

# A Classical explanation for the correlation of entangled Quantum particles

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## **Abstract**

Quantum Mechanics claim that particles can become entangled such that there is a correlation in the detected results from EPR type experiments that cannot be explained by Classical Physics. I can show that the result can be fully explained by Classical Physics, and that the correlation curve for different angles between the two detectors can be reproduced when modelled this way.

## **The Explanation**

The following URL is for a Javascript website that allows for different models to be evaluated to try and match the result as measured by Quantum Mechanics:

[http://fmoldove.blogspot.com.au/2013\\_08\\_01\\_archive.html](http://fmoldove.blogspot.com.au/2013_08_01_archive.html)

The following screenshot is from that website, showing the Classical prediction in Blue, and the Quantum Mechanical result in Green:

The goal is to try and match the QM (Green) line.

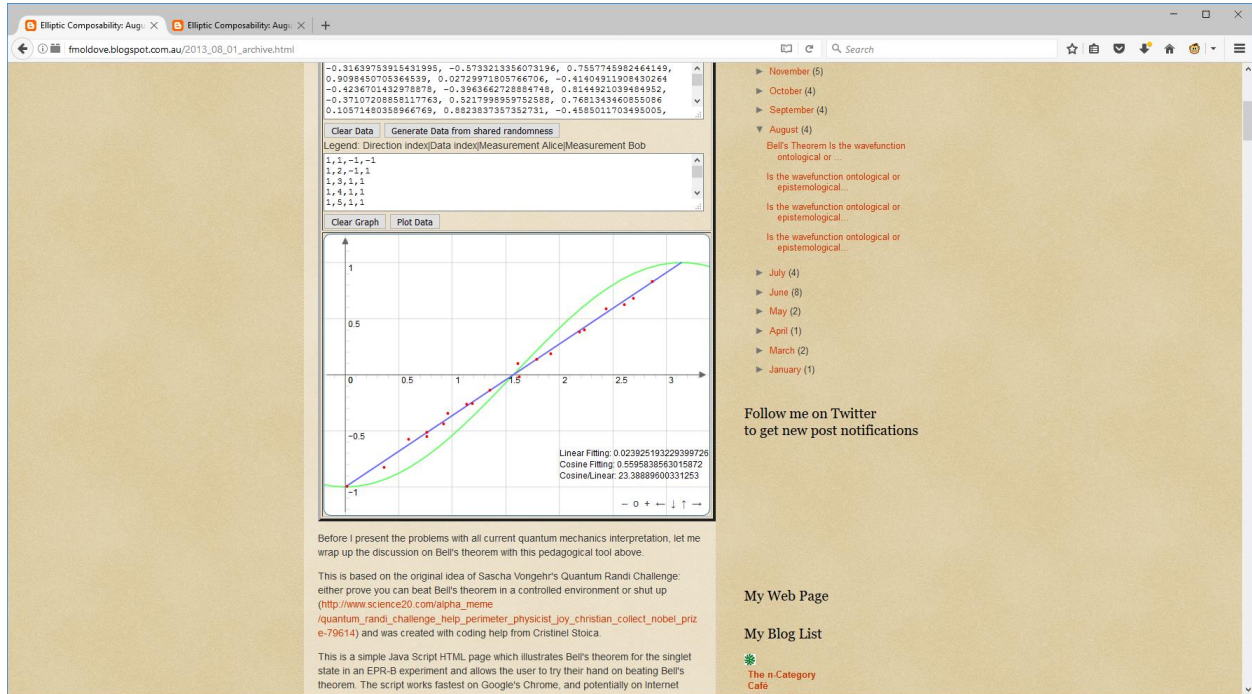


Figure (1).

I can fully explain the QM result using only Classical Physics. The plot below, Figure (2), is generated using my source code (show at the end of this paper in Appendix A) and as you can see, the plotted curve is an exact match of the QM (Green) curve in Figure (1).

