \( T = 2\pi(\hbar/E) \). Therefore, \( v_t \) will, effectively, be equal to \( v_t = 2\pi a/(2\pi\hbar/E) = a \cdot E/\hbar \).

However, if \( \lambda \) is non-zero, then the distance traveled in one period will be equal to \( 2\pi a + \lambda \). The period remains the same: \( T = 2\pi(\hbar/E) \). Hence, we can write:

\[
v_t = \frac{\Delta s}{\Delta t} = \frac{2\pi a + \lambda}{2\pi\hbar/E} = \frac{2\pi a}{2\pi\hbar/E} + \frac{\lambda}{2\pi\hbar/E} = a \cdot \frac{E}{\hbar} + \frac{E}{p} = v_p + a \cdot \frac{E}{\hbar}
\]

Now, in the next section, we will be calculating a formula for \( a \). In fact, we will find \( a \) is just the (reduced) Compton radius (if we are considering an electron, at least). We will equate an angular momentum formula (for an electron) with the actual \( +\hbar/2 \) or \(-\hbar/2 \) values of its spin and, remarkably, we do get the Compton radius, which is the scattering radius for an electron. Let us write it out:

\[
a^2 \cdot \frac{E^2}{2 \cdot \hbar \cdot c^2} = \frac{\hbar}{2} \Leftrightarrow a^2 = \frac{-\hbar^2 \cdot c^2}{E^2} = \frac{\hbar^2}{m^2 \cdot c^2} \Leftrightarrow a = \frac{\hbar}{m \cdot c}
\]

Substituting the various constants with their numerical values, we find that \( a \) is equal \( 3.8616 \times 10^{-13} \) m. Here, however, we will just want to substitute the formula itself:

\[
v_t = v_p + a \cdot \frac{E}{\hbar} = v_p + \frac{\hbar}{m \cdot c} \cdot \frac{E}{\hbar} = v_p + \frac{mc^2}{m \cdot c} = c + v_p
\]

This is an interesting result. For example, if we substitute \( v_p \) for \( v_p = c^2/v_e \)
Then our formula becomes $v_t = c + v_p = c + c^2/v_g$. When expressing velocities as relative velocities, this formula simplifies to:

$$\beta_t = 1 + \frac{v_p}{c} = 1 + \beta_p = 1 + 1/\beta_g$$

Of course, if $v_p$ is equal to $c$, then we find this tangential velocity is equal to:

$$v_t = 2c$$

Hence, the tangential velocity is twice the linear velocity. Of course, the question is: what is the physical significance of this? Further exploration might yield other fascinating insights. Some of our initial thoughts on this are further elaborated in the next two sections. But what about the paradoxes? What about that $\frac{1}{2}$ factor?

It requires further analysis of how we should build up the Fourier sum. The physical normalization condition we suggested in section II of this paper comes into play. We wrote it as:

$$c^2 \mathbf{h}^2 \mathbf{E} = \sum a_i^2 \cdot E_i^3$$

This equation makes it clear that the energy values $E_i$ are not the only values that matter. The amplitudes $a_i$ – we which we may refer to as the relative contributions to the wave packet – are important too. Hence, further analysis is needed to explain the paradoxes we highlighted and – in the process – that $\frac{1}{2}$ factor we are struggling to understand.\(^\text{46}\)

\(^{46}\) This is the primary area of future research for the author of this paper.
VIII. Explaining spin

The elementary wavefunction vector – i.e. the vector sum of the real and imaginary component – rotates around the x-axis, which gives us the direction of propagation of the wave (see Figure 3). Its magnitude remains constant. In contrast, the magnitude of the electromagnetic vector – defined as the vector sum of the electric and magnetic field vectors – oscillates between zero and some maximum (see Figure 5).

We already mentioned that the rotation of the wavefunction vector appears to give some spin to the particle. Of course, a circularly polarized wave would also appear to have spin (think of the E and B vectors rotating around the direction of propagation - as opposed to oscillating up and down or sideways only). In fact, a circularly polarized light does carry angular momentum, as the equivalent mass of its energy may be thought of as rotating as well. But so here we are looking at a matter-wave.

The basic idea is the following: if we look at $\psi = a \cdot e^{i(Et/h)}$ as some real vector – as a two-dimensional oscillation of mass, to be precise – then we may associate its rotation around the direction of propagation with some torque. The illustration below reminds of the math here.

