

The physical nature of the basic concepts of physics

3. Work, kinetic energy and Planck's constant (i)

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Abstract

The principle of conservation of 'energy' is the ultimate building stone of physics. The problem is that we don't have a tight description of what 'energy' really is and how and where it is physically stored.

On the basis of the conclusion of my paper Part 2: "The true physical nature of force" in which I have demonstrated that 'force' is a mathematical expression of the rate at which congruent translational motion is transferred, I will in this paper give a real physical definition of the true nature of 'work', which is in the present textbooks mathematically defined as the product of a force and its displacement and of the true physical nature of 'kinetic energy' of a moving body, which is in the present textbooks mathematically defined as the product of its mass times half the square of its velocity.

My clarification of the physical nature of kinetic energy will thereby allow me to unveil the true physical nature of Planck's constant and of the energy of photons.

1. The indistinct nature of the concept of 'energy'

The principle of conservation of 'energy' is the ultimate building stone of physics. It implies the transformation of different forms of 'energy' into one another while the total amount of 'energy' remains constant.

The problem thereby is that, although the textbooks of physics give exact mathematical definitions for the different forms of 'energy' – kinetic energy, potential energy, gravitational energy, electromagnetic energy, field energy, radiant energy, thermal energy, etc. - one cannot find an accurate definition of the physical nature of 'energy' as such.

In fact, most textbooks simply don't give a definition of 'energy' at all, and in those cases that they do, it is rather woolly.

In Wikipedia for instance, 'energy' is defined as "*the ability to do work*".

This 'definition' agrees with the definition of Peter Atkins of the University of Oxford, who writes ^[1] that 'energy' is "*the capacity of a system to do work*". It is however clear that the definition of something as an 'ability', a 'capacity' or a 'potentiality' doesn't exactly tell us what that something is and how it is physically present.

In his "Lectures on Physics" Noble prize winner Richard Feynman blames this vagueness with regard to 'energy' on a fundamental ignorance of its real nature ^[2]: "*It is important to realize that in physics today, we have no knowledge of what energy is. We do not have a picture that energy comes in little blobs of a definite amount. It is not that way. However, there are formulas for calculating some numerical quantity, and when we add it all together it gives always the same number. It is an abstract thing in that it does not tell us the mechanism or the reasons for the various formulas.*"

(i) Updated version of my paper <http://vixra.org/abs/1610.0268>.

In this paper I will reveal the physical nature of kinetic energy and I will give the reasons and the mechanisms for its conservation (ii). To do so we first have to deepen our insight into the laws of motion, making thereby a clear distinction between the real physical data on the one hand and the numerical results of their mathematical processing on the other hand.

2. The vagueness of the present definitions of 'work' and 'kinetic energy'

In my paper part 1 "The true nature of linear momentum", I have demonstrated that Newton's laws of motion lead to the concept of 'the quantity of motion', which is nowadays known as the 'linear momentum' of an object and which is mathematically defined as the product of its mass 'm' and velocity 'v':

$$\mathbf{p} = m\mathbf{v}$$

Another consequence of Newton's laws of motion is the so-called 'moving energy' ^[3] of an object with mass 'm' and speed 'v', which is nowadays called the 'kinetic energy' and mathematically defined as: $K = mv^2/2$

The problem is that this definition of 'kinetic energy' is a purely mathematical definition of which the physical meaning is not as clear as it seems at first sight.

In the present textbooks 'kinetic energy' is physically defined as "*something that an object possesses by virtue of having work done on it*" or as "*the capacity of an object to do work by virtue of its speed*". 'Work' on its turn is defined as "*something that is done on an object by a force as the object is displaced and which is equal to the change of kinetic energy*".

These definitions of 'work' and 'kinetic energy' are, however, mathematical equations in which the mathematical symbols are put into words and that don't give any added value.

