

Non-stationary helical flows for incompressible 3D Navier-Stokes equations

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In fluid mechanics, a lot of authors have been executing their researches to obtain the analytical solutions of Navier-Stokes equations, even for 3D case of *compressible* gas flow. But there is an essential deficiency of non-stationary solutions indeed.

In our derivation, we explore the case of non-stationary *helical* flow of the Navier-Stokes equations for incompressible fluids at *any* given initial conditions for velocity fields (*it means an open choice for the space part of a solution*).

Such a non-stationary *helical* flow is proved to be decreasing exponentially in regard to the time-parameter, the extent of time-dependent exponential component is given by the coefficient of kinematic viscosity, multiplied by the square of the coefficient of proportionality between the vorticity and velocity field.

Keywords: Navier-Stokes equations, non-stationary helical flow, Arnold-Beltrami-Childress (ABC) flow.

1. Introduction, the Navier-Stokes system of equations.

In accordance with [1-3], the Navier-Stokes system of equations for incompressible flow of Newtonian fluids should be presented in the Cartesian coordinates as below (*under the proper initial conditions*):

$$\nabla \cdot \vec{u} = 0, \quad (1.1)$$

$$\frac{\partial \vec{u}}{\partial t} + (\vec{u} \cdot \nabla) \vec{u} = -\frac{\nabla p}{\rho} + \nu \cdot \nabla^2 \vec{u} + \vec{F}, \quad (1.2)$$

- where \mathbf{u} is the flow velocity, a vector field; ρ is the fluid density, p is the pressure, ν is the kinematic viscosity, and \mathbf{F} represents external force (*per unit of mass in a volume*) acting on the fluid. Let us also choose the Ox axis coincides to the main direction of flow propagation; notation \mathbf{u} or \vec{u} means a vector field.

Besides, we assume here external force \mathbf{F} above to be the force, which has a potential ϕ represented by $\mathbf{F} = -\nabla \phi$.

2. The originating system of PDE for Navier-Stokes Eqs.

Using the identity $(\mathbf{u} \cdot \nabla) \mathbf{u} = (1/2) \nabla(\mathbf{u}^2) - \mathbf{u} \times (\nabla \times \mathbf{u})$, we could present the Navier-Stokes equations (1.1)-(1.2) for incompressible viscous flow $\mathbf{u} = \{u_1, u_2, u_3\}$ as below [4-5]:

$$\nabla \cdot \vec{u} = 0, \quad (2.1)$$

$$\frac{\partial \vec{u}}{\partial t} = \vec{u} \times \vec{w} + \nu \cdot \nabla^2 \vec{u} - \left(\frac{1}{2} \nabla(\vec{u}^2) + \frac{\nabla p}{\rho} + \nabla \phi \right)$$

- here we denote *the curl field* \mathbf{w} , a pseudovector *time-dependent* field [6]; besides, let us denote: $-\{(\nabla p/\rho) + \nabla \phi\} = \{f_x, f_y, f_z\}$.

Vorticity, associated with the curl field, is assumed to be arising due to the proper sources of vorticity in the flow of fluids [4-5]. For example, such a sources could be associated with the solid surface or pressure gradient in case of non-barotropic compressible fluids, influence of viscous forces, Coriolis forces (when one's reference frame is rotating rigidly) or curving shock fronts when speed is supersonic.

3. The presentation of time-dependent solution.

Let us search for solutions of the system (2.1) in a form of *helical* flow below:

$$\vec{w} = \alpha \cdot \vec{u} \Rightarrow \vec{u} \times \vec{w} = \vec{0}, \quad \nabla^2 \vec{u} = \nabla(\nabla \cdot \vec{u}) - \nabla \times (\nabla \times \vec{u}) = -\alpha^2 \cdot \vec{u} \quad (3.1)$$

- here α is the constant coefficient, given by the initial conditions ($\alpha \neq 0$).