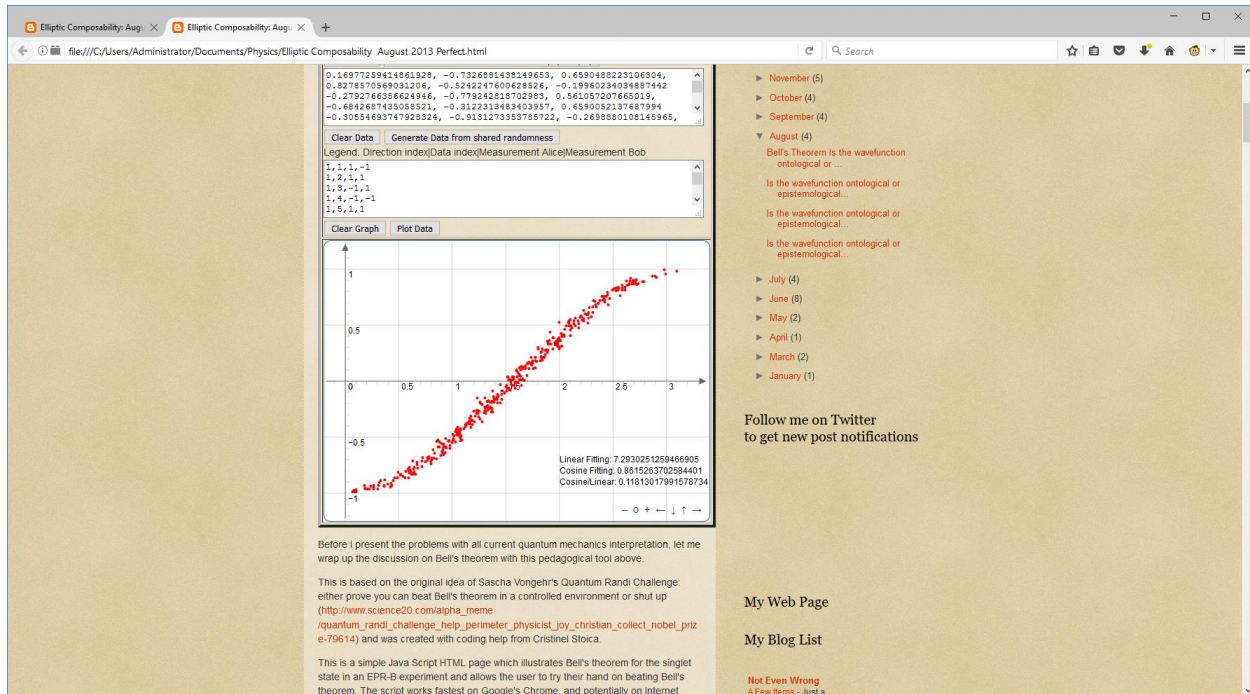


Figure (2).

The explanation for the result is that when the QM particles are incident on the detectors at a very shallow angle ( $\pi/8$  or less), on average only half of the occurrences result in a double detection (that is both detectors registering a result). The other half of the results are discarded as there were not two results recorded. The resulting plot is a record of the recorded measurements from the successful two-reading measurements. In a real experiment, the shallow angles may be more difficult to register detections, and even if the experiment is run for longer at these angles to build up the same number of samples, half of them would have been rejected, leading to the result shown in Figure (2).

Only three sections of code have been modified from the original website code:

- (1) The function: `GenerateAliceOutputFromSharedRandomness()`, to reject half of the very shallow angle incident photons for Alice's detector.
- (2) The function: `GenerateBobOutputFromSharedRandomness ()`, to reject half of the very shallow angle incident photons for Bob's detector.
- (3) A retry of another random photon angle (in function `generateData()` ) if either Alice or Bob do not record a detection.

The changed code is highlighted in Cyan to show the changes I have made to the Javascript.

## **Conclusion**

This result indicates that Classical Physics is being obeyed at all times, and that QM entanglement does not involve "spooky action at a distance" or other mystical communication between the two QM particles.

