

# The complete classification of self-similar solutions of the Navier-Stokes equations for incompressible flow

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A new classification of self-similar solutions of the Navier-Stokes system of equations is presented here. We consider equations of motion for incompressible flow (of Newtonian fluids) in the curl rotating co-ordinate system. Then the equation of momentum should be split into the sub-system of 2 equations: an irrotational (*curl-free*) one, and a solenoidal (*divergence-free*) one.

The irrotational (*curl-free*) equation used for obtaining of the components of pressure gradient  $\nabla p$ . As a term of such an equation, we used the irrotational (*curl-free*) *vector field of flow velocity*, which is given by the proper potential (*besides, the continuity equation determines such a potential as a harmonic function*).

As for solenoidal (*divergence-free*) equation, transition from Cartesian to the the curl rotating co-ordinate system transforms equation of motion to the *Helmholtz* vector differential equation for time-dependent self-similar solutions. The *Helmholtz* differential equation can be solved by separation of variables in only 11 coordinate systems, so it forms a complete set of all possible cases of self-similar solutions for Navier-Stokes system of equations.

**Keywords:** Navier-Stokes equations, self-similar solutions, incompressible flow.

## 1. Introduction, the Navier-Stokes system of equations.

In accordance with [1-2], the Navier-Stokes system of equations for incompressible flow of Newtonian fluids should be presented in the Cartesian coordinates as below:

$$\nabla \cdot \vec{u} = 0, \quad (1.1)$$

$$\frac{\partial \vec{u}}{\partial t} + (\vec{u} \cdot \nabla) \vec{u} = -\frac{\nabla p}{\rho} + \nu \cdot \nabla^2 \vec{u} + \vec{F}, \quad (1.2)$$

- where  $\mathbf{u}$  is the flow velocity, a vector field;  $\rho$  is the fluid density,  $p$  is the pressure,  $\nu$  is the kinematic viscosity, and  $\mathbf{F}$  represents body forces (*per unit of mass in a volume*) acting on the fluid and  $\nabla$  is the del (nabla) operator. Let us also choose the Oz axis coincides to the main direction of flow propagation.

The system of Navier-Stokes equations is known to be the system of the mixed parabolic and hyperbolic type [3].

## 2. The curl rotating co-ordinate system.

Using the identity  $(\mathbf{u} \cdot \nabla) \mathbf{u} = (1/2) \nabla(u^2) - \mathbf{u} \times (\nabla \times \mathbf{u})$ , and then using the curl of the curl identity  $\nabla \times (\nabla \times \mathbf{u}) = \nabla(\nabla \cdot \mathbf{u}) - \nabla^2 \mathbf{u}$ , we could present the equation (1.2) in the case of incompressible flow of Newtonian fluids as below:

$$\frac{\partial \vec{u}}{\partial t} = \vec{u} \times \vec{w} + \nu \cdot \nabla^2 \vec{u} - \left( \frac{1}{2} \nabla(u^2) + \frac{\nabla p}{\rho} - \vec{F} \right) \quad (2.1)$$

- here we denote *the curl field*  $\mathbf{w}$ , a pseudovector field (*time-dependent*).

Let us consider equation (2.1) in the *curl* rotating co-ordinate system by adding of the proper *Coriolis force* to the equation of motion (2.1) as below

$$\frac{\partial \vec{u}}{\partial t} - 2\vec{\Omega} \times \vec{u} = \vec{u} \times \vec{w} + \nu \cdot \nabla^2 \vec{u} - \left( \frac{1}{2} \nabla(u^2) + \frac{\nabla P}{\rho} - \vec{F} \right) \quad (2.2)$$

- where  $\vec{\Omega}$  - is the angular velocity of curl rotation, for which the equality below is valid in the case of Newtonian fluids [2]:

$$\vec{\Omega} = (\nabla \times \mathbf{u})/2$$

So, from the equation (2.2) we obtain

$$\frac{\partial \vec{u}}{\partial t} = \nu \cdot \nabla^2 \vec{u} - \left( \frac{1}{2} \nabla(u^2) + \frac{\nabla P}{\rho} - \vec{F} \right) \quad (2.3)$$