**Figure 8: Torque and angular momentum vectors**

A torque on some mass about a fixed axis gives it angular momentum, which we can write as the vector cross-product $L = r \times p$ or, perhaps easier for our purposes here as the product of an angular velocity ($\omega$) and rotational inertia (I), aka as the moment of inertia or the angular mass. We write:

$$L = I \omega$$

Note we can write $L$ and $\omega$ in boldface here because they are (axial) vectors. If we consider their magnitudes only, we write $L = I \cdot \omega$ (no boldface). We can now do some calculations. Let us start with the angular velocity. In our previous posts, we showed that the period of the matter-wave is equal to $T = 2\pi(\hbar/E_0)$. Hence, the angular velocity must be equal to:

$$\omega = 2\pi/(2\pi(\hbar/E_0)) = E_0/\hbar$$

We also know the distance $r$, so that is the magnitude of $r$ in the $L = r \times p$ vector cross-product: it is just $a$, so that is the magnitude of $\psi = a \cdot e^{i(Et/h)}$. Now, the momentum ($p$) is the product of a linear velocity ($v$) - in this case, the tangential velocity - and some mass (m): $p = m \cdot v$. If we switch to scalar instead of vector quantities, then the (tangential) velocity is given by $v = r \cdot \omega$. So now we only need to think about what we should use for $m$ or, if we want to work with the angular velocity ($\omega$), the angular mass (I). Here we need to make some assumption about the mass (or energy) distribution. Now, it may or may not sense to assume the energy in the oscillation – and, therefore, the mass – is distributed uniformly. In that case, we may use the formula for the angular mass of a solid cylinder: $I = m \cdot r^2/2$. If we keep the analysis non-relativistic, then $m = m_0$. Of course, the energy-mass equivalence tells us that $m_0 = E_0/c^2$. Hence, this is what we get:
\[ L = I \cdot \omega = (m_0 \cdot r^2 / 2) \cdot (E_0 / \hbar) = (1/2) \cdot a^2 \cdot E_0^2 / (2 \cdot \hbar \cdot c^2) \]

Does it make sense? Maybe. Maybe not. Let us do a dimensional analysis: that won’t check our logic, but it makes sure we made no mistakes when mapping mathematical and physical spaces. We have \( m^3 \cdot J^2 = m^3 \cdot N^2 \cdot m^2 \) in the numerator and \( N \cdot m \cdot s \cdot m^2 / s^2 \) in the denominator. Hence, the dimensions work out: we get \( N \cdot m \cdot s \) as the dimension for \( L \), which is, effectively, the physical dimension of angular momentum. It is also the action dimension, of course, and that cannot be a coincidence. Also note that the \( E = mc^2 \) equation allows us to re-write it as:

\[ L = a^2 \cdot E_0^2 / (2 \cdot \hbar \cdot c^2) \]

Of course, in quantum mechanics, we associate spin with the magnetic moment of a charged particle, not with its mass as such. Is there way to link the formula above to the one we have for the quantum-mechanical angular momentum, which is also measured in \( N \cdot m \cdot s \) units, and which can only take on one of two possible values: \( J = +h/2 \) and \( -h/2 \)? It looks like a long shot, right? How do we go from \( (1/2) \cdot a^2 \cdot m_0^2 / \hbar \) to \( \pm (1/2) \cdot \hbar \)? Let us do a numerical example. The energy of an electron is typically 0.510 MeV \( \approx 8.1871 \times 10^{-14} N \cdot m \), and \( a \)… What value should we take for \( a \)? We have an obvious trio of candidates here: the Bohr radius, the classical electron radius (aka the Thompson scattering length), and the Compton scattering radius.

Let us start with the Bohr radius, so that is about \( 0. \times 10^{-10} N \cdot m \). We get \( L = a^2 \cdot E_0^2 / (2 \cdot \hbar \cdot c^2) = 9.9 \times 10^{-31} N \cdot m \cdot s \). Now that is about \( 1.88 \times 10^4 \) times \( \hbar / 2 \). That is a huge factor. It cannot be right.

