Analysis of Histogram Based Shot Segmentation Techniques for Video Summarization

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Abstract
Content based video indexing and retrieval has its foundations in the analyses of the prime video temporal structures. Thus, technologies for video segmentation have become important for the development of such digital video systems. Dividing a video sequence into shots is the first step towards VCA and content-based video browsing and retrieval. This paper presents analysis of histogram based techniques on the compressed video features. Graphical User Interface is also designed in MATLAB to demonstrate the performance using the common performance parameters like, precision, recall and F1.

Keywords: Histogram Difference, Weighted Difference, Histogram Intersection, $\chi^2$ Histogram Matching, Block Based Histogram Comparison.

1 Introduction
There are many approaches for shot boundary detection like pixel based methods, block based methods, feature based methods, histogram based methods etc [1][2][3][4][5][6][7][8][9][10][11][12]. Histogram is a graphical representation of the tonal distribution in digital image or frame. It plots the number of pixel for each tonal value. By viewing at the histogram for a specific frame viewer can judge the entire tonal distribution. We can generate histogram for entire frame or we can divide the frame into number of sections and then generate the histogram for each section. For gray scale image or frame, the histogram represents the plot of number of occurrence of gray levels in the frame against the gray level values. The histogram provides a convenient summary of the intensities in a frame. The histogram provides more insight about image contrast and brightness.

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2 Histogram Matching Methods [13][14][15][16][17][18]

Histogram difference, weighted difference, histogram intersection, $\chi^2$ Matching and Block Based Comparison are discussed in this section.

2.1 Histogram Difference

This method based on gray-level histograms. Images are compared by computing a distance between their histograms, as shown in the following equation:[19]. Detection if

$$\sum_{v=0}^{v} = |H(I_t, v) - H(I_{t-1}, v)| > T$$

(1)

Where $T$ is Threshold fixed by user and $I_t$ and $I_{t-1}$ is the frames at time interval $t$ and $t-1$. As clearly shown in equation 1 if the difference value is greater than threshold ($T$), then only detection can be possible.

A similar method using only 64 bins for color histograms (2 bits for each color component of the RGB space). Using the notation $H_{64}(I_t, v)$, the detection is defined by [20], Detection if

$$\sum_{v=0}^{63} = |H_{64}(I_t, v) - H_{64}(I_{t-1}, v)| > T$$

(2)

Similarly for the RGB and HSV compute three histogram differences, considering separately the three color components of the RGB space. The highest value is compared to a threshold for shot change detection.

2.2 Weighted Difference

In color images, some color components may have a bigger influence than others. So it is possible to detect shot changes by weighting the histograms of each color component depending on their importance [21]. Detection if

$$\sum_{k=1}^{3} \sum_{v=0}^{v} = \frac{L(I_t, C_k)}{L_{Mean}(I_t)} |H(I_t, C_k, v) - H(I_{t-1}, C_k, v)| > T$$

(3)

Where, $L(I_t, C_k)$ and $L_{Mean}(I_t)$ are respectively the luminance for the $K^{th}$ color component of the frame $I_t$ and the average luminance of the frame $I_t$ considering all the color components.

Zhao et al use weight values for weighted histogram difference calculation. First calculate original histogram difference and after use min-max optimization for select best weight which is used in weighted histogram difference. The shot detection process is given by following equation which uses 12 operations per histogram bin [22].
\[
\sum_{k=1}^{3} \sum_{v=0}^{v} W(k, v) |H(I_t, C_k, v) - H(I_{t-1}, C_k, v)| > T
\]

(4)

Where, \( W(k, v) \) denote best weigh value.

### 2.3 Histogram Intersection

Similarity between two images can also be evaluated by histogram intersection. Histogram intersection is computed using different operators, for example a min function. Similarity ratio belonging to interval \([0, 1]\) is then compared to a given threshold. This comparison allows the detection of shot changes [13]. Detection if

\[
1 - \frac{1}{XY} \sum_{v=0}^{v} \min (|H(I_t, C_k, v), H(I_{t-1}, C_k, v)|) > T
\]

(5)

Where, \( XY \) represents the number of pixels of frames processed.

Additional method for histogram intersection based shot detection is given by following equation [13]. Detection if

\[
1 - \frac{1}{XY} \sum_{v=0}^{v} \min (|H(I_t, C_k, v), H(I_{t-1}, C_k, v)|) > T
\]

(6)

### 2.4 \( \chi^2 \) Histogram Matching

This is most efficient histogram based comparison method than the above discussed. Nagasaka et al have proposed a 64 bin histogram comparison based on \( \chi^2 \) test. This comparison is then defined by[20]: Detection if

\[
\sum_{v=0}^{63} \left( \frac{H_{64}(I_t, v) - H_{64}(I_{t-1}, v))^2}{H_{64}(I_t, v)} \right) > T
\]

(7)

With the assumption, \( H_{64}(I_t, v) \neq 0 \).