Let us denote as below (*according to the Helmholtz fundamental theorem of vector calculus*):

$$\nabla \times \vec{u} \equiv \vec{w}, \quad \vec{u} \equiv \vec{u}_p + \vec{u}_w,$$

$$\nabla \cdot \vec{u}_w \equiv 0, \quad \nabla \times (\vec{u}_p) \equiv 0,$$

- where  $\mathbf{u}_p$  is an *irrotational (curl-free)* field of flow velocity, and  $\mathbf{u}_w$  - is a *solenoidal (divergence-free)* field of flow velocity which generates a curl field  $\mathbf{w}$ :

$$\vec{u}_p \equiv \nabla \varphi, \quad \vec{u}_w \equiv \nabla \times \vec{A},$$

- here  $\varphi$  - is the proper scalar potential,  $\vec{A}$  - is the appropriate vector potential.

Thus, we could obtain from the equation (1.1) the equality below

$$\nabla \cdot (\nabla \varphi + \nabla \times \vec{A}) = 0, \Rightarrow \Delta \varphi = 0, \quad (2.4)$$

- it means that  $\varphi$  - is the proper *harmonic function* [3].

Thus, equation (2.3) could be presented as the system of equations below:

$$\left\{ \begin{array}{l} \frac{\partial (\nabla \varphi)}{\partial t} = \vec{F} - \frac{1}{2} \nabla \{(\nabla \varphi + \vec{u}_w)^2\} - \frac{\nabla p}{\rho}, \\ \frac{\partial \vec{u}_w}{\partial t} = \nu \cdot \nabla^2 \vec{u}_w, \end{array} \right. \quad (2.5)$$

- so, if we solve the second equation of (2.5) for the components of vector  $\vec{u}_w$ , we could substitute it into the 1-st equation of (2.5) for obtaining of a proper expression for vector function  $\nabla p$ :

$$\frac{\nabla p}{\rho} = \vec{F} - \frac{\partial (\nabla \varphi)}{\partial t} - \frac{1}{2} \nabla \{(\nabla \varphi + \vec{u}_w)^2\}, \quad (2.6)$$

- where  $\varphi$  - is the proper *harmonic function*, see Eq. (2.4).

The system of equations (1.1)-(2.5) is equivalent to the Navier-Stokes system of equations for incompressible Newtonian fluids (1.1)-(1.2) in the sense of existence and smoothness of a general solution.

The inverse transformation of exact solutions from the curl rotating system to the Cartesian coordinate system is possible only in case  $\Omega = \text{const}$ .

### 3. Classification of exact solutions for Navier-Stokes Eq.

For non-stationary solutions  $\partial \partial t \neq 0$ , the 2-nd of Eq. (2.5) could be solved analytically only in the cases below:

- 1)  $\partial \partial t \sim \partial \partial z$  - it means that the Oz axis represents a preferential direction similar to the time arrow in mechanical processes [4];
- 2) Time-dependent self-similar case,  $\mathbf{u}_w = \exp(-\omega t) \cdot \mathbf{u}_w(x, y, z)$ ,  $\omega = \text{const} > 0$  (*frequency-parameter*).

For the time-dependent self-similar case, 2-nd of Eq. (2.5) should be presented as

$$\nabla^2 \vec{u}_w + \left( \frac{\omega}{\nu} \right) \vec{u}_w = 0, \quad (3.1)$$

- which is the proper *Helmholtz* differential equation for vector fields  $\mathbf{u}_w$  [2].

The *Helmholtz* differential equation can be solved by separation of variables in only 11 coordinate systems, 10 of which (*with the exception of confocal paraboloidal coordinates*) are particular cases of the confocal ellipsoidal system: Cartesian, confocal ellipsoidal, confocal paraboloidal, conical, cylindrical, elliptic cylindrical, oblate

spheroidal, paraboloidal, parabolic cylindrical, prolate spheroidal, and spherical coordinates [5-6].

Thus, above 11 classes form a complete set of all possible cases of self-similar solutions for Navier-Stokes system of equations.

#### 4. Conclusion.

A new classification of self-similar solutions of the Navier-Stokes system of equations is presented here. We consider equations of motion for incompressible flow (of Newtonian fluids) in the curl rotating co-ordinate system. Then the equation of momentum should be split into the sub-system of 2 equations: an irrotational (*curl-free*) one, and a solenoidal (*divergence-free*) one.

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