Then we should obtain from (2.1) and expression for curl [6] the proper system of PDE:

$$\left\{ \begin{array}{l} \frac{\partial u_1}{\partial t} = -v \cdot \alpha^2 \cdot u_1 - \frac{1}{2} \frac{\partial}{\partial x} (u_1^2 + u_2^2 + u_3^2) + f_x, \\ \frac{\partial u_2}{\partial t} = -v \cdot \alpha^2 \cdot u_2 - \frac{1}{2} \frac{\partial}{\partial y} (u_1^2 + u_2^2 + u_3^2) + f_y, \\ \frac{\partial u_3}{\partial t} = -v \cdot \alpha^2 \cdot u_3 - \frac{1}{2} \frac{\partial}{\partial z} (u_1^2 + u_2^2 + u_3^2) + f_z, \end{array} \right. \quad (3.2)$$

- besides, the continuity equation (1.1) should be satisfied due to the special form (3.1) of helical flow solution. Also taking into consideration the expression for curl [6], we obtain:

$$\{\alpha \cdot u_1, \alpha \cdot u_2, \alpha \cdot u_3\} \equiv \left\{ \left(\frac{\partial u_3}{\partial y} - \frac{\partial u_2}{\partial z} \right), \left(\frac{\partial u_1}{\partial z} - \frac{\partial u_3}{\partial x} \right), \left(\frac{\partial u_2}{\partial x} - \frac{\partial u_1}{\partial y} \right) \right\}.$$

Let us differentiate the 3-rd equation of system (3.2) in regard to variable y , additionally differentiate the 2-nd equation (3.2) in regard to variable z , then subtract it one from each other:

$$\frac{\partial \left(\frac{\partial u_3}{\partial y} - \frac{\partial u_2}{\partial z} \right)}{\partial t} = -v \cdot \alpha^2 \cdot \left(\frac{\partial u_3}{\partial y} - \frac{\partial u_2}{\partial z} \right) + \frac{\partial f_z}{\partial y} - \frac{\partial f_y}{\partial z},$$

- where from expression for curl [6] we determine as

$$\left(\frac{\partial u_3}{\partial y} - \frac{\partial u_2}{\partial z} \right) = \alpha \cdot u_1,$$

- so, each equations of the system (3.2) should be transformed as below

$$\left\{ \begin{array}{l} \alpha \cdot \frac{\partial u_1}{\partial t} = -v \cdot \alpha^3 \cdot u_1 + \frac{\partial f_z}{\partial y} - \frac{\partial f_y}{\partial z}, \\ \alpha \cdot \frac{\partial u_2}{\partial t} = -v \cdot \alpha^3 \cdot u_2 + \frac{\partial f_x}{\partial z} - \frac{\partial f_z}{\partial x}, \\ \alpha \cdot \frac{\partial u_3}{\partial t} = -v \cdot \alpha^3 \cdot u_3 + \frac{\partial f_y}{\partial x} - \frac{\partial f_x}{\partial y}. \end{array} \right. \quad (3.3)$$

System of equations (3.3) could be presented as

$$\alpha \cdot \frac{\partial \vec{u}}{\partial t} = -v \cdot \alpha^3 \cdot \vec{u} + \nabla \times \vec{f},$$

- where

$$\vec{f} = - \left(\frac{\nabla P}{\rho} + \nabla \phi \right),$$

- thus, finally we obtain

$$\alpha \cdot \frac{\partial \vec{u}}{\partial t} = -\nu \cdot \alpha^3 \cdot \vec{u}, \quad \Rightarrow$$

$$\vec{u} = \exp(-\nu \cdot \alpha^2 \cdot t) \cdot \vec{u}(t_0) \quad (3.4)$$

- here $u_1(t_0)$, $u_2(t_0)$, $u_3(t_0)$ are the set of functions, depending on variables $\{x, y, z\}$ (which are given by the initial conditions).

As for the components of pressure gradient field, according to [7] and Eqs. (2.1), it could be presented for such a type of helical flows as below:

$$\left(\frac{1}{2} \nabla(\vec{u}^2) + \frac{\nabla p}{\rho} + \nabla \phi \right) = 0 \quad \Rightarrow \quad \frac{\nabla p}{\rho} = -\exp(-2\nu \cdot \alpha^2 \cdot t) \cdot \frac{1}{2} \nabla(\vec{u}^2(t_0)) - \nabla \phi \quad (3.5)$$