They are furthermore based on a circular reasoning, because it follows automatically from the mathematical equation of kinetic energy, that the work done by a force while displacing a body and the transfer of 'kinetic energy' to that body, are just two different expressions of one and the same thing.

$$W = \int \mathbf{F} \cdot d\mathbf{s} = \int m \cdot \mathbf{a} \cdot d\mathbf{s} = \int m \cdot d\mathbf{v} \cdot d\mathbf{s}/dt = \int m \cdot \mathbf{v} \cdot d\mathbf{v} = m \cdot v^2/2 - m \cdot v_0^2/2 = K - K_0 = \Delta K$$

But this still doesn't tell us at all what this 'thing' is and how and where it is physically present. This means that we are turning in circles and that we badly need to clarify these fundamental concepts once and for all.

3. The true nature of 'work' and 'kinetic energy'

3.1 The total amount of momentum flow

In section 3 of my paper Part 2: "The true physical nature of force" I have shown that the momentum flow ' \mathbf{Q}_p ' of a body with mass 'm' and velocity 'v' indicates the amount of linear momentum that moves across a given section per unit time:

$$\mathbf{F} = \mathbf{Q}_p = \mathbf{Q}_m \cdot \mathbf{v} = (m\mathbf{v})/t = (m\mathbf{v})/(L/v) = (m\mathbf{v}/L) \cdot \mathbf{v} = (\mathbf{p}/L) \cdot \mathbf{v}$$

(ii) The physical nature of 'potential' energy will be analyzed in my paper "The physical nature of potential energy".

In this expression the linear momentum per unit time, is expressed as the linear momentum per unit length ' \mathbf{p}/L ', multiplied by the number of unit lengths per unit time ' \mathbf{v} '.

If the momentum flow ' \mathbf{Q}_p ' of a particle system with mass ' m ' with a velocity ' \mathbf{v} ', is equal to linear momentum that is present in a unit length multiplied by its velocity, then the 'total amount (or capacity) of momentum flow' (Q_{pL}) of the whole particle system must be equal to the linear momentum that is present in its whole length ($m\mathbf{v}$) multiplied by its velocity (\mathbf{v}):

$$\mathbf{F} \cdot \mathbf{L} = \mathbf{Q}_p \cdot \mathbf{L} = \mathbf{p} \cdot \mathbf{v} = m \cdot v^2 \quad (\text{expressed in N.m} = \text{J})$$

This means that ' $m\mathbf{v}^2$ ' is a mathematical expression of the total amount of momentum flow of a particle system with mass ' m ' moving with a congruent velocity ' \mathbf{v} '.

This expression corresponds exactly to the specific situation of photons that all move with an invariable speed ' c ', in which case the total amount of (kinetic) energy is identical to the amount of momentum flow, so that we automatically obtain Einstein's mass-energy equation:

$$Q_{pL} = K = mc^2 = E \quad (\text{iii})$$

This demonstrates that the energy of a photon must be physically present as congruent kinetic energy, or in other words as congruent motion (see section 6).

3.2 The total amount of reversibly transferrable momentum flow

The way of transferring momentum flow as described in section 3.1, may be okay for photons with an invariable speed and for perfectly elastic billiard balls, but for real material composite macro structures, the accelerations and the consecutive impulsive forces become much too big and will cause a breakdown of those structures.

In section 5.3 "Driving Force (\mathbf{F}_d)" of my paper Part 2 "The true physical nature of force", I have demonstrated that in order to accelerate real physical structures, we have to use a steady driving force ' \mathbf{F}_d ' that consists of a large number of very small successive impulses that produce a steady transfer of momentum flow ' $\Delta\mathbf{Q}_p$ ', so that the velocity increases gradually from '0' to ' \mathbf{v} ' and the time interval ' t ' necessary to transfer the total momentum ' $m\mathbf{v}$ ' is:

$$t = L/v_{av} = L/(v/2) = 2L/v$$

and the frequency is consequently:

$$v = N/t = Nv/2L$$

so that the driving force is:

$$\mathbf{F}_d = \Delta\mathbf{Q}_p = \Delta\mathbf{p}_1 \cdot v = (m_1 \cdot \mathbf{v})(Nv/2L) = (Nm_1)v^2/2L = m \cdot v^2/2L = \mathbf{Q}_p/2$$

This means that we have to maintain a steady transfer of momentum flow ' $\Delta\mathbf{Q}_M$ ' that is equal to half the momentum flow ' \mathbf{Q}_p ' of that body when it steadily proceeds with that same velocity ' \mathbf{v} '.