# Appendix A

//Dot is the scalar product of 2 3D vectors

```
function Dot(a, b)
```

```
{
```

```
    return a[0]*b[0] + a[1]*b[1] + a[2]*b[2];
```

```
};
```

//Norm computes the norm of a 3D vector

```
function GetNorm(vect)
```

```
{
```

```
    return Math.sqrt(Dot(vect, vect));
```

```
};
```

//Normalize generates a unit vector out of a vector

```
function Normalize(vect)
```

```
{
```

```
    //declares the variable
```

```
    var ret = new Array(3);
```

```
    //computes the norm
```

```
    var norm = GetNorm(vect);
```

```
    //scales the vector
```

```
    ret[0] = vect[0]/norm;
```

```
    ret[1] = vect[1]/norm;
```

```
    ret[2] = vect[2]/norm;
```

```
    return ret;
```

```
};

//RandomDirection create a 3D unit vector of random direction
function RandomDirection()
{
    //declares the variable
    var ret = new Array(3);

    //fills a 3D cube with coordinates from -1 to 1 on each direction
    ret[0] = 2*(Math.random()-0.5);
    ret[1] = 2*(Math.random()-0.5);
    ret[2] = 2*(Math.random()-0.5);

    //excludes the points outside of a unit sphere (tries again)
    if(GetNorm(ret) > 1)
        return RandomDirection();

    return Normalize(ret);
};

var generateData = function()
{
    clearBoard();
    clearOutput();
    //gets the data
    var angMom = new Array();
    var t = document.getElementById('in_data').value;
    var data = t.split('\n');
    for (var i=0;i<data.length;i++)
```

```
{  
  
    var vect = data[i].split(',');  
  
    if(vect.length == 3)  
  
        angMom[i] = data[i].split(',');  
  
}  
  
var newTotAngMom = angMom.length;  
  
clearBoard();  
  
var varianceLinear = 0;  
  
var varianceCosine = 0;  
  
var totTestDirs = document.getElementById('totTestDir').value;  
  
var abDirections = new Array();  
var AliceDirections = new Array();  
var BobDirections = new Array();  
var t2 = document.getElementById('in_test').value;  
var data2 = t2.split('\n');  
for (var k = 0; k < data2.length; k++)  
{  
    var vect2 = data2[k].split(',');  
    if (vect2.length == 6)  
    {  
        abDirections[k] = data2[k].split(',');  
        AliceDirections[k] = data2[k].split(',');  
        BobDirections[k] = data2[k].split(',');  
  
        AliceDirections[k][0] = abDirections[k][0];  
    }  
}
```

```

    AliceDirections[k][1] = abDirections[k][1];

    AliceDirections[k][2] = abDirections[k][2];

    BobDirections[k][0] = abDirections[k][3];

    BobDirections[k][1] = abDirections[k][4];

    BobDirections[k][2] = abDirections[k][5];
}
}

```

```

var TempOutput = "";

```

```

var alice_result = 0;

```

```

var bob_result = 0;

```

```

//computes the output

```

```

for(var j=0; j<totTestDirs; j++)

```

```

{

```

```

    var a = AliceDirections[j];

```

```

    var b = BobDirections[j];

```

```

for(var i=0; i<newTotAngMom; i++)

```

```

{

```

```

    angMom[i] = RandomDirection();

```

```

    alice_result = GenerateAliceOutputFromSharedRandomness(a, angMom[i]);

```

```

    bob_result = GenerateBobOutputFromSharedRandomness(b, angMom[i]);

```

```

    if ( (alice_result == 0) || (bob_result == 0) ) {

```

```

        i--;

```

```

        continue;

```

```

    }

```



```

TempOutput = TempOutput + (j+1);

TempOutput = TempOutput + ",";

TempOutput = TempOutput + (i+1);

TempOutput = TempOutput + ",";

TempOutput = TempOutput +
    (alice_result);

TempOutput = TempOutput + ",";

TempOutput = TempOutput +
    (bob_result);

if(i != newTotAngMom-1 || j != totTestDirs-1)
    TempOutput = TempOutput + "\n";
}
}

appendResults(TempOutput);

};

var plotData = function()
{
    clearBoard();

    boardCorrelations.suspendUpdate();

    //gets the data

    var angMom = new Array();

    var t = document.getElementById('in_data').value;

    var data = t.split("\n");

    for (var i=0;i<data.length;i++)
    {
        var vect = data[i].split(',');