4. Discussion.

There exists a well known helical steady solution, the Arnold-Beltrami-Childres flow [8-9], which is the particular simple case of *helical* flow (3.1). The last is also known as Beltrami flow, i.e. a fluid motion in which the vorticity vector is parallel to the velocity vector at every point of the fluid. For stationary case (3.4), the space part of such an ABC-flow should be presented as below ($A, B, C = \text{const}$):

$$u_1(t_0) = A \sin z + C \cos y, \quad u_2(t_0) = B \sin x + A \cos z, \quad u_3(t_0) = C \sin y + B \cos x \quad (4.1)$$

If we remember the originating of denotation for the components of velocity field:

$$u_1(t_0) = \frac{dx}{dt}, \quad u_2(t_0) = \frac{dy}{dt}, \quad u_3(t_0) = \frac{dz}{dt},$$

- it should yield a system of ordinary differential equations as below

$$\left\{ \begin{array}{l} \frac{d x}{d t} = A \sin z + C \cos y, \\ \frac{d y}{d t} = B \sin x + A \cos z, \\ \frac{d z}{d t} = C \sin y + B \cos x, \end{array} \right. \quad (4.2)$$

- which is proved to have not an analytical solutions, but moreover it reveals a dynamical chaos among the trajectories of appropriate solutions of such a system [8-9].

The ansatz in this derivation let us generalize the idea of extending such a steady helical solutions to the viscous unsteady case at *any* given initial conditions for velocity fields (*it means an open choice for the space part of a solution*); so, it let us obtain for the space part, corresponding to the steady case of ABC-flow (4.1)-(4.2), as below:

$$\left\{ \begin{array}{l} \frac{d x}{d t} = \exp(-\nu \cdot \alpha^2 \cdot t) \cdot (A \sin z + C \cos y), \\ \frac{d y}{d t} = \exp(-\nu \cdot \alpha^2 \cdot t) \cdot (B \sin x + A \cos z), \\ \frac{d z}{d t} = \exp(-\nu \cdot \alpha^2 \cdot t) \cdot (C \sin y + B \cos x), \end{array} \right. \quad (4.3)$$

Should the system (4.3) also yield a dynamical chaos for the trajectories of the non-stationary solutions?

To answer, we should comment first this important particular case, i.e. the Arnold-Beltrami-Childres flow.

The ABC flow, a three-parameter velocity field that provides a simple stationary solution of Euler's equations in three dimensions for incompressible, inviscid fluid flows, can be considered to be a prototype for the study of turbulence - the ABC-flow provides a simple example of dynamical chaos, in spite of the simple analytical expression for each of the components of a solution [8].

In our case (3.4)-(3.5), it means that we need some boundary conditions that preserve helical the solution inside of the limited domain: indeed, the space part of the components of pressure gradient field (3.5) should strongly depend on the space part of the initial conditions for the components (3.4) of velocity $u_1(t_0), u_2(t_0), u_3(t_0)$.

Nevertheless, the possible existence of a dynamical chaos for the solutions of (4.3) could mean that such a solutions could be considered as unstable with respect to a small perturbation at the meanings of the boundary conditions.

Also we should note that since the fluid is incompressible for the development above, there is a strong link between boundary conditions and the solution inside. Due to this link, at least for the small values of time-parameter t , the space part of a solution (3.4) or (4.3) should strongly depend on the boundary conditions.

5. Conclusion.

In fluid mechanics, a lot of authors have been executing their researches to obtain the analytical solutions of Navier-Stokes equations [10], even for 3D case of *compressible* gas flow [11]. But there is an essential deficiency of non-stationary solutions indeed.

In our presentation, we explore the case of non-stationary *helical* flow (where vorticity is proportional to the flow velocity) of the Navier-Stokes equations for incompressible fluids at *any* given initial conditions for velocity fields (*it means an open choice for the space part of a solution*).

Such a non-stationary *helical* flow is proved to be decreasing exponentially in regard to the time-parameter (3.4), the extent of time-dependent exponential component is given by the coefficient of kinematic viscosity, multiplied by the square of the coefficient of proportionality between the vorticity and velocity field.

As we know, ABC-ansatz [8-9] was published as a solution of the steady problem. In their work, they never realized that its extension is possible also to the non-stationary problem. It was extended for the first time in [12] to the non-stationary problem as a time-kinematic viscosity decaying solution; also we should mention the comprehensive article [7] in regard to the non-stationary *helical* flows with the special kind of the space part for the velocity fields as well as the appropriate pressure gradient field.

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