The former equation of the driving force can also be written as:

(iii) This will be analyzed in my paper "The physical nature of mass".

$$\mathbf{F}_d = \Delta \mathbf{Q}_p = \Delta \mathbf{p}_1 \cdot v = (m \cdot \Delta v) \cdot (v/2L) = (m \cdot \Delta v / L) \cdot (v/2) = (\Delta \mathbf{p} / L) \cdot v_{av}$$

which allows us to reveal the true physical nature of the 'work' done by a driving force on a free body: If the linear momentum that is reversibly transferred by the particles of a unit length multiplied by their average velocity is equal to the transferred momentum flow ' $\Delta \mathbf{Q}_p$ ', then the linear momentum that is reversibly transferred by the particles of the whole length ' L ' multiplied by their average velocity, is equal to the total amount of momentum flow ($\Delta \mathbf{Q}_{pL}$):

$$\Delta \mathbf{Q}_{pL} = \mathbf{F}_d \cdot L = \Delta \mathbf{Q}_p \cdot L = \Delta \mathbf{p}_1 \cdot v \cdot L = (Nm_1 \cdot \Delta v) \cdot (v/2L)L = (m \cdot \Delta v) \cdot (v/2) = \Delta \mathbf{p} \cdot v_{av}$$

This demonstrates that 'work', which is classically defined as the product of a force and its displacement ($W = \mathbf{F}_d \cdot L$), is in fact a mathematical expression of the total amount of momentum flow ' $\Delta \mathbf{Q}_{pL}$ ' that is reversibly transferred to a free body by a 'force particle system' with a length ' L ' in its direction of motion, can also be expressed as the total amount of transferred linear momentum ($\Delta \mathbf{p} = m \cdot \Delta v$) multiplied by the average velocity level ($v_{av} = v/2$) at which this linear momentum is transferred.

$$W = \Delta \mathbf{Q}_{pL} = \mathbf{F}_d \cdot L = \Delta \mathbf{p} \cdot v_{av} = Q_{pL}/2$$

Which means that the total amount of reversibly transferable momentum flow ' $\Delta \mathbf{Q}_{pL}$ ' is equal to half the total amount/capacity of momentum flow of the moving force particle system ' Q_{pL} '.

It is hereby important to stress the fact that in the classic definition of work, the factor ' L ' stands for the displacement of the force (together with the body), whereas in our physical analysis of work, the factor ' L ' stands for the total active length of the force particle system in its direction of motion.

3.3 The physical nature of work

The true physical meaning of 'work' as the total amount of reversibly transferred momentum flow, can still be revealed more clearly by analyzing the physical meaning of reversibility with regard to the velocity increase. If we want to increase the velocity of a real physical body in a reversible way, we have to do so with the smallest possible increasing momentum quanta. In mathematics these quanta are the so-called 'infinitesimal' velocity increases ' dv ', so that:

$$W = \int \mathbf{F} dL = m \int v dv = mv^2/2$$

When we take this "smallest possible velocity increase" as the natural velocity unit, then we have to fire mass particles with increasing velocity quanta from '1' up to 'v'. It is clear that in this system of extremely small natural velocity quanta, 'v' must represent an incredibly large number.

