Lagrangian Analysis of a Class of Quadratic Liénard-Type Oscillator Equations with Exponential-Type Restoring Force function

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Abstract

This research work proposes a Lagrangian and Hamiltonian analysis for the unique class of position-dependent mass oscillator characterized by a harmonic periodic solution and parabolic potential energy and its inverted version admitting a position-dependent mass dynamics.

1. Analysis of the class of quadratic Liénard-type harmonic nonlinear oscillator equations

This section is devoted to the analysis of a class of quadratic Liénard-type nonlinear dissipative oscillator equations that admits exact analytical harmonic periodic solutions. Consider the equation [1, 2]

$$\ddot{x} - \gamma \varphi'(x) \dot{x}^2 + \omega^2 x e^{2\gamma \varphi(x)} = 0 \tag{1}$$

that represents the class of equations under analysis. γ and ω are arbitrary parameters, and $\varphi(x)$ is an arbitrary function of x. The dot over a symbol means differentiation with respect to time, and prime holds for differentiation with respect to x. By restriction of $\varphi(x) = \ln f(x)$

and
$$\gamma = -\frac{1}{2}$$
, the equation (1), yields

$$\ddot{x} + \frac{1}{2} \frac{f'(x)}{f(x)} \dot{x}^2 + \frac{\omega^2 x}{f(x)} = 0$$
⁽²⁾

where $f(x) \neq 0$, is an arbitrary function of x. The equation (1) is of the general form

$$\ddot{x} + F(x)\dot{x}^2 + G(x) = 0 \tag{3}$$

for which the Lagrangian is given by [3,4]

$$L(\dot{x}, x) = \frac{1}{2} \dot{x}^2 M(x) - V(x)$$
(4)

where

$$M(x) = e^{2\int F(x)dx}$$
⁽⁵⁾

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$$V(x) = \int M(x)G(x)dx \tag{6}$$

designate the position dependent mass and the potential function respectively.

The Lagrangian of the equation (1) becomes

$$L(\dot{x}, x) = \frac{1}{2} \dot{x}^2 e^{-2\gamma\varphi(x)} - \frac{1}{2} \omega^2 x^2$$
(7)

Applying the Euler-Lagrange equation formula in [4]

$$\ddot{x} + \frac{1}{2} \frac{M'(x)}{M(x)} \dot{x}^2 + \frac{1}{M(x)} \frac{\partial V(x)}{\partial x} = 0$$
(8)

to the equation (7), gives the equation (1). By restricting V(x) to the harmonic potential, that is $V(x) = \frac{1}{2}m_0 \omega^2 x^2$, with unit mass, $m_0 = 1$, the equation (8) becomes identical to the equation (2), with the position-dependent mass function M(x) = f(x). In this regard, the equation (1) represents the unique class of position-dependent mass oscillators exhibiting not only exact harmonic periodic solution but also a harmonic potential function.

Now, using [3]

$$H(p,x) = \frac{p^2}{2M(x)} + V(x)$$
(9)

one may deduce from (5) and (6) the Hamiltonian

$$H(p,x) = \frac{p^2}{2}e^{2\gamma\phi(x)} + \frac{1}{2}\omega^2 x^2$$
(10)

Let us now consider, as illustration, some specific examples of (1). Let $\varphi(x) = x$. Then (1) becomes

$$\ddot{x} - \gamma \dot{x}^2 + \omega^2 x e^{2\gamma x} = 0 \tag{11}$$

The equation (10) admits the position dependent mass and the potential

$$M(x) = e^{-2\gamma x}$$
, and $V(x) = \frac{1}{2}\omega^2 x^2$ (12)

respectively, which provides the Lagrangian function

$$L(\dot{x}, x) = \frac{1}{2} \dot{x}^2 e^{-2\gamma x} - \frac{1}{2} \omega^2 x^2$$
(13)

The application of the Euler-Lagrange equation (8) to (13) gives, as expected, (11). In this regard the Hamiltonian associated to (11) takes the form

$$H(p,x) = \frac{p^2}{2}e^{2\gamma x} + \frac{1}{2}\omega^2 x^2$$
(14)

So, the Hamilton equations

$$\begin{cases} \dot{x} = \frac{\partial H}{\partial p} \\ \dot{p} = -\frac{\partial H}{\partial x} \end{cases}$$
(15)

yield for (14)

$$\begin{cases} \dot{x} = p e^{2\gamma x} \\ \dot{p} = -\gamma p^2 e^{2\gamma x} - \omega^2 x \end{cases}$$
(16)

The explicit expression for the conjugate momentum p, as a function of x and \dot{x} takes then the form

$$\dot{p} = -e^{-2\gamma x} \left(\gamma \dot{x}^2 + \omega^2 x e^{2\gamma x} \right) \tag{17}$$

Putting now $\varphi(x) = \frac{1}{2}x^2$, into (1), one may obtain as equation

$$\ddot{x} - \gamma x \dot{x}^2 + \omega^2 x e^{\gamma x^2} = 0 \tag{18}$$

The position dependent mass and the potential of (18) take then the form

$$M(x) = e^{-\gamma x^2}$$
 and $V(x) = \frac{1}{2}\omega^2 x^2$ (19)

respectively.

