# A class of integrable mixed Liénard-type differential equations 

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#### Abstract

This letter is devoted to show the existence of a general class of integrable mixed Liénard-type equations that includes some physically important nonlinear differential equations like the generalized modified Emden-type equation (MEE) through the first integral under differentiation approach.


## 1. Theory

Let us consider that the first integral of the desired generalized nonlinear differential equation of interest may be written in the form

$$
\begin{equation*}
a(x, \dot{x})=g(x) \dot{x}+x f(x) \tag{1}
\end{equation*}
$$

where $g(x) \neq 0$, and $f(x)$ are arbitrary functions of $x$, and the dot over a symbol means differentiation with respect to time. Suppose, now, that the function $a(x, \dot{x})$ satisfies

$$
\begin{equation*}
\frac{d a(x, \dot{x})}{d t}=0 \tag{2}
\end{equation*}
$$

Substitution of the equation (1) into (2), after a few mathematical rearrangements, yields immediately the desired class of solvable mixed Liénard-type differential equations

$$
\begin{equation*}
\ddot{x}+\frac{g^{\prime}(x)}{g(x)} \dot{x}^{2}+\frac{f^{\prime}(x)}{g(x)} x \dot{x}+a \frac{f(x)}{g(x)^{2}}-\frac{f(x)^{2}}{g(x)^{2}} x=0 \tag{3}
\end{equation*}
$$

where prime designates differentiation with respect to $x$.

## 2. Application

Let $g(x)=a_{1} x^{m}$, and $f(x)=a_{1}^{2} x^{2 m+1}$, where the exponent $m$ is a real number. So, the equation (3) reduces to

$$
\begin{equation*}
\ddot{x}+m \frac{\dot{x}^{2}}{x}+(2 m+1) a_{1} x^{m+1} \dot{x}+a x-a_{1}^{2} x^{2 m+3}=0 \tag{4}
\end{equation*}
$$

The equation (4) consists of a generalized mixed Liénard-type equation [1].
Now, substitution of $m=0$, into the equation (4), leads immediately to the generalized modified Emden type equation [1]

[^0]\[

$$
\begin{equation*}
\ddot{x}+a_{1} x \dot{x}+a x-a_{1}^{2} x^{3}=0 \tag{5}
\end{equation*}
$$

\]

Also, $m=-\frac{1}{2}$, gives, taking into account the equation (4)

$$
\begin{equation*}
\ddot{x}-\frac{1}{2} \frac{\dot{x}^{2}}{x}+a x-a_{1}^{2} x^{2}=0 \tag{6}
\end{equation*}
$$

The equation (6) is known as a quadratic Liénard-type differential equation [2,3]. It is interesting to note that a more generalization of equation (1) may be written in the form

$$
\begin{equation*}
a(x, \dot{x})=g(x) \dot{x}+x^{l} f(x) \tag{7}
\end{equation*}
$$

where the exponent $l$ is a real number.

## References

[1] M. Lakshmanan, V. K. Chandrasekar, Generating finite dimensional integrable nonlinear dynamical systems, arXiv:1307.0273v1.(2013).
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