Let us try the classical electron radius, which is about \( 2.81 \times 10^{-15} m \). We get an \( L \) that is equal to about \( 2.81 \times 10^{-39} N \cdot m \cdot s \), so now it is a tiny fraction of \( \hbar / 2 \)! This, too, does not work.

Let us use the Compton scattering length, so that is about \( 2.42631 \times 10^{-12} m \). This gives us an \( L \) of \( 2.08 \times 10^{-13} N \cdot m \cdot s \), which is only 20 times \( \hbar \). This is not so bad, but it is good enough?

Let us calculate it the other way around: what value should we take for \( a \) so as to ensure \( L = a^2 \cdot E_0^2 / (2 \cdot \hbar \cdot c^2) = \hbar / 2 \)? Let us write it out:

\[ \frac{a^2 \cdot E_0^2}{2 \cdot \h \cdot c^2} = \frac{\hbar}{2} \iff a^2 = \frac{\hbar^2 \cdot c^2}{E_0^2} \iff a = \frac{\hbar}{m_0 \cdot c} \]

In fact, this is the formula for the so-called reduced Compton wavelength. This is perfect. We found what we wanted to find. Substituting this value for \( a \) (you can calculate it: it is about \( 3.8616 \times 10^{-13} m \)), we get what we should find:

\[ L = \frac{a^2 \cdot E_0^2}{2 \cdot \h \cdot c^2} = \frac{\hbar}{2} = 5.272859 \times 10^{-35} N \cdot m \cdot s \]

This is a rather spectacular result, and one that would – a priori – support the interpretation of the wavefunction that is being suggested in this paper.

Of course, if we can calculate some radius, then we should, perhaps, also try to calculate other dimensions. The appendix to this paper further explores this possibility.\(^{47}\)

\(^{47}\) The analysis is rather primitive because the author limits it to one-dimensional space only. The results, while interesting, are difficult to interpret. They basically present a picture of the elementary wavefunction as an astronomically but finitely long string.
IX. The boson-fermion dichotomy

Let us do some more thinking on the boson-fermion dichotomy. Again, we should remind ourselves that an actual particle is localized in space and that it can, therefore, not be represented by the elementary wavefunction \( \psi = a e^{-i(\text{E}t + \mathbf{p} \cdot \mathbf{x})/\hbar} \) or, for a particle at rest, the \( \psi = a e^{-i\text{E}/\hbar} \) function. We must build a wave packet for that: a sum of wavefunctions, each with their own amplitude \( a_i \) and their own \( \omega_i = -\text{E}/\hbar \). Each of these wavefunctions will contribute some energy to the total energy of the wave packet. Now, we can have another wild but logical theory about this.

Think of the apparent right-handedness of the elementary wavefunction: surely, Nature can’t be bothered about our convention of measuring phase angles clockwise or counterclockwise. Also, the angular momentum can be positive or negative: \( J = +\hbar/2 \) or \(-\hbar/2\). Hence, we would probably like to think that an actual particle - think of an electron, or whatever other particle you’d think of - may consist of right-handed as well as left-handed elementary waves. To be precise, we may think they either consist of (elementary) right-handed waves or, else, of (elementary) left-handed waves. An elementary right-handed wave would be written as:

\[
\psi(\theta) = a_i (\cos \theta, + i \sin \theta)
\]

In contrast, an elementary left-handed wave would be written as:

\[
\psi(\theta) = a_i (\cos \theta, - i \sin \theta)
\]

Both are illustrated below.

**Figure 9: Left- and right-handed matter-wave**

How does that work out with the \( E_0t \) argument of our wavefunction? Position is position, and direction is direction, but time? Time has only one direction, but Nature surely does not care how we count time: counting like 1, 2, 3, etcetera or like \(-1, -2, -3\), etcetera is just the same. If we count like 1, 2, 3, etcetera, then we write our wavefunction like:

\[
\psi = a \cdot \cos(E_0t/\hbar) - i \cdot a \cdot \sin(E_0t/\hbar)
\]

If we count time like \(-1, -2, -3\), etcetera then we write it as:

\[
\psi = a \cdot \cos(-E_0t/\hbar) - i \cdot a \cdot \sin(-E_0t/\hbar) = a \cdot \cos(E_0t/\hbar) + i \cdot a \cdot \sin(E_0t/\hbar)
\]

Hence, it is just like the left- or right-handed circular polarization of an electromagnetic wave: we can have both for the matter-wave too! This, then, should explain why we can have either positive or negative quantum-mechanical spin (+\hbar/2 or \(-\hbar/2\)). It is the usual thing: we have two mathematical possibilities here, and so we must have two physical situations that correspond to it.