```

```

if(vect.length == 3)

angMom[i] = data[i].split(',');

}

var newTotAngMom = angMom.length;

var variancelinear = 0;

var varianceCosine = 0;

var totTestDirs = document.getElementById('totTestDir').value;

//extract directions

var abDirections = new Array();

var AliceDirections = new Array();

var BobDirections = new Array();

var t2 = document.getElementById('in_test').value;

var data2 = t2.split('\n');

for (var k = 0; k < data2.length; k++)
{
    var vect2 = data2[k].split(',');

    if (vect2.length == 6)
    {
        abDirections[k] = data2[k].split(',');

        AliceDirections[k] = data2[k].split(',');

        BobDirections[k] = data2[k].split(',');

        AliceDirections[k][0] = abDirections[k][0];

        AliceDirections[k][1] = abDirections[k][1];

        AliceDirections[k][2] = abDirections[k][2];

        BobDirections[k][0] = abDirections[k][3];
    }
}

```

```

    BobDirections[k][1] = abDirections[k][4];

    BobDirections[k][2] = abDirections[k][5];
}
}

var tempLine = new Array();

var Data_Val = document.getElementById('out_measurements').value;

var data_rows = Data_Val.split('\n');

var directionIndex = 1;

var beginNewDirection = false;

    var a = new Array(3);
a[0] = AliceDirections[0][0];
a[1] = AliceDirections[0][1];
a[2] = AliceDirections[0][2];

    var b = new Array(3);
b[0] = BobDirections[0][0];
b[1] = BobDirections[0][1];
b[2] = BobDirections[0][2];

var sum = 0;

for (var ii=0;ii<data_rows.length;ii++)
{
//parse the input line

var vect = data_rows[ii].split(',');

if(vect.length == 4)

    tempLine = data_rows[ii].split(',');

```

```

//see if a new direction index is starting

if (directionIndex != tempLine[0])
{
beginNewDirection = true;
}

if(!beginNewDirection)
{
var sharedRandomnessIndex = tempLine[1];

var sharedRandomness = angMom[sharedRandomnessIndex];

var aliceOutcome = tempLine[2];

var bobOutcome = tempLine[3];

sum = sum + aliceOutcome*bobOutcome;
}

if (beginNewDirection)
{
//finish computation

var epsilon = sum/newTotAngMom;

var angle = Math.acos(Dot(a, b));

boardCorrelations.createElement('point', [angle,epsilon],{size:0.1,withLabel:false});

var diffLinear = epsilon - (-1+2/Math.PI*angle);

varianceLinear = varianceLinear + diffLinear*diffLinear;

var diffCosine = epsilon + Math.cos(angle);

varianceCosine = varianceCosine + diffCosine*diffCosine;

```

```

//reset and start a new cycle

directionIndex = tempLine[0];

a[0] = AliceDirections[directionIndex-1][0];
a[1] = AliceDirections[directionIndex-1][1];
a[2] = AliceDirections[directionIndex-1][2];
b[0] = BobDirections[directionIndex-1][0];
b[1] = BobDirections[directionIndex-1][1];
b[2] = BobDirections[directionIndex-1][2];

sum = 0;

var sharedRandomnessIndex = tempLine[1];

var sharedRandomness = angMom[sharedRandomnessIndex];

var aliceOutcome = tempLine[2];

var bobOutcome = tempLine[3];

sum = sum + aliceOutcome*bobOutcome;

beginNewDirection = false;
}

}

//finish computation for last element of the loop above

var epsilon = sum/newTotAngMom;

var angle = Math.acos(Dot(a, b));

boardCorrelations.createElement('point', [angle,epsilon],{size:0.1,withLabel:false});

var diffLinear = epsilon - (-1+2/Math.PI*angle);

varianceLinear = varianceLinear + diffLinear*diffLinear;

var diffCosine = epsilon + Math.cos(angle);

varianceCosine = varianceCosine + diffCosine*diffCosine;

