

Author:

Ramesh Chandra Bagadi

Data Scientist

INSOFE (International School Of Engineering), Hyderabad, India.

rameshcbagadi@uwalumni.com

+91 9440032711

Technical Note

Abstract

In this research Technical Note the author has presented a novel method of finding a Generalized Similarity Measure between two Vectors or Matrices or Higher Dimensional Data of different sizes.

Theory

Considering two different vectors of different sizes namely

$A_{1 \times m}$ and $B_{1 \times n}$, we first find the Proximity Matrix between elements of the given vectors wherein the Proximity Matrix is given by

$$P_A = \begin{bmatrix} d(1,1) & d(1,2) & d(1,3) & \dots & d(1,(m-1)) & d(1,m) \\ d(2,1) & d(2,2) & d(2,3) & \dots & d(2,(m-1)) & d(2,m) \\ d(3,1) & d(3,2) & d(3,3) & \dots & d(3,(m-1)) & d(3,m) \\ \cdot & \cdot & \cdot & \dots & \cdot & \cdot \\ \cdot & \cdot & \cdot & \dots & \cdot & \cdot \\ \cdot & \cdot & \cdot & \dots & \cdot & \cdot \\ \cdot & \cdot & \cdot & \dots & \cdot & \cdot \\ d((m-1),1) & d((m-1),2) & d((m-1),3) & \dots & d((m-1),(m-1)) & d((m-1),m) \\ d(m,1) & d(m,2) & d(m,3) & \dots & d(m,(m-1)) & d(m,m) \end{bmatrix}$$

and

$$P_B = \begin{bmatrix} d(1,1) & d(1,2) & d(1,3) & \dots & d(1,(n-1)) & d(1,n) \\ d(2,1) & d(2,2) & d(2,3) & \dots & d(2,(n-1)) & d(2,n) \\ d(3,1) & d(3,2) & d(3,3) & \dots & d(3,(n-1)) & d(3,n) \\ \cdot & \cdot & \cdot & \dots & \cdot & \cdot \\ \cdot & \cdot & \cdot & \dots & \cdot & \cdot \\ \cdot & \cdot & \cdot & \dots & \cdot & \cdot \\ \cdot & \cdot & \cdot & \dots & \cdot & \cdot \\ d((n-1),1) & d((n-1),2) & d((n-1),3) & \dots & d((n-1),(n-1)) & d((n-1),n) \\ d(n,1) & d(n,2) & d(n,3) & \dots & d(n,(n-1)) & d(n,n) \end{bmatrix}$$

d indicates the distance measured in some metric (default = Euclidean)

We then find the Norm Of P_A as $\|P_A \cdot P_A\|$. For the Euclidean case, it is given by

$$\|P_A \cdot P_A\| = \sum_{j=1}^m \sum_{i=1}^m P(i, j) \cdot P(i, j). \text{ Also, } m < n. \text{ Similarly, we compute the Norm of } P_B \text{ as } \|P_B \cdot P_B\|$$

. For the Euclidean case, it is given by $\|P_B \cdot P_B\| = \sum_{j=1}^n \sum_{i=1}^n P(i, j) \cdot P(i, j)$. We then find the ratio

$$k_1 = \frac{\|P_B \cdot P_B\|}{\|P_A \cdot P_A\|}. \text{ Similarly, we find another ratio } k_2 = \frac{\|P_B^2 \cdot P_B^2\|}{\|P_A^2 \cdot P_A^2\|} \text{ and so on so forth, till}$$

$$k_n = \frac{\|P_B^{g/2} \cdot P_B^{g/2}\|}{\|P_A^{g/2} \cdot P_A^{g/2}\|} \text{ where } g = 2^n.$$

We also find We now consider a fictitious Vector $A_{B_{1xn}}$, i.e., Vector A in the basis of Vector B, colloquially speaking. Let this be $A_{B_{1xn}} = [c_1 \ c_2 \ c_3 \ \dots \ c_{n-1} \ c_n]$. Now, for this, vector, we

find the Proximity Matrix $P_{A_{B_{1xn}}}$ and now assert that $k_n = \frac{\|P_B^{g/2} \cdot P_B^{g/2}\|}{\|P_{A_{B_{1xn}}}^{g/2} \cdot P_{A_{B_{1xn}}}^{g/2}\|}$. This gives us n

number of equations from which we can solve for elements of $A_{B_{1xn}}$. Now, we can find distance between $A_{B_{1xn}}$ and B_{1xn} and can also consequently find the Similarity co-efficient between them.

We can also, repeat this procedure using the normalized values of the vectors A_{1xm} and B_{1xn} . The motivation to cook this kind of procedure is that Norms are usually invariant under Dimension Upgrading or/ and Downgrading Transformations {Hadamard Theorem}. In the same fashion as detailed above, we can repeat this procedure for Matrices or Higher Dimensional Data of differing sizes.

References

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http://www.vixra.org/author/ramesh_chandra_bagadi