It is only natural. If we have left- and right-handed photons - or, generalizing, left- and right-handed bosons - then we should also have left- and right-handed fermions (electrons, protons, etcetera). Back
to the dichotomy. The textbook analysis of the dichotomy between bosons and fermions may be epitomized by Richard Feynman’s Lecture on it (Feynman, III-4), which is confusing and — we would dare to say — even inconsistent: how are photons or electrons supposed to know that they need to interfere with a positive or a negative sign? They are not supposed to know anything: knowledge is part of our interpretation of whatever it is that is going on there.

Hence, it is probably best to keep it simple, and think of the dichotomy in terms of the different physical dimensions of the oscillation: newton per kg versus newton per coulomb. And then, of course, we should also note that matter-particles have a rest mass and, therefore, actually carry charge. Photons do not. But both are two-dimensional oscillations, and the point is: the so-called vacuum — and the rest mass of our particle (which is zero for the photon and non-zero for everything else) — give us the natural frequency for both oscillations, which is beautifully summed up in that remarkable equation for the group and phase velocity of the wavefunction, which applies to photons as well as matter-particles:

\[(v_{\text{phase}}c)(v_{\text{group}}c) = 1 \Leftrightarrow v_p \cdot v_g = c^2\]

The final question then is: why are photons spin-zero particles? Well... We should first remind ourselves of the fact that they do have spin when circularly polarized. Here we may think of the rotation of the equivalent mass of their energy. However, if they are linearly polarized, then there is no spin. Even for circularly polarized waves, the spin angular momentum of photons is a weird concept. If photons have no (rest) mass, then they cannot carry any charge. They should, therefore, not have any magnetic moment. Indeed, what we wrote above shows an explanation of quantum-mechanical spin requires both mass as well as charge.49

---

48 A circularly polarized electromagnetic wave may be analyzed as consisting of two perpendicular electromagnetic plane waves of equal amplitude and 90° difference in phase.

49 Of course, the reader will now wonder: what about neutrons? How to explain neutron spin? Neutrons are neutral. That is correct, but neutrons are not elementary: they consist of (charged) quarks. Hence, neutron spin can (or should) be explained by the spin of the underlying quarks.
X. Concluding remarks

There are, of course, other ways to look at the matter – literally. For example, we can imagine two-dimensional oscillations as *circular* rather than linear oscillations. Think of a tiny ball, whose center of mass stays where it is, as depicted below. Any rotation – around any axis – will be some combination of a rotation around the two other axes. Hence, we may want to think of a two-dimensional oscillation as an oscillation of a polar and azimuthal angle.

**Figure 10:** Two-dimensional *circular* movement

The point of this paper is not to make any definite statements. That would be foolish. Its objective is just to challenge the simplistic mainstream viewpoint on the reality of the wavefunction. Stating that it is a mathematical construct only without physical significance amounts to saying it has no meaning at all. That is, clearly, a non-sustainable proposition.

The interpretation that is offered here looks at amplitude waves as traveling fields. Their physical dimension may be expressed in force per mass unit, as opposed to electromagnetic waves, whose amplitudes are expressed in force per (electric) charge unit. Also, the amplitudes of matter-waves incorporate a phase factor, but this may actually explain the rather enigmatic dichotomy between fermions and bosons and is, therefore, an added bonus.

The interpretation that is offered here has some advantages over other explanations, as it explains the how of diffraction and interference. However, while it offers a great explanation of the wave nature of matter, it does not explain its particle nature: while we think of the energy as being spread out, we will still observe electrons and photons as pointlike particles once they hit the detector. Why is it that a detector can sort of ‘hook’ the whole blob of energy, so to speak?

The interpretation of the wavefunction that is offered here does not explain this. Hence, the *complementarity principle* of the Copenhagen interpretation of the wavefunction surely remains relevant.
Appendix: The elementary wavefunction as a finite string

If we can calculate some radius with this model, then we should also try to calculate other dimensions. The preliminary analysis that is offered here is rather primitive because we limit ourselves to one-dimensional space only. However, the results are encouraging.