```

```

//display total fit

boardCorrelations.createElement('text',[2.0, -0.7, 'Linear Fitting: ' +
varianceLinear,{}]);

boardCorrelations.createElement('text',[2.0, -0.8, 'Cosine Fitting: ' +
varianceCosine,{}]);

boardCorrelations.createElement('text',[2.0, -0.9, 'Cosine/Linear: ' +
varianceCosine/varianceLinear,{}]);

boardCorrelations.unsuspendUpdate();

};

var clearBoard = function()
{
JXG.JSXGraph.freeBoard(boardCorrelations);

boardCorrelations =
JXG.JSXGraph.initBoard('jxgboxCorrelations',{boundingbox:[-0.20, 1.25,
3.4, -1.25],axis:true,

showCopyright:false});

boardCorrelations.create('functiongraph', [function(t){ return
-Math.cos(t); }, -Math.PI*10, Math.PI*10],{strokeColor:

"#66ff66", strokeWidth:2,highlightStrokeColor: "#66ff66",
highlightStrokeWidth:2});

boardCorrelations.create('functiongraph', [function(t){ return
-1+2/Math.PI*t; }, 0, Math.PI],{strokeColor: "#6666ff",

```

```
strokeWidth:2,highlightStrokeColor: "#6666ff", highlightStrokeWidth:2});
```

```
};
```

```
var clearInput = function()
```

```
{
```

```
document.getElementById('in_data').value = "";
```

```
};
```

```
var clearTestDir = function()
```

```
{
```

```
document.getElementById('in_test').value = "";
```

```
};
```

```
var clearOutput = function()
```

```
{
```

```
document.getElementById('out_measurements').value = "";
```

```
};
```

```
var generateTestDir = function()
```

```
{
```

```
clearBoard();
```

```
var totTestDir = document.getElementById('totTestDir').value;
```

```
var testDir = new Array(totTestDir);
```

```
var strData = "";
```

```
for(var i=0; i<totTestDir; i++)
```

```
{
```

```
//first is Alice, second is Bob
```

```
testDir[i] = RandomDirection();
```

```
strData = strData + testDir[i][0] + ", " + testDir[i][1] + ", " +
```

```

testDir[i][2]+ ", " ;

testDir[i] = RandomDirection();

strData = strData + testDir[i][0] + ", " + testDir[i][1] + ", " +
testDir[i][2] + '\n';
}

document.getElementById('in_test').value = strData;

};

var generateRandomData = function()
{
clearBoard();

var totAngMoms = document.getElementById('totAngMom').value;

var angMom = new Array(totAngMoms);

var strData = "";

for(var i=0; i<totAngMoms; i++)
{
angMom[i] = RandomDirection();

strData = strData + angMom[i][0] + ", " + angMom[i][1] + ", " +
angMom[i][2] + '\n';
}

document.getElementById('in_data').value = strData;

};

var apendResults= function(newData)
{
var existingData = document.getElementById('out_measurements').value;

existingData = existingData + newData;
}

```



```
document.getElementById('out_measurements').value = existingData;
```

```
};
```

```
function GenerateAliceOutputFromSharedRandomness(direction, sharedRandomness3DVector) {
```

```
    var dot = Dot(direction, sharedRandomness3DVector);
```

```
    var rand = Math.random();
```

```
    if ((dot > 0) && (rand <= 0.5) && (Math.acos(dot) > Math.PI*(1/2-1/8)) ) return 0;
```

```
    if ((dot <= 0) && (rand <= 0.5) && (Math.acos(dot) < Math.PI*(1/2+1/8)) ) return 0;
```

```
    //replace this with your own function returning +1 or -1
```

```
    if (dot > 0)
```

```
        return +1;
```

```
    else
```

```
        return -1;
```

```
    //}
```

```
};
```

```
function GenerateBobOutputFromSharedRandomness(direction, sharedRandomness3DVector) {
```

```
    var dot = Dot(direction, sharedRandomness3DVector);
```

```
    var rand = Math.random();
```

```
    if ((dot > 0) && (rand <= 0.5) && (Math.acos(dot) > Math.PI*(1/2-1/8)) ) return 0;
```

```
    if ((dot <= 0) && (rand <= 0.5) && (Math.acos(dot) < Math.PI*(1/2+1/8)) ) return 0;
```

```
    //replace this with your own function returning +1 or -1
```

```
    if (dot > 0)
```

```
        return -1;
```

```
    else
        return +1;
//}
};

var boardCorrelations = JXG.JSXGraph.initBoard('jxgboxCorrelations',
{axis:true, boundingbox: [-0.25, 1.25, 3.4, -1.25],
showCopyright:false});

clearBoard();

generateRandomData();

generateTestDir();

generateData();

plotData();
```