The total amount of linear momentum (congruent translational motion) that has to be transferred to increase the velocity of the body in a reversible way by means of 'unit' or a 'quantum' velocity increases, from '0' (the initial speed of the body) to 'v' (the final speed of the body), is then equal to the sum of the linear momenta of all the successively fired particles with unit mass and with increasing speeds (Fig. 3.1):

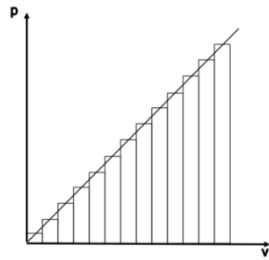


Fig. 3.1

$$\begin{aligned} \Delta p_{\text{tot}} &= m(1 + 2 + 3 + \dots + v) \\ &= m[v(1 + v)/2] \end{aligned}$$

which for $v \gg 1$ gives us:

$$\Delta p_{\text{tot}} = mv^2/2$$

This physical reasoning demonstrates that the numerical value of the performed ‘work’ represents in fact the sum of all the linear momenta at all the intermediary velocity levels.

This definition of ‘work’ corresponds to the thermodynamic generation of work by means of an infinite number of reversible Carnot processes, with infinitesimally increasing temperatures, during which the fluid goes through successive equilibrium states that produce the same amount of work as the real cycle ^[4] (Fig 3.2).

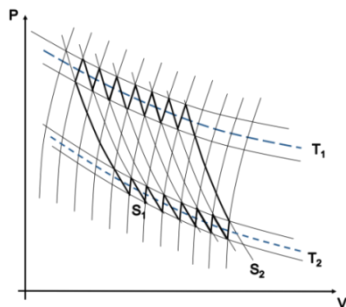


Fig. 3.2

Since I have demonstrated in my paper Part 1 that ‘linear momentum’ is a mathematical expression of the total amount of congruent translational motion, this means that ‘work’ is a mathematical expression of the total amount of reversibly transferred congruent translational motion/velocity in the given reference frame.

In this way we have revealed the true physical nature of ‘work’ as a mathematical expression of the total amount of congruent translational motion that is reversibly transferred between particle systems at different velocity levels in a given reference frame.

From this conclusion follows logically that a ‘constant’ force on a free body means that we have to transmit a steady stream of impulses with increasingly higher velocities in the given reference frame.

3.4 The physical nature of ‘kinetic energy’ of bulk motion

For an initial zero velocity, ' $\Delta\mathbf{v} = \mathbf{v}$ ' so that in that case, the 'work' or i.e. the total amount of reversibly transferred congruent/coherent translational motion is equal to:

$$W = \Delta Q_{pL} = \Delta Q_p \cdot L = \mathbf{F}_d \cdot L = (m \cdot v^2 / 2L) \cdot L = m \cdot v^2 / 2 = Q_{pL} / 2 = \Delta K$$

which is the equation of the 'kinetic energy' of a mass 'm' moving with a speed 'v'. This demonstrates that the 'kinetic energy' of a moving mass is in fact a mathematical expression of its total amount/capacity of reversibly transferable congruent translational motion at a given speed level with regard to any free body that is initially at rest in that same reference frame.

It follows from this that the work 'W' on a body with a mass 'm' that is propelled from a velocity 'v' to a velocity 'v + $\Delta\mathbf{v}$ ' is equal to the difference between of the kinetic energies of this mass at both velocity levels:

$$W = \int m\mathbf{v}d\mathbf{v} = m(\mathbf{v} + \Delta\mathbf{v})^2/2 - mv^2/2 = \Delta K$$

and

$$\Delta K = m(\mathbf{v} + \Delta\mathbf{v})^2/2 - m \cdot v^2/2 = m \cdot \mathbf{v} \cdot \Delta\mathbf{v} + m \cdot \Delta v^2/2 = m \cdot \Delta\mathbf{v}(\mathbf{v} + \Delta\mathbf{v})/2 = m \cdot \Delta\mathbf{v} \cdot \mathbf{v}_{av} = \Delta \mathbf{p} \cdot \mathbf{v}_{av}$$

Which demonstrates that the work done by a driving force on a body that is free to move, and the transfer of kinetic energy to that body while exerting this force, are evidently one and the same thing.