The equation for the elementary wavefunction is the usual one:

$$\psi = a \cdot e^{-(E \cdot t - p \cdot x)/\hbar} = a \cdot e^{-(E \cdot t - p \cdot x)/\hbar} = a \cdot \cos(p \cdot x/\hbar - E \cdot t/\hbar) + i \cdot a \cdot \sin(p \cdot x/\hbar - E \cdot t/\hbar)$$

In one-dimensional space (think of a particle traveling along some line), the vectors \(p\) and \(x\) become scalars, and so we simply write:

$$\psi = a \cdot e^{-(E \cdot t - p \cdot x)/\hbar} = a \cdot e^{-(E \cdot t - p \cdot x)/\hbar} = a \cdot \cos(p \cdot x/\hbar - E \cdot t/\hbar) + i \cdot a \cdot \sin(p \cdot x/\hbar - E \cdot t/\hbar)$$

Let us assume our particle is an electron and, as mentioned, we reduced its motion to a one-dimensional motion only: we are thinking of it as traveling along the x-axis. We can then use the y- and z-axes as mathematical axes only; they will show us how the magnitude and direction of the real and imaginary component of \(\psi\). As mentioned in the paper, the wavefunction can be right-handed or left-handed, as shown below.

These wavefunctions come with constant probabilities \(|\psi|^2 = \sigma^2\), so we need to define a space outside of which \(\psi = 0\). This is obvious: oscillations pack energy, and the energy of our particle is finite. Hence, each particle - be it a photon or an electron - will pack a finite number of oscillations. It will, therefore, occupy a finite amount of space. Mathematically, this corresponds to the normalization condition: all probabilities have to add up to one, as illustrated below.

Now, the oscillations of the elementary wavefunction have the same (maximum) amplitude: \(a\). [Terminology is a bit confusing here because we use the term amplitude to refer to two very different things here: we may say \(a\) is the (maximum) amplitude of the (probability) amplitude \(\psi\).] So how many oscillations do we have? If this is a particle in a box, then what is the size of the box?

In our one-dimensional model, this amounts to asking how we can calculate the length of an electron. The question is interesting: we know the frequency (whose order of magnitude is \(10^{15}\) Hz and \(10^{20}\) Hz for...
the photon and the electron respectively) gives us the number of oscillations per second. But how many oscillations do we have in one photon, or in one electron?

Let us first think about photons, because we have more clues here. Photons are emitted by atomic oscillators: atoms going from one state (energy level) to another. We know how to calculate the Q of these atomic oscillators (see, for example, Feynman I-32-3): it is of the order of $10^8$, which means the wave train will last about $10^{-8}$ seconds (to be precise, that is the time it takes for the radiation to die out by a factor $1/e$). Now, the frequency of sodium light, for example, is $0.5 \times 10^{15}$ oscillations per second, and the decay time is about $3.2 \times 10^{-8}$ seconds, so that makes for $(0.5 \times 10^{15}) \cdot (3.2 \times 10^{-8}) = 16$ million oscillations. Now, the wavelength is 600 nanometer $(600 \times 10^{-9})$ m, so that gives us a wave train with a length of $(600 \times 10^{-9}) \cdot (16 \times 10^6) = 9.6$ m.

These oscillations may or may not have the same amplitude and, hence, each of these oscillations may pack a different amount of energies. However, if the total energy of our sodium light photon (i.e. about $2 \text{ eV} = 3.3 \times 10^{-19}$ J) is to be packed in those oscillations, then each oscillation would pack about $2 \times 10^{-26}$ J, on average, that is. We may speculate on how we might imagine the actual wave pulse that atoms emit when going from one energy state to another, but we will not do that here. However, the following illustration of the decay of a transient signal may be useful.

![Oscillation with exponential decay in time.
\[ \tau = \text{how long to die to } 1/e, \text{ about } 37\% \]

The calculation above is interesting, but gives us a paradox: if a photon is a pointlike particle, how can we say its length is like 10 meter or more? Fortunately, relativity theory saves us here. We need to distinguish the reference frame of the photon – riding along the wave as it is being emitted, so to speak – and our stationary reference frame, which is that of the emitting atom. Now, because the photon travels at the speed of light, relativistic length contraction will make it look like a pointlike particle.