The associated Lagrangian becomes

$$L(\dot{x}, x) = \frac{1}{2} \dot{x}^2 e^{-\gamma x^2} - \frac{1}{2} \omega^2 x^2$$
(20)

The application of the Euler-Lagrange equation (8) to (20) gives with satisfaction (18). So, the associated Hamiltonian may be written as

$$H(p,x) = \frac{p^2}{2}e^{\gamma x^2} + \frac{1}{2}\omega^2 x^2$$
(21)

such that the Hamilton equations take the form

$$\begin{cases} \dot{x} = p e^{\gamma x^2} \\ \dot{p} = -\gamma p^2 x e^{\gamma x^2} - \omega^2 x \end{cases}$$
(22)

The relation between \dot{x} and \dot{p} reads in this perspective

$$\dot{p} = -xe^{-\gamma x^2} (\gamma \dot{x}^2 + \omega^2 e^{\gamma x^2})$$
(23)

2. Analysis of inverted versions

Consider now the inverted version of (1)

$$\ddot{x} + \gamma \varphi'(x) \dot{x}^2 + \omega^2 x e^{2\gamma \varphi(x)} = 0$$
(24)

which gives for $\varphi(x) = x$, the following equation

$$\ddot{x} + \gamma \dot{x}^2 + \omega^2 x e^{2\gamma x} = 0 \tag{25}$$

The position dependent mass and potential function of (25) may be then deduced from (4) as

$$M(x) = e^{2\gamma x}$$
 and $V(x) = \frac{\omega^2}{4\gamma} x e^{4\gamma x} - \frac{\omega^2}{16\gamma^2} e^{4\gamma x}$ (26)

respectively.

Therefore, the Lagrangian for (25) may be written in the form

$$L(\dot{x},x) = \frac{1}{2}\dot{x}^2 e^{2\gamma x} + \frac{\omega^2}{16\gamma^2} e^{4\gamma x} - \frac{\omega^2}{4\gamma} x e^{4\gamma x}$$
(27)

In this perspective, it may be verified that the application of the Euler-Lagrange equation (8) to (27) yields, as expected, (25). The Hamiltonian for (25) may also be computed as

$$H(p,x) = \frac{p^2}{2}e^{-2\gamma x} + \frac{\omega^2}{4\gamma}xe^{4\gamma x} - \frac{\omega^2}{16\gamma^2}e^{4\gamma x}$$
(28)

which gives the Hamiltonian equations

$$\begin{cases} \dot{x} = p e^{-2\gamma x} \\ \dot{p} = \gamma p^2 e^{-2\gamma x} - \omega^2 x e^{4\gamma x} \end{cases}$$
(29)

from which the conjugate momentum becomes

$$\dot{p} = e^{2\gamma x} \left(\gamma \dot{x}^2 - \omega^2 x e^{2\gamma x} \right) \tag{30}$$

By analysis, other forms of equations are also suggested by the previous studied equations. So, the following equations may also be considered in the perspective of this study, that is

$$\ddot{x} + \gamma x \dot{x}^2 + \omega^2 x e^{\gamma x^2} = 0$$
(31)

or in general

$$\ddot{x} + \gamma \varphi'(x) \dot{x}^2 + \omega^2 x e^{\gamma \varphi(x)} = 0 \tag{32}$$

$$\ddot{x} - \gamma \varphi'(x) \dot{x}^2 + \omega^2 x e^{\gamma \varphi(x)} = 0 \tag{33}$$

Finally one may consider the following more generalizations

$$\ddot{x} + \gamma \varphi'(x) \dot{x}^2 + \omega^2 h(x) e^{\gamma \varphi(x)} = 0 \tag{34}$$

$$\ddot{x} - \gamma \varphi'(x)\dot{x}^2 + \omega^2 h(x)e^{\gamma \varphi(x)} = 0$$
(35)

$$\ddot{x} + \gamma \varphi'(x) \dot{x}^2 + \omega^2 h(x) e^{2\gamma \varphi(x)} = 0$$
(36)

$$\ddot{x} - \gamma \varphi'(x) \dot{x}^2 + \omega^2 h(x) e^{2\gamma \varphi(x)} = 0$$
(37)

$$\ddot{x} + \gamma \varphi'(x) \dot{x}^2 + \omega^2 h(x) e^{-\gamma \varphi(x)} = 0$$
(38)

$$\ddot{x} + \gamma \varphi'(x) \dot{x}^2 + \omega^2 h(x) e^{-\gamma \varphi(x)} = 0$$
(39)

$$\ddot{x} + \gamma \varphi'(x) \dot{x}^2 + \omega^2 h(x) e^{-2\gamma \varphi(x)} = 0$$
(40)

These equations will be investigated in a subsequent work.

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