In this way I have revealed that the 'kinetic energy of congruent/bulk motion' of a body with a given velocity is a mathematical expression of its total amount of reversibly transferable congruent/coherent translational motion with regard to any free body that is at rest in the same reference frame.

This definition of the kinetic energy of a moving body is generally considered as a relative datum because it depends on a fortuitously chosen reference frame. But it was already demonstrated in 1669 by Christiaan Huygens ^[5] that this so-called 'relative' velocity in regard to any other physical body in the same reference frame is an absolute, physical datum (iv).

3.5 The direct link between 'force' and 'kinetic energy' of congruent/bulk motion

It follows from the former definitions of kinetic energy of bulk motion that 'force', which is classically defined as the transfer of linear momentum per unit time, can also be defined as the transfer of kinetic energy (or i.e. of the total amount of momentum flow) per running meter:

$$\mathbf{F} = \Delta \mathbf{p} / \Delta t = K / L = Q_{pL} / L = \mathbf{Q}_p$$

As I have mentioned in my paper part 2 'The true nature of force', this direct link between 'force' and 'energy' by means of the concept of momentum flow was already indirectly demonstrated by Andrea diSessa, who proposed in his paper "Momentum flow as an alternative perspective in elementary mechanics" ^[6] to use the notion of 'momentum flow' instead of 'force', because momentum flow analysis provides a better appreciation for the distribution mechanism of the 'forces' in static structures involving real bodies. To

(iv) The nature of velocity will be analyzed in my paper "The physical nature of extent and velocity".

demonstrate this he worked out a number of examples in which he compared momentum flow with 'force' (while holding an apple in one's hand, in a rope pulled by two elephants, in the legs of a racehorse, etc.). But in his last example (E) he comes to a derivation of Bernoulli's law, which as he writes himself, is clearly a question of energy instead of force. This illustrates that the intuitive link between 'force' and 'kinetic energy' that was made by diSessa was an evident link, because from the standpoint of momentum flow, 'force' is nothing else than the transferred (kinetic) energy per running meter.

This similarity between 'force' and 'energy' has however led to a non-proper use of both concepts in the 19th century. The reason therefore is that originally 'mv²' was referred to as the 'living force' (vis-viva) which was widely used by physiologists to explain the motion of biological bodies at that time ^[7]. This explains why the first paper that established the conservation of energy: "*On the quantitative and qualitative determination of forces*", that was published in 1841 by Julius Robert von Mayer, used the word 'force' instead of 'energy' (v). In that same period, Hermann von Helmholtz (1821 – 1894), also used the word 'force' instead of 'energy' in his paper "On the conservation of force", which shows that the two concepts were poorly differentiated at that time.

3.6 The difference between 'kinetic energy of bulk motion' and 'linear momentum'

Already in the Newton's time there was a considerable controversy about the relative significance of the 'quantity of motion' (nowadays called the 'linear momentum') and the quantity then called the "living force" that was related to what we now call 'moving' or 'kinetic' energy ^[8] and the great European physicists, Descartes, Leibnitz and D'Alembert had long discussions ^[9] whether 'kinetic energy' or 'linear momentum' was the true property that is considered by the conservation laws.

My unveiling of the physical nature of 'linear momentum' and 'kinetic energy of bulk motion' allows us to clarify the difference between both physical concepts.

In section 3 of my paper "Part 1: The true nature of linear momentum" I have demonstrated that the conservation of "linear momentum" (or i.e. of the amount of 'congruent' translational motion of a particle system at a given velocity level) is a mathematical expression of the physical fact that the particles of a particle system cannot change their 'congruent' velocity by their own.

This is completely different with the nature of 'kinetic energy' of bulk/congruent motion which is a mathematical expression of the amount of reversible transferrable congruent translational motion between different velocity levels (in a given reference frame).