What about the electron? Can we use similar assumptions? For the photon, we can use the decay time to calculate the effective number of oscillations. What can we use for an electron? We will need to make some assumption about the phase velocity or, what amounts to the same, the group velocity of the particle. What formulas can we use?

If our particle is at rest, then $p = 0$ and the $p \cdot x / \hbar$ term in our wavefunction vanishes, so the wavefunction reduces to:

$$\psi = a \cdot e^{-iE \cdot t / \hbar} = a \cdot \cos(E \cdot t / \hbar) - i \cdot a \cdot \sin(E \cdot t / \hbar)$$

Hence, our wave does not travel. It has the same amplitude at every point in space at any point in time. Both the phase and group velocity become meaningless concepts. Of course, the amplitude varies – because of the sine and cosine – but the probability remains the same: $|\psi|^2 = a^2$. How can we calculate the size of our box? We may think of the formula we wrote down in our paper (see section II):

$$E = \sum m_i \cdot a_i^2 \cdot \omega_i^2 = \sum \frac{E_i}{c^2} \cdot a_i^2 \cdot \frac{E_i^2}{\hbar^2}$$
This is a physical normalization condition: the energy contributions of the waves that make up a wave packet need to add up to the total energy of our wave. Of course, for our elementary wavefunction here, the subscripts vanish and so the formula reduces to \( E = \frac{(E/c^2) \cdot a^2 \cdot (E^2/h^2)}{c^2} \), out of which we get our formula for the Compton scattering radius: \( a = \frac{\hbar}{mc} \). Now how do we pack that energy in our cylinder? Assuming that energy is distributed uniformly, we are tempted to write something like \( E = a^2 \cdot l \) or, looking at the geometry of the situation, to think of the formula for the volume of a cylinder:

\[
E = \pi \cdot a^2 \cdot l \Leftrightarrow l = \frac{E}{\pi \cdot a^2}
\]

Using the value we got for the Compton scattering radius \( a = 3.8616 \times 10^{-13} \text{ m} \), we find an \( l \) that is equal to \( (8.19 \times 10^{-14})/(\pi \cdot 14.9 \times 10^{-26}) \approx 0.175 \times 10^{12} \text{ m} \). That is - literally - astronomical. It corresponds to 583 light-seconds, or 9.7 light-minutes. So that is about 1.17 times the (average) distance between the Sun and the Earth. Of course, that space is quite large to look for an electron. It just underlines the need to properly build a wave packet by making use of the Uncertainty Principle: paradoxically, the uncertainty in the energy will, effectively, reduce the uncertainty in position.

We may wonder if we could possibly get less astronomical proportions without uncertainty. What if we impose that \( l \) should equal \( a \)? We get the following condition:

\[
\frac{l}{a} = \frac{E}{\pi \cdot a^2} = \frac{m \cdot c^2}{\pi \cdot \hbar^3} = \frac{m^4 \cdot c^5 \cdot \pi \cdot \hbar^3}{m^3 \cdot c^3} \Rightarrow m = \sqrt{\frac{\pi \cdot \hbar^3}{c^5}}
\]

We find that \( m \) would have to be equal to \( m = 1.11 \times 10^{-36} \text{ kg} \). That is tiny. In fact, it is equivalent to an energy of about 0.623 eV (623 meV). This corresponds to light with a wavelength of about 2 \( \mu \text{m} \) (micrometer). That is light in the infrared spectrum. Note the proportionality of the \( l/a \) ratio with \( m^4 \).

However, these manipulations do not tell us much. Should we make a guess at the equivalent of the electricity constant to see whether we get another, perhaps more meaningful, result?