If this assumption does not hold, we use the following equation instead[20]: Detection if

\[
\sum_{v=0}^{63} \left( \frac{H_{64}(I_t, v) - H_{64}(I_{t-1}, v))^2}{H_{64}(I_{t-1}, v)} \right) > T
\]

(8)

With the assumptions \( H_{64}(I_{t-1}, v) \neq 0 \) and \( H_{64}(I_t, v) = 0 \). This method is considered as more efficient than simple histogram comparison-based methods.
2.5 Block Based Histogram Comparison

Block sampling is used to increase the quality of shot boundary detection and decrease the calculation time. Block based method has advantages like relative insensitivity to noise and object motion. Color histograms computed on blocks of image noted \( H(I_t, b, C_k, v) \) which gives shot boundary detection given by Swanberg et al.[23]

\[
\left( \sum_{k=1}^{3} \sum_{b=1}^{3} \sum_{v=0}^{v \leq 3} \left( \frac{H(I_t, b, C_k, v) - H(I_{t-1}, b, C_k, v)}{H(I_t, b, C_k, v) + H(I_{t-1}, b, C_k, v)} \right)^2 \right) > T
\]  

3 Performance Parameter Matrix \([24][25][26][27][28][29][30]\)

i Correct (C): Number of shot changes that are correctly detected by algorithm.

ii Missed (M): Number of shot changes that actually present in video but algorithm fails to detect.

iii False-Positive (FP): Number of shot changes that are detected by algorithm but actually not present in video. Once we get the values of correct, missed, and FP, now we can derive performance parameter like Recall(R), Precision(P) and F1 measure from them. Definitions and equations of these parameters are as follow. Here, TH stands for Threshold Value; TF stands for Total number of Frames and D stands for Shot change detection.

iv Recall (R): It is defined as percentage of actual (desire) shot changes that are detected correctly by algorithm.

\[
Recall = \frac{Correct}{Correct + Missed}
\]  

v Precision (P): It is defined as percentage of total detected shot change by algorithm that is correct.

\[
Precision = \frac{Correct}{Correct + FP}
\]  

vi F1 measure: It is defined as a measure that combines precision and recall; it is the harmonic mean of precision and recall.

\[
F1 = \frac{2 \times R \times P}{R + P}
\]

4 Simulation Results

Section presents simulation results for methods discussed in section 2 using MATLAB for three different types of video namely Animation video, NEWS video and Sport video using following procedure:

- Determine shot changes present in a video, by manually checking the frames of video using MATLAB programme to convert video into bunch of images.
• Apply different methods/algorithm to a video. Table 1 depicts the list of files developed for the methods.

• Comparing manual results with the algorithm result to obtain values of parameters like correct, missed, and False Positive (FP).

• Study effect of Variation of threshold values for each method on each video

• Use the values of parameter R, P, and F1 for comparative analysis.

• Tabulate the results (Tables 2, 3, 4, 5, 6, 7 are generated using MATLAB for the methods or algorithms).

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Table 4: $\chi^2$ Histogram Matching Method

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5 Graphical User Interface

**Design Steps:**
The three principal elements required to create a MATLAB Graphical User Interface as follows. Using these elements, the Screen shot of GUI created is shown in figure 1 for selection of technique.

1. **Components:** The types of components include graphical controls (pushbuttons, edit boxes, lists, sliders, etc.), static elements (frames and text strings), menus, and axes. Graphical controls and static elements are created by the function uicontrol, and menus are created by
the functions uimenu and uicontextmenu. Axes, which are used to display graphical data, are created by the function axes.

2. **Figures:** The components of a GUI must be arranged within a figure, which is a window on the computer screen. However, empty figures can be created with the function figure and can be used to hold any combination of components.

3. **Callbacks:** Finally, there must be some way to perform an action if a user clicks a mouse on a button or types information on a keyboard. A mouse click or a key press is an event, and
the MATLAB program must respond to each event if the program is to perform its function. The code executed in response to an event is known as a callback.

![Figure 1: Front Panel of GUI](image)

### 6 Conclusion

F1 value near to 1 for a particular method at some particular threshold that means it is efficient method for that particular case. If lower threshold value is selected FP will increase and as we take
higher threshold value missed shot will increase. Hence select the threshold value in such a way that F1 goes near to 1. It is seen that a particular method cannot work efficiently for all type of video and at all time. Different methods behave differently for different types of videos. Depending upon type of video content and how shot is taken, whether having more similarity or not, different method behaves differently at different threshold level. Each method has optimum threshold value in the range where it works efficiently. at certain threshold value. This can be verified form the table of simulation results. Every method has certain range of threshold over which it has F1=1, means optimum result.

If we take certain range of threshold, then there are two points at which results start getting worst. This two points are the boundary of the threshold range over which F1=1. By observing every methods at this points where results start getting worst, we can decide which method is better. More specifically, $\chi^2$ (chi-square) histogram based method gives most efficient results for almost all types of video. In sport videos there are more similarity between frames due to limited content (i.e. ground and player), so normal histogram of frames are similar hence, Histogram Intersection method is better than $\chi^2$ (chi-square) method.

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References