To demonstrate this, we first consider the case in which we push a free body with mass 'm' gradually from a zero velocity to a velocity ' Δv '. In that case:

- the increase of the linear momentum is equal to the mass times the velocity increase:
 $\mathbf{p} = m \cdot \Delta \mathbf{v}$
- the total transferred momentum at all the intermediary velocity levels or i.e. the increase of kinetic energy, is equal to the transferred linear momentum times the average velocity at which this momentum is transferred:
 $W = Q_{pL} = \mathbf{p} \cdot \mathbf{v}_{av} = (m \cdot \Delta \mathbf{v}) \cdot (\Delta \mathbf{v} / 2) = m \cdot \Delta v^2 / 2$

(v) Julius Robert von Mayer (1814 – 1878) was not taken seriously and his achievements were overlooked and credit was later given to James Joule. Mayer tried to commit suicide in 1850, but permanently lame himself. Later his scientific reputation began to recover and in 1871, he received the Copley Medal of the Royal Society of London for his scientific work.

Then we consider the case in which we push the same body gradually from a velocity ' \mathbf{v} ' to a velocity ' $\mathbf{v} + \Delta\mathbf{v}$ '. In that case:

- the increase of the linear momentum is equal to the mass times the velocity increase:
 $\mathbf{p} = m.\Delta\mathbf{v}$
Which means that the transfer of linear momentum depends only on the increase of the momentum and is independent of the velocity level at which this increase takes place.
- the increase of kinetic energy is then:
 $W = Q_{pL} = \Delta\mathbf{p}.\mathbf{v}_{av} = (m.\Delta\mathbf{v}).[\mathbf{v} + (\mathbf{v} + \Delta\mathbf{v})]/2 = (m.\Delta\mathbf{v}).(\mathbf{v} + \Delta\mathbf{v}/2)$
This equation tells us that in order to give a body with a mass ' m ' and a velocity ' \mathbf{v} ' a velocity increase ' $\Delta\mathbf{v}$ ', we must add a linear momentum ' $m.\Delta\mathbf{v}$ ' at a velocity level ' $\mathbf{v} + \Delta\mathbf{v}/2$ ', so that:
 $W = Q_{pL} = \Delta\mathbf{p}.\mathbf{v}_{av} = m.\Delta\mathbf{v}.\mathbf{v} + m.\Delta\mathbf{v}^2/2$
This equation tells us that in order to increase the velocity of a body in a reversible way, we must first make sure that the force particle system finds itself at the same velocity level as the body. So the first term of this equation represents the amount of linear momentum ' $m.\Delta\mathbf{v}$ ' at the velocity level ' \mathbf{v} ' and the second term represents the momentum flow that corresponds to the transfer of the necessary amount of linear momentum ' $m.\Delta\mathbf{v}$ ' from velocity level ' \mathbf{v} ' to level ' $\mathbf{v} + \Delta\mathbf{v}$ '.

To illustrate this, we take e.g. the case of an object in space with a mass of ' $m = 1000 \text{ kg}$ ' of which we want to increase the speed by ' $\Delta v = 1 \text{ m/s}$ '.

- When the object has a velocity ' $v = 0 \text{ m/s}$ ' with regard to the force particle system:
 - o The momentum increase is equal to $\Delta p = m.\Delta v = 1000 \text{ Ns}$
 - o The total momentum flow or 'work' is equal to
 $W = m.\Delta v^2/2 = 500 \text{ Nm}$
- When the object has a velocity of ' $v = 1 \text{ m/s}$ ' with regard to the force particle system:
 - o The momentum increase is equal to $\Delta p = m.\Delta v = 1000 \text{ Ns}$
 - o The total momentum flow or 'work' is equal to:
 $W = m.v.\Delta v + m.\Delta v^2/2 = 1000 + 500 = 1500 \text{ Nm}$

This confirms our conclusion that the kinetic energy of a material object with regard to another material object depends on its relative velocity with respect to that body, which means that the relative velocity between material bodies is a real, physical characteristic (vi).