Let us think about the scaling constant: the probabilities will, obviously, not be identical to the energy densities, but proportional. Hence, we need to find the constant of proportionality, i.e. the equivalent of the electric constant \( \varepsilon_0 \) for the energy density formula for the wavefunction. How should we go about this? For inspiration, we may look once again at the structural similarity between Newton’s and Coulomb’s force laws:

\[
F = k_e \frac{q_1 \cdot q_2}{r^2}
\]

\[
F = G \frac{m_1 \cdot m_2}{r^2}
\]

This is what inspired us to analyze the wavefunction as an energy propagation mechanism. Indeed, we associated the components of the wavefunction with a physical dimension (N/kg, i.e. force per unit mass) because we noted the electric and magnetic field vectors were associated with a similar physical dimension (N/C, i.e. force per unit charge). Of course, we duly noted that the mass unit (1 kg) is equivalent to 1 N·s\(^2\)/m and, hence, that our N/kg dimension is actually the dimension of acceleration:

\[
\text{N/kg} = \frac{N}{(N\cdot s^2/m)} = \text{m/s}^2
\]
This, in turn, inspired us to analyze the wavefunction as a gravitational wave. Should we push the comparison further? Coulomb’s constant \( k_e = 1/4\pi\varepsilon_0 \) serves two purposes as a constant of proportionality:

1. As a mathematical constant of proportionality, they give us, effectively a constant of proportionality.
2. As a physical constant, it will ensure the physical dimensions on both sides of the equation are compatible.

The physical dimension of Coulomb’s constant is \( N \cdot m^2/C^2 \). Likewise, the physical dimension of \( G \) is equal to \( N \cdot m^2/kg^2 \). We also know that \( k_e \) is equal to \( 1/4\pi\varepsilon_0 \). The \( 1/4\pi \) factor is, obviously, a geometric factor.

Hence, if we denote the equivalent of \( \varepsilon_0 \) as \( g_0 \), we may, perhaps, write the following:

\[
g_0 \approx \frac{1}{4\pi G} = \frac{1}{4\pi \cdot 6.674 \times 10^{-11}}
\]

We may then guess the following for the energy density:

\[
u = g_0 \frac{a^2}{2} (\cos\theta)^2 + g_0 \frac{a^2}{2} (\sin\theta)^2 = g_0 \frac{a^2}{2} (\cos^2\theta + \sin^2\theta) = g_0 \frac{a^2}{2} = \frac{a^2}{8\pi G}
\]

We calculated a length using the energy density above, and we got a nonsensical result (about \( 0.175 \times 10^{12} \) m). However, that result could, perhaps, be explained because we did not do any thinking about the proportionality coefficient. Would we get a better result with the energy density formula above? Let us see.

Assuming that energy is distributed uniformly, we may use, once again, the formula for the volume of a cylinder. However, this time we will not use the simple \( E = \pi a^2 l \) formula. We will multiply the \( \pi a^2 \) area (or surface) with the energy density \( u \). [This formula may or may not make sense, but the dimensions work out: \( m^2/(N/m^2) \cdot m \) gives us \( N \cdot m \), so we do get the energy dimension out of it.] So let us do a revised calculation:

\[
\Rightarrow l = \frac{m_e \cdot c^2}{\pi a^2 \cdot u} = \frac{m_e \cdot c^2}{\pi a^2 \cdot \frac{a^2}{8\pi G}} = \frac{8 \cdot G \cdot m_e \cdot c^2}{(\frac{\hbar}{m_e c})^4} = \frac{8 \cdot G \cdot m_e^5 \cdot c^6}{h^4}
\]

The numerical result we get is even more astronomical:

\[
l \approx 1.96581 \times 10^{27} \text{ m}.
\]

This value corresponds to 0.2 billion light years. Our interpretation of an elementary particle as some astronomically long – but finite – string obviously needs more analysis. This is, in fact, the primary area of future research for the author of this paper, as it is clearly related to the nitty-gritty of how a wave packet (or a wave train) is to be built from elementary \( \psi(\theta) = a_i (\cos\theta \pm i\sin\theta) \) component waves.

The author welcomes suggestions from more mathematically oriented readers in this regard. Such suggestions and remarks can be sent to his personal e-mail: jeanlouisvanbelle@yahoo.co.uk. If valuable, they will be incorporated and acknowledged in a follow-on article.
References

This paper discusses general principles in physics only. Hence, references can be limited to references to physics textbooks only. For ease of reading, any reference to additional material has been limited to a more popular undergrad textbook that can be consulted online: Feynman’s Lectures on Physics (http://www.feynmanlectures.caltech.edu). References are per volume, per chapter and per section. For example, Feynman III-19-3 refers to Volume III, Chapter 19, Section 3.

All of the illustrations in this paper are open source or have been created by the author.