4. Kinetic energy of internal motion

The advantage of the concept of kinetic energy is that it is a scalar, which means that its use is not restricted to congruent translational motion, but that it can also be used to characterize rotating or vibrating motion.

Translational motion: $K = mv^2/2$

Rotational motion: $v = R\omega$ so that: $K = mR^2\omega^2/2$

(vi) The nature of velocity will be analyzed in my paper "The physical nature of extent and velocity".

Vibrational motion: $x = x_m \cos(\omega t + \theta)$ and consequently $v = -\omega x_m \sin(\omega t + \theta)$
So that: $K = (m\omega^2/2)x_m^2 \sin^2(\omega t + \theta)$

In the case of inelastic collisions, the motions of the colliding bodies will be scattered over all possible directions, so that the kinetic energies of the colliding particle systems will be transformed into kinetic energy of isotropic/thermal motion or i.e. into 'thermal energy' (vii).

5. The total amount of kinetic energy

In the former section we have seen that kinetic energy is a scalar that characterizes the total amount of reversibly transferable motion between two velocity levels, and that it can also be used to express the total amount of motion of a particle system (its congruent as well as its thermal motion). In that way, the conservation of 'energy' means that the total amount of congruent and internal motion, will be conserved.

6. The physical meaning of Planck's constant

In section 3.2 "The total amount of reversible transferable momentum flow", I have demonstrated that the driving force can be expressed as the transfer of linear momentum per impulse ' Δp_1 ' times the frequency ' ν ' of the impulses:

$$F_d = \Delta Q_p = \Delta p_1 \cdot \nu$$

So that we can write the equation of supplied 'kinetic energy' as:

$$K = F_d \cdot L = (\Delta p_1 \cdot L) \cdot \nu$$

This equation of kinetic energy of particle systems has the same form as Planck's formula for the photon energy:

$$E = h \cdot \nu = (\Delta p_1 \cdot L) \cdot \nu = K$$

Which demonstrates that the energy of photons is physically present under the form of coherent kinetic energy, and that Planck's constant:

$$h = \Delta p_1 \cdot L$$

which means that, since 'h' is a constant, ' $\Delta p_1 \cdot L$ ' must have the same, invariable value for all photons:

For rotational motion:

$$h = \Delta p_1 \cdot R = m \nu R = m R^2 \omega = I \omega = L$$

(vii) This will be analyzed in my paper "The physical nature of pressure, temperature, thermal energy and thermodynamic entropy".

This allows us to unveil the real physical meaning of Planck's constant 'h', as a mathematical expression of the spin angular momentum of photons, which must for all photons have the same invariable value, no matter their frequency (viii): $h = L = 6,63 \cdot 10^{-34} \text{ J}\cdot\text{s}$ and which means that the kinetic energy of a photon is physically present under the form of its rotational/vibrational kinetic energy (ix).

7. Conclusion

On the basis of the conclusion of my paper Part 2: "The true nature of force" in which I have demonstrated that 'force' is a mathematical expression of the rate at which congruent translational motion is transferred, I have in this paper come to the conclusion that 'work', (which is in the present textbooks mathematically defined as the product of a force times its displacement) is a mathematical expression of the total amount of congruent translational velocity/motion that is reversibly transferred between particle systems at different velocity levels in a given reference frame.

In the same way, I have demonstrated that the 'kinetic energy' of a moving body in a given reference frame (which is in the present textbooks mathematically defined as the product of its mass times half the square of its velocity) is a mathematical expression of its total amount of reversibly transferable congruent translational motion in regard to any free body that is at rest in the same reference frame.

And my explanation of the true physical nature of kinetic energy has allowed me, in a natural way, to unveil the true physical nature of the most fundamental concept of quantum physics, namely Planck's constant, as a mathematical expression of the invariable spin angular momentum of photons.

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(viii) The nature of Planck's constant will be further analyzed in my paper "The physical nature of quantum physics".

(ix) The relationship between Einstein's and Planck's energy equations will be analysed in my paper "The physical nature of mass".

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